



INTRODUCTION

TPU S430 is a multifunction protection and control relay that provides a cost-effective solution for a wide range of applications.

It can be used as a secure solution for line/feeder protection as well as backup or auxiliary protection of transformers or other equipment in all voltage levels. Furthermore, TPU S430 features, in option, supervision and control of capacitor banks as well as voltage regulation and tap changer control suitable for managing two- or three-winding transformers operating independently of each other or in parallel.

TPU S430 offers additional measurement and recording functions for easy and reliable power system management.

TPU S430 further combines enhanced user programmability to deliver all the required functions for power system protection and control in a single unit.

Based on the 430 IED platform, TPU S430 provides flexible I/O options and has been designed with IEC 61850 and other open standards in mind, being future-proof and integration friendly.

As part of the Efacec CLP 500 family, TPU S430 provides object-oriented engineering, system tools and full IEC 61850 open design that allows users to straightforwardly apply the product in different system architectures.

PROTECTION

- Restricted Earth-Fault
- (Directional) Phase Overcurrent
- (Directional) Earth-Fault Overcurrent
- (Directional) Negative Sequence Overcurrent
- Cold Load Pickup
- Thermal Overload
- Switch-Onto-Fault
- Broken Conductor Check
- Undercurrent
- Directional Earth-Fault Overcurrent for Non-Earthed Systems
- Directional Power
- Phase Undervoltage
- Phase Overvoltage
- Residual Overvoltage
- Negative Sequence Overvoltage
- Underfrequency / Overfrequency
- Frequency Rate-of-Change

CONTROL / SUPERVISION

- Three-Phase Trip Logic
- Trip Circuit Supervision
- Circuit Breaker Failure
- Automatic Reclosing
- Synchronism and Voltage Check
- Lockout
- VT / CT Supervision
- Circuit Breaker Control / Supervision
- Circuit Switch Control / Supervision
- Automatic Voltage Control
- Tap Changer Control / Supervision
- Transformer Protection Supervision
- Distributed Automation
- Programmable Automation (IEC 61131-3 based)

IEC 61131-3
ladder programming

MONITORING / RECORDING

- Three-Phase Measurements
- Single-Phase Measurements
- Metering
- Fault Locator
- Disturbance Recorder
- Event Recorder / SOE
- Fault Report
- Self-tests and Watchdog

COMMUNICATION

- IEC 61850 Server / GOOSE
- IEC 60870-5-101/103/104
- DNP 3.0 (TCP/IP or Serial)
- Modbus (TCP/IP or Serial)
- Other serial and IP protocols available

IEC 61850
open design

TIME SYNCHRONIZATION

- IRIG-B Input
- SNTP Client

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AUTOMATION STUDIO-READY

- Integrated configuration and programming
- Simplified engineering and handling

OVERVIEW

TPU S430 is a multifunction protection and control relay prepared for applications in all voltage levels that draws on the experience obtained with previous field-proven product families and, as such, provides significantly enhanced protection and control algorithms, with new and additional features included allowing for a wide range of protection, control and automation functions. A careful design of protection functions and device architecture provides an adequate balance between speed, sensitivity and accuracy.

TPU S430 provides protection of power system aerial lines or underground cables, in high or medium voltage networks, with grounded, low-impedance, isolated or compensated neutral. TPU S430 additionally allows for supervision and control of capacitor banks connected to any voltage level.

It also fits transformer applications, as backup protection for main transformer differential protection which include restricted earth-fault function to improve sensitivity to high impedance faults in the transformer, as well as other applications such as motor and generator backup protection. Several other current, voltage and frequency protection functions are also available allowing for the TPU S430 to be used as backup to other protection relays in more complex applications.

TPU S430 also features, in option, voltage regulation and tap changer control suitable for managing two- or three-winding transformers operating independently of each other or in parallel. While operating in parallel, TPU S430 can control a transformer with up to eight other transformers in parallel by exchanging, for instance, through GOOSE publish/subscribe messaging the necessary information with the TPU S430 responsible for each one of the remaining transformers.

Several control and supervision functions extend the application of the relay, with option for additional user-defined automation functions and logic (for example, interlocking logic or load transfer and restoration schemes). Accurate measured and metered values and a wide range of records and other stored information add value to the base application.

High configurability via flexible binary and analogue I/O configurations, advanced user-programmable functions and a comprehensive library of selectable built-in firmware functions allows the user to adapt the device to different substation topologies as well as protection and control schemes. Integration in a state of the art engineering toolset allows straightforward engineering throughout the system life-cycle without compromising user requirements.

A graphic display is integrated in the local TPU S430 interface where menus, tables and user-defined mimics can be displayed to represent any available data on the unit. On the front panel several functional keys and alarms are provided for straightforward bay status inspection and local control.

The device provides self-supervision of all hardware components and software modules. Diagnostic information can be accessed through the engineering toolset or communication interfaces.

Designed with IEC 61850 and other open standards in mind the TPU S430 is flexible, future-proof and can be seamlessly integrated in multivendor distributed protection, automation and control systems.

FEATURE SUMMARY

TPU S430	
Size	
1/2 x 19" rack / height 6U	●
A.C. Analogue Inputs	
Maximum Number of Inputs	12
Maximum Number of Current Inputs	6
Maximum Number of Voltage Inputs	6
D.C. Analogue Inputs	
Maximum Number of Inputs	8
Binary Inputs / Outputs	
Maximum Number of Inputs	104
Maximum Number of Outputs	56
Base I/O	
8 Binary Inputs + 8 Binary Outputs + Watchdog Output	●
Availability	
Hardware Watchdog and Auto-reset	●
Software Failure Detection and Recovery	●
User Interface	
640 x 480 Graphic Colour LCD	●
Programmable Alarms / Indication LEDs	16
Function Keys	9
Relay Status LEDs	3
Integrated Webservice	●
Time Synchronization	
IRIG-B Input	●
SNTP Client	●
By Communication Protocol	●
Communication Interfaces (Rear Panel)	
1 RS-232 / RS-485	●
1 RS-232 / RS-485 / Glass / Plastic Fibre	○
1 Single / Dual Ethernet 10/100BASE-TX or 100BASE-FX Interface	○
RSTP-enabled Interface	○
PRP/HSR-enabled Interface **	○
IEC 61850 Communications	
IEC 61850-8-1 Server and GOOSE	○
Communication Protocols	
Maximum Number of Simultaneous Protocols	3
Protocol Up / Slave	
IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial)	○
IEC 60870-5-103 (Serial)	○
DNP 3.0 (TCP/IP or Serial)	○
Modbus (TCP/IP or Serial)	○
Others available	(please contact)
Configuration, Operational Support & Programming	
Automation Studio (Automation Studio license not included)	●
Industry-specific function libraries	(please contact)

● - Base feature

○ - Optional feature

** - Currently under development

			Without Capacitor Bank P&C (option C1)	With Capacitor Bank P&C (option C2)	
General					
Three-Phase Tripping			●	●	
Single Breaker Arrangements			●	●	
Protection Functions					
	ANSI	IEC 61850			
Restricted Earth Fault	87N	PDIF	○(1)	○(1)	(a)
(Directional) Phase Overcurrent	50/51/67	PTOC, RDIR	●(2)	●(2)	
(Directional) Earth-Fault Overcurrent	50N/51N/67N 50G/51G/67G	PTOC, RDIR	●(3)	●(3)	
(Directional) Negative Sequence Overcurrent	46/67	PTOC, RDIR	●(1)	●(1)	
Editable Time-Current Curves			●	●	
Inrush Restraint	68	PHAR	●	●	
Cold Load Pickup		RCLP	●(1)	●(1)	
Thermal Overload	49	PTTR	●(1)	●(1)	
Switch-Onto-Fault	50HS	RSOF, PIOC	●(1)	●(1)	
Current Unbalance for Capacitor Banks **	60C	PTOC	●(3)	●(3)	
Broken Conductor Check / Phase Unbalance	46BC	RBCD	●(1)	●(1)	
Undercurrent / Loss of Load	37	PTUC	●(1)	●(1)	
Directional Earth-Fault Overcurrent for Non-Earthed Systems	32N	PSDE	●(2)	●(2)	
Directional Power	32	PDOP, PDUP	●(1)	●(1)	
Phase Undervoltage	27	PTUV	●(2)	●(2)	
Phase Overvoltage	59	PTOV	●(2)	●(2)	
Residual Overvoltage	59N	PTOV	●(2)	●(2)	
Negative Sequence Overvoltage	47	PTOV	●(1)	●(1)	
Underfrequency	81U	PTUF	●(1)	●(1)	
Overfrequency	81O	PTOF	●(1)	●(1)	
Frequency Rate-of-Change	81RC	PFRC	●(1)	●(1)	
Control and Supervision Functions					
	ANSI	IEC 61850			
Trip Logic	94	PTRC	●(1)	●(4)	
Trip Circuit Supervision	74TC	STRC	●(2)	●(5)	
Circuit Breaker Failure	50BF	RBRF	●(2)	●(5)	
Automatic Reclosing	79	RREC	●(1)	●(1)	
Synchronism and Voltage Check	25	RSYN	○(1)	○(1)	(b)
Circuit Breaker Close Lock / Lockout	86	RCBL	●(1)	●(4)	
Fuse Failure / VT Supervision	60	RVTS	●(1)	●(1)	
CT Supervision		RCTS	●(2)	●(2)	
Circuit Breaker Control / Supervision	52	CSWI, XCBR	●(2)	●(5)	
Circuit Breaker Condition Monitoring		SCBR	●	●	
Circuit Switch Control / Supervision	89	CSWI, XSWI	●(6)	●(6)	
Automatic Voltage Control (up to 8 transformers in parallel)	90	ATCC	○(1)	○(1)	(c)
Tap Changer Control / Supervision		YLTC	○(1)	○(1)	(c)
Transformer Protection Supervision	94T	SPTR	●	●	
Distributed Automation		GGIO (or user defined)	●	●	
Programmable Automation (IEC 61131-3)		GAPC (or user defined)	●	●	
Monitoring and Recording Functions					
	ANSI	IEC 61850			
Three-Phase Measurements		MMXU, MSQI	●(2)	●(2)	
Single-Phase Measurements		MMXN	●(3)	●(3)	
Metering		MMTR	●(1)	●(1)	
Statistics **		MMXU (or user defined)	●	●	
Sags and Swells **		QVVR	○	○	(d)
Harmonics **		MHAI	○	○	(d)
Fault Locator	21FL	RFLO	●(1)	●(1)	
Disturbance Recorder		RDRE	●	●	
Chronological Event Log / SOE			●	●	
Fault Report			●	●	
Load Diagram / Trend Recorder **			●	●	
Histogram **			●	●	
Power Quality Event Recorder **			○	○	(d)
Self-tests and Watchdog			●	●	

- - Base feature
- - Optional feature
- ** - Currently under development
- (n) - Maximum number of instances

Functional restrictions according to order code:

- (a) With Restricted Earth-Fault (option A2)
- (b) With Synchronism Check (option B2)
- (c) With Voltage and VAR Control (option D2)
- (d) With Power Quality (option E2)

TECHNICAL SPECIFICATIONS

A.C. Analogue Inputs (General Data)		
Number	Max. 12 (depends on the type of expansion board)	
Rated frequency	$f_r = 50$ or 60 Hz (configurable by user)	
Angular reference	Any of the AC analogue inputs (configurable by user)	
Acquisition	ADC type	Sigma-Delta
	Resolution	24 bit (12 a.c. analogue inputs board)
		16 bit (8 a.c. analogue inputs board)
Sampling rate	160 samples per cycle at rated frequency (8 kHz @ $f_r = 50$ Hz; 9.6 kHz @ $f_r = 60$ Hz)	
A.C. Current Inputs		
Number	Max. 6 (depends on the type of expansion board)	
Standard option	Rated current	$I_r = 1$ or 5 A (configurable by user)
	Operation range	$[0.05 \dots 50.0] \times I_r$
	Thermal withstand	500 A for 1 s
		150 A for 10 s
		20 A continuous
	Dynamic load-carrying withstand	1250 A one half wave
Burden	< 0.05 VA @ $I_r = 1$ A < 0.15 VA @ $I_r = 5$ A	
Sensitive option	Rated current	$I_r = 1$ or 5 A (configurable by user)
	Operation range	$[0.005 \dots 5.0] \times I_r$
	Thermal withstand	250 A for 1 s
		10 A continuous
	Dynamic load-carrying withstand	750 A one half wave
Burden	< 0.05 VA @ $I_r = 1$ A < 0.25 VA @ $I_r = 5$ A	
A.C. Voltage Inputs		
Number	Max. 6 (depends on the type of expansion board)	
Standard range (configurable by user)	Rated voltage	$U_r = 100/3, 110/3, 115/3$ or $120/3$ V (residual)
		$U_r = 100/\sqrt{3}, 110/\sqrt{3}, 115/\sqrt{3}$ or $120/\sqrt{3}$ V (phase-earth)
		$U_r = 100, 110, 115$ or 120 V (phase-phase)
	Operation range	$[0.25 \dots 220] V_{rms}$
	Thermal withstand	500 V for 1 s 460 V continuous
Burden	< 0.05 VA @ U_r	
Extended range (configurable by user)	Rated voltage	$U_r = 100/\sqrt{3}, 110/\sqrt{3}, 115/\sqrt{3}$ or $120/\sqrt{3}$ V (residual)
		$U_r = 100, 110, 115, 120$ V or 230 V (phase-earth)
		$U_r = 100 \times \sqrt{3}, 110 \times \sqrt{3}, 115 \times \sqrt{3}, 120 \times \sqrt{3}$ V or 400 V (phase-phase)
	Operation range	$[0.5 \dots 440] V_{rms}$
	Thermal withstand	500 V for 1 s 460 V continuous
Burden	< 0.25 VA @ U_r	

D.C. Analogue Inputs		
Number	Max. 8	
Current ranges	Operation ranges (configurable by user)	$\pm 1 \text{ mA}; \pm 5 \text{ mA}; \pm 10 \text{ mA}; \pm 20 \text{ mA};$ $0 \dots 1 \text{ mA}; 0 \dots 5 \text{ mA}; 0 \dots 10 \text{ mA}; 0 \dots 20 \text{ mA}; 4 \dots 20 \text{ mA}$
	Thermal withstand	0.1 A continuous 0.5 A for 1 s
	Input impedance	50 Ω
Low voltage ranges	Operation ranges (configurable by user)	$\pm 5 \text{ V}; \pm 10 \text{ V}$
	Thermal withstand	20 V continuous 50 V for 1 s
	Input impedance	45 k Ω
High voltage ranges	Operation ranges (configurable by user)	$\pm 150 \text{ V}; \pm 300 \text{ V}$
	Thermal withstand	360 V continuous 420 V for 1 s
	Input impedance	1.3 M Ω
Acquisition	ADC type	Sigma-Delta, auto-ranging with PGA
	Resolution	16 bit + sign
	Accuracy	< 0.2 % full-range
	Normal-mode rejection ratio	> 110 dB
	Common-mode rejection ratio	> 130 dB
	Scan cycle	100 ms

Power Supply		
Rated values / voltage ranges	24 / 48 / 60 V d.c.	(19 .. 72 V d.c.)
	48 / 60 / 110 / 125 / 220 / 250 V d.c. 115 / 230 V a.c.	(38 .. 350 V d.c. / 60 .. 265 V a.c.)
Burden	Quiescent state (maximum configuration)	< 20 W (d.c.) < 40 VA (a.c.)
	Additional burden per actuated binary output	0.3 W
Ripple at d.c. auxiliary power supply	$\leq 12\%$	
Earthing arrangements for d.c. supply	Floating (free from earth)	Class EF

Binary Inputs		
Number	Base	8
	Maximum	104
Rated values / voltage thresholds (configurable by user)	24 V d.c.	$V_{\text{LOW}} \leq 8 \text{ V d.c.}$ $V_{\text{HIGH}} \geq 20 \text{ V d.c.}$
	48 / 60 V d.c.	$V_{\text{LOW}} \leq 26 \text{ V d.c.}$ $V_{\text{HIGH}} \geq 38 \text{ V d.c.}$
	110 / 125 V d.c.	$V_{\text{LOW}} \leq 66 \text{ V d.c.}$ $V_{\text{HIGH}} \geq 85 \text{ V d.c.}$
	220 / 250 V d.c.	$V_{\text{LOW}} \leq 132 \text{ V d.c.}$ $V_{\text{HIGH}} \geq 170 \text{ V d.c.}$
Maximum permitted voltage	300 V d.c.	
Burden	24 V d.c.	< 0.05 W (1.5 mA @ 24 V d.c.)
	48 / 60 V d.c.	< 0.1 W (1.5 mA @ 48 V d.c.)
	110 / 125 V d.c.	< 0.2 W (1.5 mA @ 125 V d.c.)
	220 / 250 V d.c.	< 0.4 W (1.5 mA @ 250 V d.c.)
Inrush current	Peak	50 mA $\pm 20\%$ @ V_r
	Impulse time constant	10 ms $\pm 20\%$
	Total impulse duration	Approx. 50 ms
Filtering	Debounce time	[1 .. 128] ms
	Oscillation filter	Max [2 .. 255] changes in [2 .. 10000] ms

Binary Outputs			
Number	Base	8 + Watchdog	
	Maximum	56 + Watchdog	
Standard option	Rated voltage	250 V a.c./ d.c.	
	Rated current	8 A	
	Making capacity		1 s @ 10 A
			0.2 s @ 30 A
	Breaking capacity	d.c.: 1 / 0.4 / 0.2 A @ 48 / 110 / 220 V; L/R < 40 ms a.c.: 1250 VA (250 V / 5 A); $\cos \varphi > 0,4$	
Voltage across open contacts (1 min)	1 kV _{rms}		
Pulse configuration	Pulse time	[0 .. 60000] ms	
	Delay time	[0 .. 60000] ms	
	Reset time	[0 .. 60000] ms	

Serial Ports - System Interface		
Number	Base interface	1 (RS-232/RS-485)
	Additional interface	1 (RS-232/RS-485, Plastic FO or Glass FO)
Transmission rate	Setting range	600 to 57600 baud
RS-232 option	Connector	D9 male connector
RS-485 option	Connector	D9 male connector
Plastic fibre optics option	Fibre type	Plastic fibre optics (POF) 1mm
	Wavelength	650 nm
	Connector	Snap-in type
	Maximum distance	45 m
	Optical power budget with 1 mm POF	10.4 dB (min.)
Glass fibre optics option	Fibre type	Multimode glass fibre optics 50/125 μm or 62.5/125 μm
	Wavelength	820 nm
	Connector	ST
	Maximum distance	1.7 km using an optical fibre 62.5/125 μm
	Optical power budget with 50/125 μm fibre	4.2 dB (min.)
	Optical power budget with 62.5/125 μm fibre	8.0 dB (min.)

Clock Synchronization Ports - IRIG-B Interface		
Number	1	
Galvanic option	Connector	D9 female connector
	Input voltage level	5 V, 12 V or 24 V
	Voltage range	$\pm 20\%$ of input voltage level

Rear Ethernet Ports - System Interface		
Number	Dual-interface (10/100BASE-TX or 100BASE-FX) or Single-interface (10/100BASE-TX or 100BASE-FX)	
Copper interface option	Media type	10/100BASE-TX
	Connector	RJ-45
Fibre interface option (100 Mbps)	Media type	100BASE-FX
	Fibre type	Multimode glass fibre optics 50/125 μm or 62.5/125 μm
	Wavelength	1300 nm
	Connector	MT-RJ or LC Duplex
	Maximum distance	2 km
	Output optical power (62.5/125 μm , NA = 0.275)	-20.0 dBm ... -14.0 dBm
	Output optical power (50/125 μm , NA = 0.20)	-23.5 dBm ... -14.0 dBm
	Receiver sensitivity	-31.0 dBm (max.)
Receiver overload	-14.0 dBm (min.)	

Front Ethernet Port - Service Interface		
Copper interface	Media type	10/100BASE-TX
	Connector	RJ-45

Case		
Design	Dimensions	6U, ½ x 19" rack
	Weight	< 6 kg

Environmental Conditions	
Operating temperature range	- 10 °C to + 60 °C, temporarily can be up to 70 °C (tested for 72 hours); Recommended: - 5 °C to + 55 °C
Storage temperature range	- 25 °C to + 70 °C
Relative humidity	10 to 95%
Pollution degree	2
Altitude	< 2000 m

CE Marking		
Electromagnetic Compatibility Directive (2004/108/CE)	Immunity	EN 61000-6-2: 2005 EN 60870-2-1: 1996 EN 60255-26: 2009 EN 50263: 1999
	Emission	EN 61000-6-4: 2007 + A1: 2011 EN 60870-2-1: 1996 EN 60255-26: 2009 EN 50263: 1999
Low Voltage Directive (2006/95/CE)		EN 60950-1: 2006 + A1: 2010 + A11: 2009 + A12: 2011 EN 60255-27: 2005 EN 60255-5: 2001

Insulation Tests		
High voltage test	EN 60255-5	2.0 kV a.c. 1 min 50 Hz
	EN 60255-27	2.8 kV d.c. 1 min (power supply)
Impulse voltage test	EN 60255-5	5 kV 1.2/50 µs, 0.5 J
	EN 60255-27	
Insulation resistance test	EN 60255-5	> 100 MΩ @ 500 V d.c.
	EN 60255-27	
Protective bonding resistance test	EN 60255-27	< 0.1 Ω

EMC – Immunity Tests		
Electrostatic discharge immunity test	EN 61000-4-2 EN 60255-22-2	8 kV contact; 15 kV air
Electromagnetic field immunity test	EN 61000-4-3 EN 60255-22-3	80 MHz – 1000 MHz; 30 V/m 1000 MHz – 3000 MHz; 10 V/m
Fast transient disturbance immunity test	EN 61000-4-4 EN 60255-22-4	4 kV, 5/50 ns
Surge immunity test	EN 61000-4-5 EN 60255-22-5	4/2 kV, 1.2/50 µs
Conducted RF disturbance test	EN 61000-4-6 EN 60255-22-6	10 V r.m.s., 150 kHz – 80 MHz @ 1 kHz 80% am
Power frequency magnetic field immunity test	EN 61000-4-8	100 A/m, cont; 1000 A/m, 3 s
Damped oscillatory magnetic field immunity test	EN 61000-4-10	100 A/m, 0.1 MHz and 1 MHz
Voltage variations immunity test	EN 61000-4-11 EN 60255-11	500 ms @ 70%; 200 ms @ 40% 500 ms @ 40%;
	EN 61000-4-29 EN 60255-11	500 ms @ 70%; 200 ms @ 40% 500 ms @ 40%;
Voltage interruptions immunity test	EN 61000-4-11 EN 60255-11	5, 10, 20, 50, 100, 200 and 500 ms
	EN 61000-4-29 EN 60255-11	5, 10, 20, 50, 100, 200 and 500 ms
Ring waves immunity test	EN 61000-4-12	4 kV common mode
Conducted, common mode disturbances in the frequency range 0 Hz to 150 kHz	EN 1000-4-16 EN 60255-22-7	150 V (differential mode) 100 Ω, 0.1 µF 300 V (common mode) 220 Ω, 0.47 µF
Damped oscillatory waves immunity test	EN 61000-4-18 EN 60255-22-1	2.5 kV common mode 1 kV differential mode

EMC – Emission Tests		
Radiated emission	EN 55022 EN 60255-25	30 – 1000 MHz class A
Conducted emission	EN 55022 EN 60255-25	0.15 – 30 MHz class A
Harmonic currents emission test	EN 61000-3-2	Class A
Voltage fluctuation and flicker emission test	EN 61000-3-3	Class A

Mechanical Tests		
Vibration tests	EN 60255-21-1	Class 2, 2 g, 10 Hz to 150 Hz
	EN 60870-2-2	Class Cm, 2 g, 9 Hz to 200 Hz
Shock tests	EN 60255-21-2	Class 2, 30 g, 11ms
	EN 60870-2-2	Class Cm, 30 g, 11 ms
Bump tests	EN 60255-21-2	Class 1, 10 g, 16ms
Free fall test	EN 60870-2-2	Class Cm, 0.25 m
	EN 60068-2-31	Method 1, 0.25 m
Degrees of protection provided by enclosures for electrical equipment against external mechanical impacts (IK code)	EN 50102	IK07

Environmental Tests			
Cold test	EN 60068-2-1	Operational	- 10 °C, 72h (Test Ad)
		Storage	- 25 °C, 72h (Test Ab)
Dry heat test	EN 60068-2-2	Operational	+ 70 °C, 72h (Test Bd)
		Storage	+ 85 °C, 72h (Test Bb)
Damp heat test, cyclic (12h+12h cycle)	EN 60068-2-30		+ 25 °C (97%) to + 40 °C (93%), 6 cycles
Damp heat test, steady state	EN 60068-2-78		+ 40 °C, 93% RH, 10 days
Degree of protection frontal side, flush mounted	EN 60529		IP50
Degree of protection, rear side	EN 60529		IP30

FUNCTIONAL SPECIFICATIONS

Restricted Earth Fault		
Number of independent functions		1 function
Number of stages (per function)		1 stage
Operation characteristic	Minimum operate current	$[0.05 \dots 1.0] \times I_r$; step 0.01
	Slope	$[0.0 \dots 1.0] I_{diff}/I_{bias}$; step 0.01
	Slope switch current	$[1.0 \dots 20.0] \times I_r$; step 0.01
	Accuracy	$\pm 3\% I_{op}$ (minimum $\pm 3\% I_r$)
	Dropout ratio	> 96%
	Pickup time	20 ms min. < 35 ms typ. for $I > 2 \times I_{op}$ and directional characteristic enabled
	Time delay	$[0 \dots 60000]$ ms; step 1
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	30 ms typ.
Directional characteristic	Open angle	$[60.0 \dots 90.0]^\circ$; step 1.0

(Directional) Phase Overcurrent		
Number of independent functions		2 functions
Number of stages (per function)		4 stages
Operational current	Setting range	[0.05 .. 40.0] × I _r ; step 0.01 (stages 1 and 2) [0.05 .. 20.0] × I _r ; step 0.01 (stages 3 and 4)
	Accuracy	± 1% I _{op} (minimum ± 1% I _r)
	Dropout ratio	> 96%
	Maximum cold load pickup multiplier	[1.0 .. 20.0] ; step 0.01 (independent per stage)
Definite time (all stages)	Pickup time	20 ms typ. for I > 2 × I _{op} , non-directional 35 ms typ. for I > 2 × I _{op} , directional
	Time delay	[0 .. 60000] ms ; step 1
	Time accuracy	± 3% (minimum ± 10 ms)
	Reset type	Instantaneous or delayed
	Reset time	30 ms typ.
	Dropout delay	[0 .. 60000] ms ; step 1
Inverse time (stages 3 and 4 only)	Curve types (ANSI/ IEEE)	Extremely Inverse, Very Inverse, Normal Inverse, Moderately Inverse, Long Time Extremely Inverse, Long Time Very Inverse, Long Time Inverse
	Curve types (IEC)	Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse
	Curve types (Recloser)	104 (N), 105 (R), 116 (D), 117 (B), 132 (E), 133 (C), 138 (W), 162 (KP)
	User defined curves	6 to 25 points
	Time multiplier	[0.05 .. 15.0] ; step 0.01
	Constant time adder	[0 .. 30000] ms ; step 1
	Minimum operation time	[0 .. 60000] ms ; step 10
	Maximum operation time	[0 .. 60000] ms ; step 10
	Start value	[1.0 .. 4.0] × I _{op} ; step 0.01
	Accuracy class	ANSI/ IEEE C37.112, Class 5 IEC 60255-3, Class 5
	Reset type	Instantaneous or dynamic
	Reset time	30 ms typ.
	Directionality	Direction options
Polarization		Negative-sequence voltage, positive-sequence voltage and voltage memory, according to actual fault condition; Cross phase-phase voltage and voltage memory, according to actual fault condition, in option
Characteristic angle		[-90.0 .. 90.0]° ; step 1.0
Phase angle accuracy		± 2°
VT failure action		Non-directional trip or function block
Inrush restraint	Operation	Disabled / enabled (independent stage selection)
	Restriction mode	Second harmonic
	Second harmonic ratio	[0.1 .. 1.0] I _{2h} /I _{1h} ; step 0.01
	Cross-block	One phase out of three, two phases out of three or disabled

(Directional) Earth-Fault Overcurrent		
Number of independent functions		3 functions
Number of stages (per function)		4 stages
Operational current	Quantity	Residual current (calculated sum of three phase currents) or neutral current (independent input)
	Setting range (normal CT input)	[0.05 .. 40.0] × I _r ; step 0.001 (stages 1 and 2) [0.05 .. 20.0] × I _r ; step 0.001 (stages 3 and 4)
	Setting range (sensitive CT input)	[0.005 .. 4.0] × I _r ; step 0.001
	Accuracy	± 1% I _{op} (minimum ± 1% I _r)
	Dropout ratio	> 96%
	Maximum cold load pickup multiplier	[1.0 .. 20.0]; step 0.01 (independent per stage)
Definite time (all stages)	Pickup time	25 ms typ. for I > 2 × I _{op} , non-directional 35 ms typ. for I > 2 × I _{op} , directional
	Time delay	[0 .. 60000] ms; step 1 (stages 1 and 2) [0 .. 300000] ms; step 1 (stages 3 and 4)
	Time accuracy	± 3% (minimum ± 10 ms)
	Reset type	Instantaneous or delayed
	Reset time	30 ms typ.
	Dropout delay	[0 .. 60000] ms; step 1
Inverse time (stages 3 and 4 only)	Curve types (ANSI/ IEEE)	Extremely Inverse, Very Inverse, Normal Inverse, Moderately Inverse, Long Time Extremely Inverse, Long Time Very Inverse, Long Time Inverse
	Curve types (IEC)	Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse
	Curve types (Recloser)	111 (8+), 113 (8), 131 (9), 135 (2), 140 (3), 141 (11)
	Curve types (other)	Logarithmic
	User defined curves	6 to 25 points
	Time multiplier	[0.05 .. 15.0]; step 0.01
	Constant time adder	[0 .. 30000] ms; step 1
	Minimum operation time	[0 .. 60000] ms; step 10
	Maximum operation time	[0 .. 60000] ms; step 10
	Start value	[1.0 .. 4.0] × I _{op} ; step 0.01
	Accuracy class	ANSI/ IEEE C37.112, Class 5 IEC 60255-3, Class 5
	Reset type	Instantaneous or dynamic
	Reset time	30 ms typ.
Directionality	Direction options	Non-directional, forward or reverse (independent stage selection)
	Polarization	Residual voltage and/or neutral current; negative-sequence voltage/current in option
	Characteristic angle	[-90.0 .. 90.0]°; step 1.0
	Minimum polarization voltage	[0.01 .. 1.0] × U _r ; step 0.005 (phase-earth rated voltage)
	Minimum polarization current	[0.05 .. 1.0] × I _r ; step 0.01
	Accuracy	± 1% U _{pol} (minimum ± 1% U _r) ± 1% I _{pol} (minimum ± 1% I _r)
	Phase angle accuracy	± 2°
	VT failure action	Non-directional trip or function block
Inrush restraint	Operation	Disabled / enabled (independent stage selection)
	Restriction mode	Second harmonic
	Second harmonic ratio	[0.1 .. 1.0] I _{2h} /I _{1h} ; step 0.01

(Directional) Negative Sequence Overcurrent		
Number of independent functions		1 function
Number of stages (per function)		4 stages
Operational current	Setting range	$[0.05 \dots 4.0] \times I_r$; step 0.01
	Accuracy	$\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$)
	Dropout ratio	> 96%
Definite time (all stages)	Pickup time	25 ms typ. for $I > 2 \times I_{op}$, non-directional 35 ms typ. for $I > 2 \times I_{op}$, directional
	Time delay	[0 .. 60000] ms; step 1
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset type	Instantaneous or delayed
	Reset time	30 ms typ.
	Dropout delay	[0 .. 60000] ms; step 1
	Inverse time (stages 3 and 4 only)	Curve types (ANSI/IEEE)
Curve types (IEC)		Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse
Curve types (Recloser)		104 (N), 105 (R), 116 (D), 117 (B), 132 (E), 133 (C), 138 (W), 162 (KP)
User defined curves		6 to 25 points
Time multiplier		[0.05 .. 15.0]; step 0.01
Constant time adder		[0 .. 30000] ms; step 1
Minimum operation time		[0 .. 60000] ms; step 10
Maximum operation time		[0 .. 60000] ms; step 10
Start value		$[1.0 \dots 4.0] \times I_{op}$; step 0.01
Accuracy class		ANSI/IEEE C37.112, Class 5 IEC 60255-3, Class 5
Reset type		Instantaneous or dynamic
Reset time		30 ms typ.
Directionality		Direction options
	Polarization	Negative-sequence voltage
	Characteristic angle	$[-90.0 \dots 90.0]^\circ$; step 1.0
	Minimum polarization voltage	$[0.01 \dots 1.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{pol}$ (minimum $\pm 1\% U_r$)
	Phase angle accuracy	$\pm 2^\circ$
	VT failure action	Non-directional trip or function block

Cold Load Pickup		
Number of independent functions		1 function
Operational current multiplier	Dynamic	0 to 100 % of overcurrent function setting
Operational time	Pickup delay	[0 .. 60] min; step 1
	Pickup time	[0 .. 720] min; step 1
	Reset delay	[0 .. 60] min; step 1
	Reset time	[0 .. 720] min; step 1
Loss of supply / return of supply detection	External activation	Optional (dedicated binary input)
	Maximum dead voltage	$[0.05 \dots 0.80] \times U_r$; step 0.01
	Minimum live voltage	$[0.20 \dots 1.20] \times U_r$; step 0.01

Thermal Overload		
Number of independent functions		1 function
Thermal characteristics	Time constant	[1 .. 60000] s ; step 1
	Maximum continuous current	[0.0 .. 999999.9] A ; step 0.1
	Maximum temperature rise	[0.0 .. 250.0] °C ; step 1.0
	Environment temperature	[-50.0 .. 200.0] °C ; step 1.0
Operate levels	Curve types	IEC 60255-8
	Initial temperature option	Environment or steady-state temperature
	Alarm temperature level	[0.0 .. 250.0] °C ; step 1.0
	Trip temperature level	[0.0 .. 250.0] °C ; step 1.0
	Reclose temperature level	[0.0 .. 250.0] °C ; step 1.0
	Accuracy class	Class 5

Switch-onto-Fault		
Number of independent functions		1 function
Number of stages (per function)		1 independent overcurrent stage; association with other protection function stages via trip logic
Operational current	Setting range	[0.5 .. 40.0] × I _r ; step 0.01
	Accuracy	± 1% I _{op} (minimum ± 1% I _r)
	Dropout ratio	> 96%
Instantaneous time	Pickup time	20 ms typ. for I > 2 × I _{op}
	Reset time	30 ms typ.
Activation	Origin	External order (CB close command) or dead line detection
	Maximum activation time (after CB closed)	[40 .. 60000] ms ; step 10
Dead line detection	Maximum dead current	[0.05 .. 1.5] × I _r ; step 0.01
	Maximum dead voltage	[0.05 .. 0.8] × U _r ; step 0.01
	Confirmation time	[40 .. 10000] ms ; step 10

Broken Conductor Check / Phase Unbalance		
Number of independent functions		1 function
Detection	Principle	Negative-sequence current / positive-sequence current ratio
	Ratio I ₂ /I ₁	[0.2 .. 1.0] ; step 0.01
	Minimum operating negative-sequence current	2.5% I _r
	Accuracy	2% (I ₂ /I ₁) _{op}
	Dropout ratio	> 97% (I ₂ > 0.05 × I _r) > 94% (I ₂ < 0.05 × I _r)
	Minimum phase current	[0.05 .. 0.3] × I _r ; step 0.01
Operation time	Alarm delay	[100 .. 60000] ms ; step 1
	Reset delay	[0 .. 60000] ms ; step 1
	Time accuracy	± 3% (minimum ± 20 ms)

Undercurrent / Loss of Load		
Number of independent functions		1 function
Number of stages (per function)		2 stages
Operational current	Setting range	$[0.005 \dots 5.0] \times I_r$; step 0.001
	Accuracy	$\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$)
	Dropout ratio	$< 104\% I_{op}$ (minimum dead band $2\% I_r$)
	Pickup criterion	Any phase or all phases
Definite time (all stages)	Pickup time	55 ms typ.
	Time delay	$[0 \dots 300000]$ ms; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 20 ms)
	Reset type	Instantaneous or delayed
	Reset time	55 ms typ.
	Dropout delay	$[0 \dots 60000]$ ms; step 10
Block conditions	Trip inhibition	Disabled / CB open
	Block time	$[0 \dots 7200]$ s; step 1

Directional Earth-Fault Overcurrent for Non-Earthed Systems		
Number of independent functions		2 functions
Principle	Operation quantities	Residual (or neutral) voltage; Residual (or neutral) voltage and residual (or neutral) current
Operational voltage	Setting range	$[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage)
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout ratio	$> 96\%$
Operational current	Quantity	Residual (or neutral) current
	Setting range (normal CT input)	$[0.05 \dots 1.0] \times I_r$; step 0.001
	Setting range (sensitive CT input)	$[0.005 \dots 1.0] \times I_r$; step 0.001
	Accuracy	$\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$)
	Dropout ratio	$> 96\%$
Definite time	Pickup time	35 ms typ.
	Pickup time delay	$[0 \dots 300000]$ ms; step 1
	Operation time delay	$[0 \dots 300000]$ ms; step 1
	Time accuracy	$\pm 3\%$ (minimum ± 20 ms)
	Reset time	35 ms typ.
Directionality	Direction options	Non-directional, forward or reverse
	Polarization	Residual voltage
	Measuring principle	Wattmetric (minimum power) or current phase angle (minimum current magnitude)
	Characteristic angle	$[0.0 \dots 90.0]^\circ$; step 1.0
	Open angle	$[10.0 \dots 90.0]^\circ$; step 1.0
	Phase angle accuracy	$\pm 2^\circ$
Alarm	Principle	Voltage unbalance
	Minimum voltage	$[0.1 \dots 2.0] \times U_r$; step 0.01
	Maximum voltage	$[0.1 \dots 2.0] \times U_r$; step 0.01

Directional Power		
Number of independent functions		1 function
Number of stages (per function)	Overpower stages	2 stages
	Underpower stages	2 stages
Overpower stages	Operational power	[0.001 .. 1000.0] MVA ; step 0.001
	Accuracy	$\pm 3\% S_{op}$ (minimum $\pm 1\% S_r$)
	Dropout ratio	$[0.80 .. 0.96] \times S_{op}$; step 0.01
	Characteristic angle	$[0.0 .. 360.0]^\circ$; step 1.0
Underpower stages	Operational power	[0.001 .. 1000.0] MVA ; step 0.001
	Accuracy	$\pm 3\% S_{op}$ (minimum $\pm 1\% S_r$)
	Dropout ratio	$[1.04 .. 1.20] \times S_{op}$; step 0.01
	Characteristic angle	$[0.0 .. 360.0]^\circ$; step 1.0
Definite time (all stages)	Pickup time	35 ms typ. for $I > 2 \times I_{op}$
	Time delay	[0 .. 60000] ms ; step 1
	Time accuracy	$\pm 3\%$ (minimum ± 20 ms)
	Reset time	35 ms typ.
	Dropout delay	[0 .. 60000] ms ; step 1

Phase Undervoltage		
Number of independent functions		2 functions
Number of stages (per function)		2 stages
Operational voltage	Quantity	Phase-phase or phase-earth voltages, in option
	Setting range	$[0.01 .. 2.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout ratio	< 104%
Definite time (all stages)	Pickup time	35 ms typ.
	Time delay	[0 .. 300000] ms ; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	35 ms typ.
Inverse time (stage 2 only)	Time multiplier	[0.05 .. 15.0] ; step 0.01
	Accuracy class	Class 5
	Reset type	Instantaneous

Phase Overvoltage		
Number of independent functions		2 functions
Number of stages (per function)		2 stages
Operational voltage	Quantity	Phase-phase or phase-earth voltages, in option
	Setting range	$[0.01 .. 2.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout ratio	> 96%
Definite time (all stages)	Pickup time	35 ms typ.
	Time delay	[0 .. 300000] ms ; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	35 ms typ.
Inverse time (stage 2 only)	Time multiplier	[0.05 .. 15.0] ; step 0.01
	Accuracy class	Class 5
	Reset type	Instantaneous

Residual Overvoltage		
Number of independent functions		2 functions
Number of stages (per function)		2 stages
Operational voltage	Quantity	Residual voltage (calculated or open-delta VT) or neutral voltage
	Setting range	$[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage)
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout ratio	> 96%
Definite time (all stages)	Pickup time	35 ms typ.
	Time delay	$[0 \dots 300000]$ ms ; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	35 ms typ.
Inverse time (stage 2 only)	Time multiplier	$[0.05 \dots 15.0]$; step 0.01
	Accuracy class	Class 5
	Reset type	Instantaneous

Negative Sequence Overvoltage		
Number of independent functions		1 function
Number of stages (per function)		2 stages
Operational voltage	Quantity	Negative sequence voltage
	Setting range	$[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage)
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout ratio	> 96%
Definite time (all stages)	Pickup time	35 ms typ.
	Time delay	$[0 \dots 300000]$ ms ; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	35 ms typ.
Inverse time (stage 2 only)	Time multiplier	$[0.05 \dots 15.0]$; step 0.01
	Accuracy class	Class 5
	Reset type	Instantaneous

Underfrequency		
Number of independent functions		1 function
Number of stages (per function)		5 stages
Operational frequency	Quantity	Phase-phase or phase-earth voltages
	Setting range	$[0.8 \dots 1.2] \times f_r$; step 0.0001
	Accuracy	± 10 mHz
	Dropout differential	< 20 mHz
Definite time (all stages)	Pickup time	70 ms typ.
	Time delay	$[0 \dots 120000]$ ms ; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	< 100 ms
Block voltage	Setting range	$[0.15 \dots 1.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)

Overfrequency		
Number of independent functions		1 function
Number of stages (per function)		5 stages
Operational frequency	Quantity	Phase-phase or phase-earth voltages
	Setting range	$[0.8 \dots 1.2] \times f_r$; step 0.0001
	Accuracy	± 10 mHz
	Dropout differential	< 20 mHz
Definite time (all stages)	Pickup time	70 ms typ.
	Time delay	$[0 \dots 120000]$ ms; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	< 100 ms
Block voltage	Setting range	$[0.15 \dots 1.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)

Frequency Rate-of-Change		
Number of independent functions		1 function
Number of stages (per function)		5 stages
Rate-of-change of frequency	Quantity	Phase-phase or phase-earth voltages
	Setting range	$[-10.0 \dots -0.1] \cup [0.1 \dots 10.0]$ Hz/s; step 0.05
	Accuracy	± 0.1 Hz/s
	Dropout differential	< 0.1 Hz/s
Definite time (all stages)	Pickup time	100 ms typ. for $ df/dt > 2 \times df/dt_{op}$
	Observation time interval for average calculation	$[10 \dots 50]$ cycles; step 1
	Time delay	$[0 \dots 120000]$ ms; step 10
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	< 100 ms
Frequency supervision (optional)	Setting range	$[0.8 \dots 1.2] \times f_r$; step 0.0001
	Accuracy	± 10 mHz
Block voltage	Setting range	$[0.15 \dots 1.0] \times U_r$; step 0.005
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)

Trip Logic		
Number of independent functions		4 functions
Operation	Number of circuit breakers	1
	Trip mode	Three-phase
	Switch-onto-fault interaction	Instantaneous trip with SOTF active (for selected protection relay stages)
	Additional outputs	General protection pickup and trip

Trip Circuit Supervision		
Number of independent functions		5 functions
Supervision	Number of supervised circuits	2 (main and backup)
	Alarm delay	$[500 \dots 60000]$ ms
	Reset time	$[500 \dots 60000]$ ms

Circuit Breaker Failure		
Number of independent functions		5 functions
Number of stages		1 or 2 (only external trip / re-trip and external trip)
Operation principles		Current and / or circuit breaker status supervision
Operational current	Start range	$[0.05 \dots 20.0] \times I_r$
	Operational range	$[0.05 \dots 1.5] \times I_r$
	Accuracy	$\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$)
Operation time	Re-trip time delay	$[0 \dots 30000]$ ms
	External trip time delay	$[50 \dots 30000]$ ms
	Time accuracy	$\pm 3\%$ (minimum ± 10 ms)
	Reset time	15 ms typ.

Automatic Reclosing		
Number of independent functions		1 function
Number of reclose shots		Maximum 5 shots
Channels	Number of channels	5
	Start inputs per channel	Maximum 5 protection function stages associated with each channel
Operation	Channel action options (first 2 cycles)	Ignore / block auto-reclose sequence / start new cycle (wait for protection trip) / start new cycle (auto-reclose trip)
	Channel action options (last 3 cycles)	Ignore / block auto-reclose sequence / start new cycle (wait for protection trip)
	Auto-reclose trip delay (first 2 cycles)	$[0 \dots 60000]$ ms
	Dead time (independent per channel and per cycle)	$[100 \dots 180000]$ ms
	Wait for master before close command	Optional
	Reclaim time	$[100 \dots 300000]$ ms
Block conditions	Maximum CB open time	$[10 \dots 1000]$ ms
	Maximum CB close time	$[10 \dots 1800000]$ ms
	Maximum wait time for protection trip	$[10 \dots 300000]$ ms
	Synchronism check	Disabled / enabled
	Maximum wait time for synchronism	$[0 \dots 60000]$ ms
	Maximum dead time	$[500 \dots 3000000]$ ms
	CB ready for OFO evaluation	Disabled / before start of auto-reclose sequence / before close command / before start of auto-reclose sequence and before close command
	Block time after successful reclose sequence	$[0 \dots 300000]$ ms
Coordination	Block time after manual close command	$[0 \dots 300000]$ ms
	Block high-speed protection element	Disabled / always / before second reclose shot / before third reclose shot / before fourth reclose shot / before fifth reclose shot
Frequent operation alarm	Zone Sequence Coordination	Disabled / enabled
	Observation time	$[0 \dots 720]$ min
	Maximum number of reclose shots	$[1 \dots 200]$

Synchronism and Voltage Check		
Number of independent functions		1 function
Operation	Operating modes	U ₁ dead / U ₂ dead U ₁ live / U ₂ dead U ₁ dead / U ₂ live U ₁ live / U ₂ live (synchronous) U ₁ live / U ₂ live (asynchronous) Unconditional release
	Command origin	Independent settings for manual and automatic CB close commands
Voltage check	Quantity	Phase-phase or phase-earth voltages
	Maximum dead voltage	$[0.05 \dots 0.8] \times U_r$
	Minimum live voltage	$[0.2 \dots 1.2] \times U_r$
	Maximum voltage	$[0.5 \dots 1.5] \times U_r$
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Dropout differential	$< 2\% U_r$
Frequency check	Permitted operating range	$f_r \pm 3 \text{ Hz}$
Magnitude difference	Setting range	$[0.01 \dots 0.5] \times U_r$
	Accuracy	$\pm 1\% U_r$
Phase angle difference	Setting range	$[2.0 \dots 80.0]^\circ$
	Accuracy	$\pm 2^\circ$
Frequency difference	Setting range	$[0.01 \dots 1.0] \text{ Hz}$
	Accuracy	$\pm 10 \text{ mHz}$
Asynchronous operation	Maximum frequency difference	$[0.02 \dots 2.0] \text{ Hz}$
	CB close time	$[10 \dots 500] \text{ ms}$
Confirmation time	Minimum measuring time	70 ms
	Time delay	$[0 \dots 60000] \text{ ms}$
	Time accuracy	$\pm 3\%$ (minimum $\pm 10 \text{ ms}$)
Measurements	Magnitude difference accuracy	$1\% U_r$
	Phase angle difference accuracy	2°
	Frequency difference accuracy	20 mHz

Circuit Breaker Close Lock / Lockout		
Number of independent functions		4 functions
Lock	Mode	Latched (resettable by user); unlatched; timed
	Reset time (for unlatched lock)	$[0 \dots 3600] \text{ s}$
	Lock time (for timed lock)	$[1 \dots 3600] \text{ s}$

Fuse Failure / VT Supervision		
Number of independent functions		1 function
Operation principles		MCB status supervision; analogue signal validation (asymmetrical / symmetrical failures)
Asymmetrical failure detection	Principle	Voltage and current unbalance (residual and negative-sequence components)
	Residual voltage threshold	$[0.01 \dots 1.0] \times U_r$ (phase-earth rated voltage)
	Residual current threshold	$[0.05 \dots 1.0] \times I_r$
	Negative-sequence voltage threshold	$[0.01 \dots 1.0] \times U_r$ (phase-earth rated voltage)
	Negative-sequence current threshold	$[0.05 \dots 1.0] \times I_r$
	Operation time	25 ms typ.
	Latch time	[1000 .. 20000] ms
Symmetrical failure detection	Principle	Three-phase undervoltage and current variation
	Voltage threshold	$[0.01 \dots 1.0] \times U_r$
	Current variation	$[0.1 \dots 1.0] \times I_r$
	Operation time	25 ms typ.
Voltage measurement evaluation	Alarms	Voltage absence check; polarity and sequence check
	Evaluation time	[1000 .. 60000] ms
Minimum current	Setting range	$[0.05 \dots 1.0] \times I_r$

CT Supervision		
Number of independent functions		2 functions
Operation principles		Analogue signal validation (asymmetrical / symmetrical failures)
Asymmetrical failure detection	Principle	Comparison with reference current and/or voltage
	Residual current threshold	$[0.05 \dots 4.0] \times I_r$
	Reference residual current threshold	$[0.05 \dots 4.0] \times I_r$
	Reference residual voltage threshold	$[0.01 \dots 1.0] \times U_r$
	Operation time	25 ms typ.
Symmetrical failure detection	Principle	Three-phase current drop and variation of reference current and/or voltage
	Pre-fault current threshold	$[0.1 \dots 1.0] \times I_r$
	Operation time	25 ms typ.
Alarm time	Time delay	[0 .. 60000] ms
Current measurement evaluation	Alarms	Polarity and sequence check
	Evaluation time	[1000 .. 60000] ms
	Minimum current	$[0.05 \dots 1.0] \times I_r$

Circuit Breaker Control		
Number of independent functions		5 functions
Blocking / release conditions	Block inputs (per type of command)	Independent for open and close commands
	Block inputs (per origin)	Independently defined for: general block, local manual command block, remote manual command block, automatic command block
	Interlocking	Freely programmed by user
	Synchronism check (for close commands)	Interaction with synchronism check function (disabled / enabled)
	Maximum wait time for synchronism	[0 .. 600000] ms
Block / interlocking bypass	Mode	Latched / timed
	Bypass time	[0 .. 3600] s
Hit & run	Open command delay	[0 .. 300] s
	Close command delay	[0 .. 300] s

Circuit Breaker Supervision		
Number of independent functions		5 functions
CB command	Minimum open command time	[0 .. 60000] ms
	Minimum close command time	[0 .. 60000] ms
	Adaptive pulse	Disabled / enabled
	Number of close (re)tries	[1 .. 500]
	Retry interval	[1 .. 60] s
CB status supervision	Intermediate state filtering	Disabled / enabled
	Filter time for intermediate state	[0 .. 60000] ms
CB operation supervision	Maximum start time	[0 .. 60000] ms
	Maximum operation time	[0 .. 60000] ms
	Maximum open pole time	[0 .. 60000] ms
Condition monitoring	Contact travel time monitoring	Independent for open and close operations
	Open operation time correction	[0 .. 500] ms
	Close operation time correction	[0 .. 500] ms
	Maximum operation counter	[0 .. 100000]
	Switched current exponent	[1.0 .. 3.0]
	Maximum switched square current sum	[1.0 .. 99999.0] kA ²
	Contact wear monitoring criterion	Disabled / remaining operations alarm / remaining operations warning / contact wear alarm / contact wear warning
	Contact wear warning level	[10000 .. 1] opening operations [1 .. 10000] × 0.01 %
	Contact wear alarm level	[10000 .. 1] opening operations [1 .. 10000] × 0.01 %

Circuit Switch Control		
Number of independent functions		6 functions
Blocking / release conditions	Block inputs (per type of command)	Independent for open and close commands
	Block inputs (per origin)	Independently defined for: general block, local manual command block, remote manual command block, automatic command block
	Interlocking	Freely programmed by user

Circuit Switch Supervision		
Number of independent functions		6 functions
SW command	Minimum open command time	[0 .. 60000] ms
	Minimum close command time	[0 .. 60000] ms
	Adaptive pulse	Disabled / enabled
SW status supervision	Intermediate state filtering	Disabled / enabled
	Filter time for intermediate state	[0 .. 60000] ms
SW operation supervision	Maximum start time	[0 .. 60000] ms
	Maximum operation time	[0 .. 60000] ms
	Maximum operation counter	[0 .. 100000]

Automatic Voltage Regulation		
Number of independent functions		1 function
Mode		Automatic or manual
Operational voltage	Quantity	A0, B0, C0, AB, BC, CA or positive sequence
	Reference voltage	$[0.85 \dots 1.20] \times U_r$
	Accuracy	$\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$)
	Admissible voltage deviation	$[0.005 \dots 0.09] \times U_r$
	Voltage deviation reset	$[0.25 \dots 1] \times$ admissible voltage deviation
Reference voltage variation	Trigger	External condition
	Number of configurable voltage adjustments	3
	Admissible variation	$[-0.20 \dots 0.20] \times U_r$
Time characteristic	Characteristic (1st control)	Definite or inverse time
	Operating time (1st control)	$[1 \dots 1000]$ s
	Characteristic (following controls)	Definite or inverse time
	Operating time (following controls)	$[1 \dots 1000]$ s
	Minimum operating time for inverse time	$[1 \dots 120]$ s
	Time accuracy	$\pm 3\%$ (minimum ± 125 ms)
Operation acceleration	Trigger	External condition or overvoltage threshold
	Overvoltage threshold	$[1.0 \dots 1.8] \times U_r$
	Characteristic	Inverse time or successive controls
Line drop compensation	Line resistance	$[0.0 \dots 150.0] \Omega$
	Line reactance	$[-150.0 \dots 150.0] \Omega$
Alarm and block conditions	Voltage upper limit (LV side)	$[0.7 \dots 1.2] \times U_r$, (dropout ratio > 99%)
	Voltage lower limit (LV side)	$[0.8 \dots 1.8] \times U_r$, (dropout ratio > 101%)
	Undervoltage (HV side)	$[0.5 \dots 1.2] \times U_r$, (dropout ratio > 101%)
	Undervoltage (LV side)	$[0.5 \dots 1.2] \times U_r$, (dropout ratio > 101%)
	Overcurrent	$[0.05 \dots 10] \times I_r$, (dropout ratio > 96%)
	Maximum consecutive raising controls	$[1 \dots 240]$
	Time interval associated with maximum number of raising controls	$[1 \dots 60]$ min
	Block time when maximum raising controls reached	$[0 \dots 99999]$ min
	Block inputs	Independently defined for: full block, automatic mode block, full raise / lower control block and automatic mode raise / lower control block
Parallel operation	Number of transformers	Up to 8
	Transformer reactance	$[0.1 \dots 200.0] \Omega$
	Method	Master-Follower or Circulating Current
	Master-Follower option	Follow tap or follow command
	Circulating Current option	Used independently from voltage regulation / used with voltage regulation by taking into account the circulating current's corresponding voltage difference
	Priority mode when parallel is first established	Manual or automatic
	Behaviour to changes in mode while in parallel	Follow mode, adapt mode or manual
Additional features for parallel operation	Voltage mismatch supervision	Threshold $[0.005 \dots 0.1] \times U_r$ Alarm delay $[1 \dots 300]$ s
	Tap position supervision	Maximum tap difference $[0 \dots 30]$ Tap offset $[-16 \dots 16]$
	Circulating current supervision	Two thresholds $[0.01 \dots 2.5] \times I_r$ Two alarms per threshold First alarm instantaneous Second alarm with delay $[1 \dots 60]$ min

Automatic Voltage Regulation		
	Tracking mode	Tap changer continues to be updated when transformer connected only through the HV side
	Automatic sync mode	Ensures the existence of only one master in the master-follower method
	Average voltage mode	Use voltage average of all the transformers connected to the parallel
	Simultaneous tapping	No simultaneous tapping of the transformers connected to the parallel is permitted
Three-winding transformers	Priority level	Secondary or tertiary
	Settings	Equal for both windings or separately configured
	Alarms	Differentiated by voltage level

Tap Changer Control and Supervision		
Number of independent functions		1 function
Tap changer specification	Position code	Digital: BINARY, GRAY, BCD, SIGNED BCD or 1-of-N Analogue: mA
	Tap position	[-16 .. 63]
	Tap position (mA)	[0.0 .. 25.0] mA
	Relation between voltage and tap position	Direct or inverse
	Reference tap	[-16 .. 63]
Operation	Control pulse duration	[0.5 .. 10.0] s
	Time after position change before the value is accepted (stable time)	[0 .. 60] s
	Timeout	[1 .. 120] s
Alarm and block conditions	Operation error	Maximum errors allowed [0 .. 20]
	Position error	Delay [0 .. 120] s
	Block inputs	Independently defined for: full block or raise / lower control block and supply lost
	Tap position	Lowest or highest tap reached

Three-Phase Measurements		
Number of independent functions		2 functions
Orientation		Forward or reverse
Current	Measurements	Phase, residual, neutral, symmetrical components
	Magnitude accuracy	0.25% I_r
	Phase angle accuracy	0.2°
	Range	$[0.05 .. 2.0] \times I_r$
Voltage	Measurements	Phase-earth, phase-phase, residual, neutral, symmetrical components
	Magnitude accuracy	0.25% U_r
	Phase angle accuracy	0.2°
	Range	$[0.05 .. 2.0] \times U_r$
Power	Measurements	Active, reactive, apparent and power factor (total and per phase)
	Accuracy	0.5% S_r
	Range	$[0.05 .. 2.0] \times S_r$
Frequency	Accuracy	10 mHz
	Range	$f_r \pm 3$ Hz

Single-Phase Measurements		
Number of independent functions		3 functions
Orientation		Forward or reverse
Current	Measurements	Phase, residual or neutral
	Magnitude accuracy	0.25% I_r
	Phase angle accuracy	0.2°
	Range	$[0.05 \dots 2.0] \times I_r$
Voltage	Measurements	Phase-earth, phase-phase, residual or neutral
	Magnitude accuracy	0.25% U_r
	Phase angle accuracy	0.2°
	Range	$[0.05 \dots 2.0] \times U_r$
Power	Measurements	Active, reactive, apparent and power factor
	Accuracy	0.5% S_r
	Range	$[0.05 \dots 2.0] \times S_r$
Frequency	Accuracy	10 mHz
	Range	$f_r \pm 3$ Hz

Metering		
Number of independent functions		1 function
Orientation		Forward or reverse
Energy counters	Active	Forward, reverse and total
	Reactive	Forward, reverse and total
	Apparent	Total
Accuracy		0.5%

Fault Locator		
Number of independent functions		1 function
Line parameters	Line section length	$[0.1 \dots 1000.0]$ length units
	Length units	km / miles
	Positive sequence resistance	$[0.01 \dots 500.0] \Omega$
	Positive sequence reactance	$[0.01 \dots 500.0] \Omega$
	Zero sequence resistance	$[0.01 \dots 500.0] \Omega$
	Zero sequence reactance	$[0.01 \dots 500.0] \Omega$
Fault location	Measuring principle	Local quantities (phase currents and voltages)
	Outputs	Fault type, fault loop, fault impedance, fault loop resistance and reactance, fault resistance, fault distance
	Fault distance	In ohm, km, miles and percentage of total line length
	Accuracy	2% of total line length ($30^\circ < \varphi < 90^\circ$)

Disturbance Recorder		
Recording	Number of records	Max. 200
	Sampling rate	40 samples per cycle at rated frequency (2 kHz @ $f_r = 50$ Hz; 2.4 kHz @ $f_r = 60$ Hz)
	Trigger options	External (user command), internal (analogue and binary channel supervision) or both
	Retrigger	Disabled / enabled
	Pre-fault time	[50 .. 500] ms
	Post-fault time	[50 .. 2000] ms
	Maximum record duration	[200 .. 10000] ms
	Maximum record duration (manual trigger)	[200 .. 10000] ms
Analogue channels	Action when memory is full	Overwrite older records
	Number	Up to 16 channels
	Trigger options	Defined by trigger levels (high / low) or none (only register)
	High trigger level	[0.0 .. 999999.9] (in A for currents, kV for voltages)
Binary channels	Low trigger level	[0.0 .. 999999.9] (in A for currents, kV for voltages)
	Number	Up to 96 channels
Binary channels	Trigger options	Rising edge, falling edge, none (only register)

Event Log		
Recording	Total number of events	Max. 25000
	Chronological order of events	Ascendant / descendant
	Time resolution	1 ms
	Local HMI visualization	Last 100 events
	Action when memory is full	Overwrite older records
Entities	Number	Max. 3000
	Reason for inclusion	Configurable (data-change, quality-change, data-update, range-change)

Fault Report		
Recording	Total number of reports	Max. 50
	Trigger	General protection pickup (trip logic)
	Fault type	Record a report every time a fault occurs or only in case a protection function tripped
	Recorded information	Fault summary, timeline, pre-fault and fault measurements, correlated disturbance records
	Local HMI visualization	Last report
	Action when memory is full	Overwrite older records

User Programmable Automation / Logic	
Maximum number of tasks	5
Scheduling	Pre-emptive multi-tasking (1 thread per task)
Distinct task priority levels	5
Maximum number of programs	64
Code area size	128 KB
Global area size (data and stack)	512 KB
On-event program execution	Yes, multi-event
Execution triggering events	Multiple device data changes / updates High-performance timers Control execution Cycle
Basic data types	Boolean, Floating points (32, 64 bits) and Integers (8, 16, 32, 64 bits)
Date / time	Yes
Programming languages	IEC 61131-3 ST and FBD
Standard library	Full
User function block libraries	Yes
In-tool code simulation	Available
Logical device association	Free association of user functions to logical devices
Setting groups	Settings freely defined for user functions

Input / Output Processing		
AC analogue inputs	Channel inputs	Phase-earth, phase-phase or neutral inputs
	Orientation	Forward or reverse
	Primary rated value	[0.0 .. 10000.0] (in A for currents, kV for voltages)
	External measuring transformer ratio	[1.0 .. 20000.0]
DC analogue inputs	Conversion function	Polynomial / piecewise linear
	Number of coefficients (polynomial function)	Up to 8
	Number of points (piecewise linear function)	Up to 8
Binary inputs	Types of entities	Single status / double status / integer status / pulse counters
	Intermediate state filtering (double status)	Disabled / enabled
	Filter time for intermediate state (double status)	[0 .. 30000] ms
	Code (integer status)	Binary / Gray / BCD / 1-of-N / Signed BCD
	Number of inputs (integer status)	Max. 32 bits (1-of-N code) Max. 6 bits (other codes)
	Pulse type (pulse counters)	Rising edge, falling edge or both
Binary outputs	Types of entities	Single / double (status or controls)
	Number of entities per output	Max. 16 entities per output (logical OR)

Device and Function Management		
Logical devices	Number	Max. 8
	Mode	Off / On / Test
	Set of functions	Free association of functions (built-in or user-defined)
Setting groups	Number of groups	8 (per logical device)
	Switchover	Via engineering tool, local HMI, remote control or logical condition (freely programmed by user)
Switching hierarchy	Switching authority levels	Process, bay, station and control centre
	Multilevel control	Disabled (only one switching authority allowed) / enabled (more than one switching authority)

Human-Machine Interface		
IED status indications	Available indications	POWER, RUN and COMM
	Blinking (RUN indication)	Configurable by user
Alarms	Number	16
	Colour	Red or yellow (configurable by user)
	Entities	Max. 16 entities per alarm (logical OR)
	Mode of operation	Unlatched or latched (resettable by user)
	Blinking (latched alarms)	Configurable by user
Function keys	Number	9
	Mode of operation	Status and/ or control, shortcut, selection from a list of options
Display	Type	640 × 480 graphic colour LCD
	Language	Portuguese / English / Spanish / French / Russian Others available (please contact)
	Information handling	Menu and mimic oriented
	Available information	Operation and control, management of operational settings, active setting groups and operating modes, IED status monitoring, access to measurements and records, among other actions, are available in the menu structure. The mimic structure is defined by the user.
Web interface	Access	Local (via service front Ethernet port) or remote (via system rear Ethernet ports)
	Available information	Visualization of operational settings, active setting groups and operating modes, IED status monitoring, access to measurements and records, among other actions.

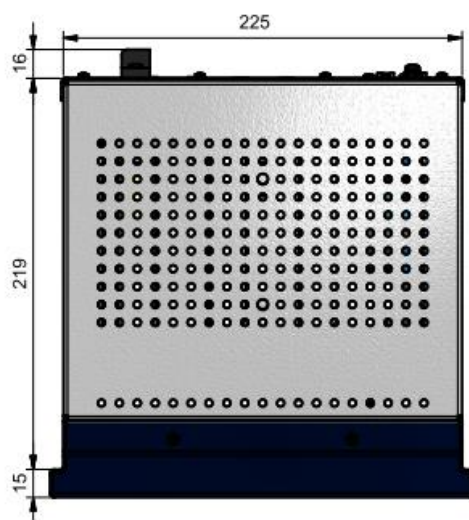
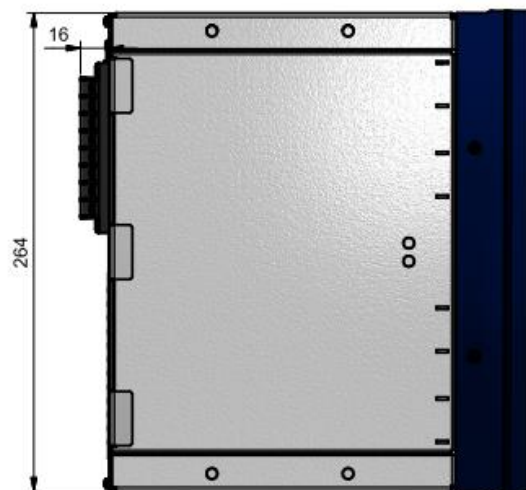
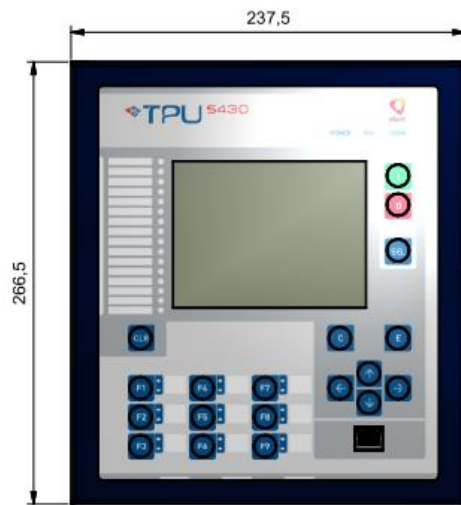
RTC and Clock Synchronization		
Application clock	Resolution	1 ms
	Time deviation (internal clock)	Max. 0.005%
	Synchronization	IRIG-B, NTP/ SNTP time slave or through communication protocol
	Backup power	Yes, lithium battery
	Local time offset	Adjustable
	Daylight savings configuration	Adjustable

IEC 61850		
IEC 61850-8-1 Server	Number of simultaneous clients	Max. 6
	Number of datasets	Max. 128
	Number of data attributes per dataset	Max. 128
	Maximum report control blocks (RCB)	Max. 128
	Buffered / unbuffered reports	Yes
IEC 61850-8-1 GOOSE	Number of published GOOSE control blocks	64
	Number of subscribed GOOSE control blocks	64

Other Communication Protocols	
Protocols Up/ Slave	IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial) IEC 60870-5-103 (Serial) DNP 3.0 (TCP/IP or Serial) Modbus (TCP/IP or Serial) Others available (Please Contact)

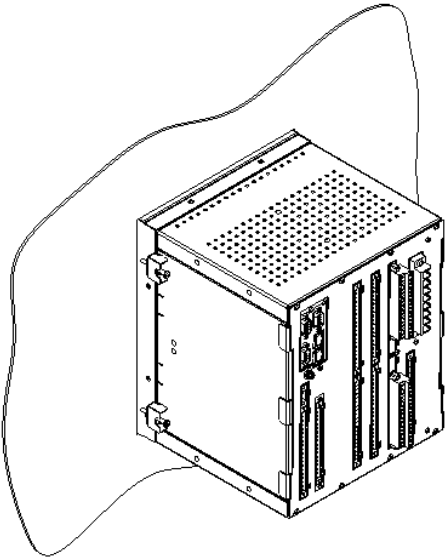
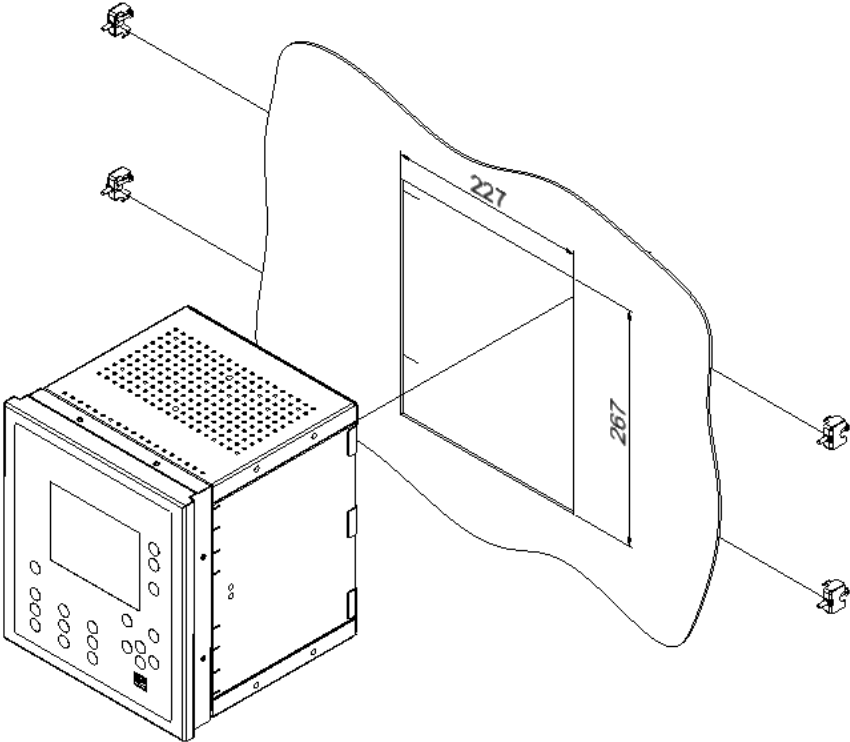
Automation Studio Engineering Software Integration	
IED configuration editors	Yes
IEC 61131-3 programming	Yes
Advanced 2D mimic design tools	Yes
System Engineering tools	Yes
Compound mimic symbols	Available
SVG and raster import	Available
Library projects	Yes
Device templates	Available
Settings static validation	Yes
Microsoft Excel® iterative import / export	Yes
Settings comparison	Yes
In-tool simulation	Available for user defined functions, mimics and RTDB
IEC 61850 SCL import / export	Yes
IEC 61850 user logical node designer	Available
SCL cross-validator integration	Available
Online monitoring integration	Available (IEC 61850 based and proprietary protocol)
Logics monitoring	Available
Add live device to project	Yes
Deploy / extract configuration settings	Yes
Extract records	Yes
Integrated analysis tools	COMTRADE, Fault Reports, SOE, System Logs, Statistical Data Trends
Team revision control system	Yes
Auto data retrieval and handling	Yes

DIMENSIONS



All dimensions in millimetres

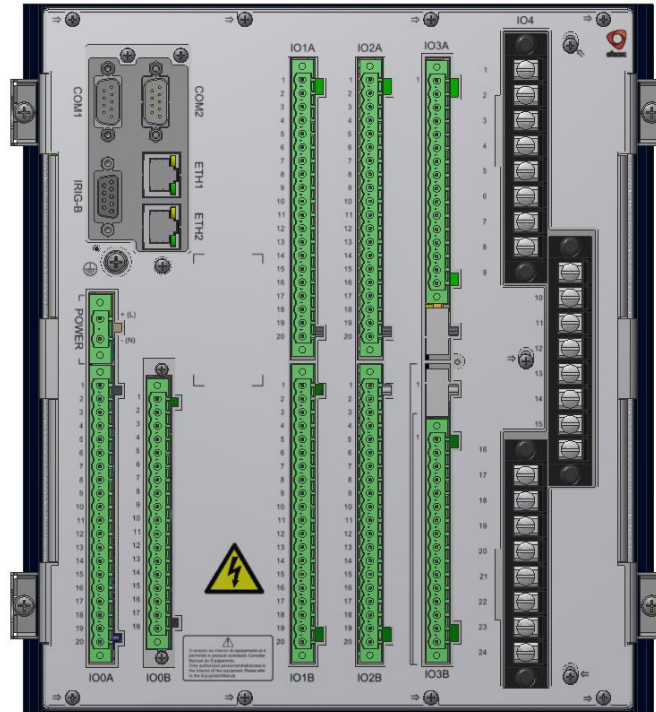
MOUNTING



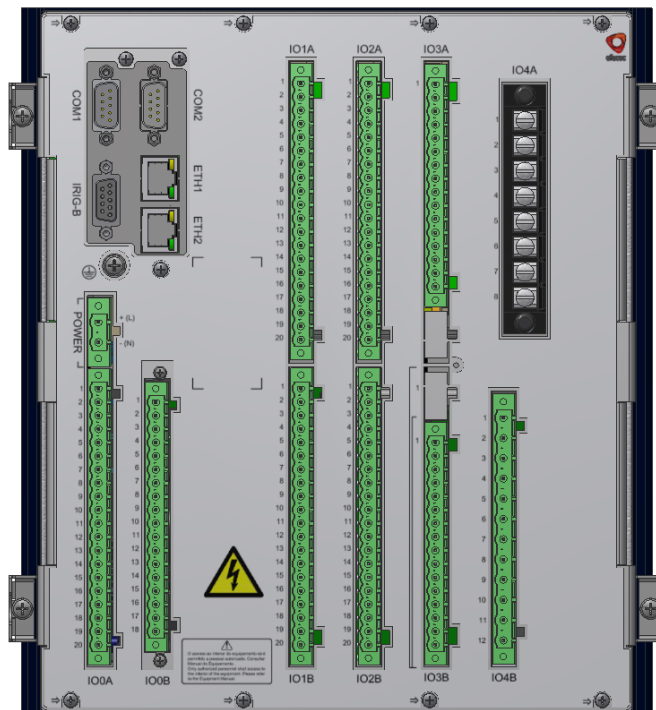
All dimensions in millimetres

CONNECTORS IDENTIFICATION

1/2 x 19" CASE WITH 12 A.C. ANALOGUE INPUTS BOARD, BACK SIDE VIEW

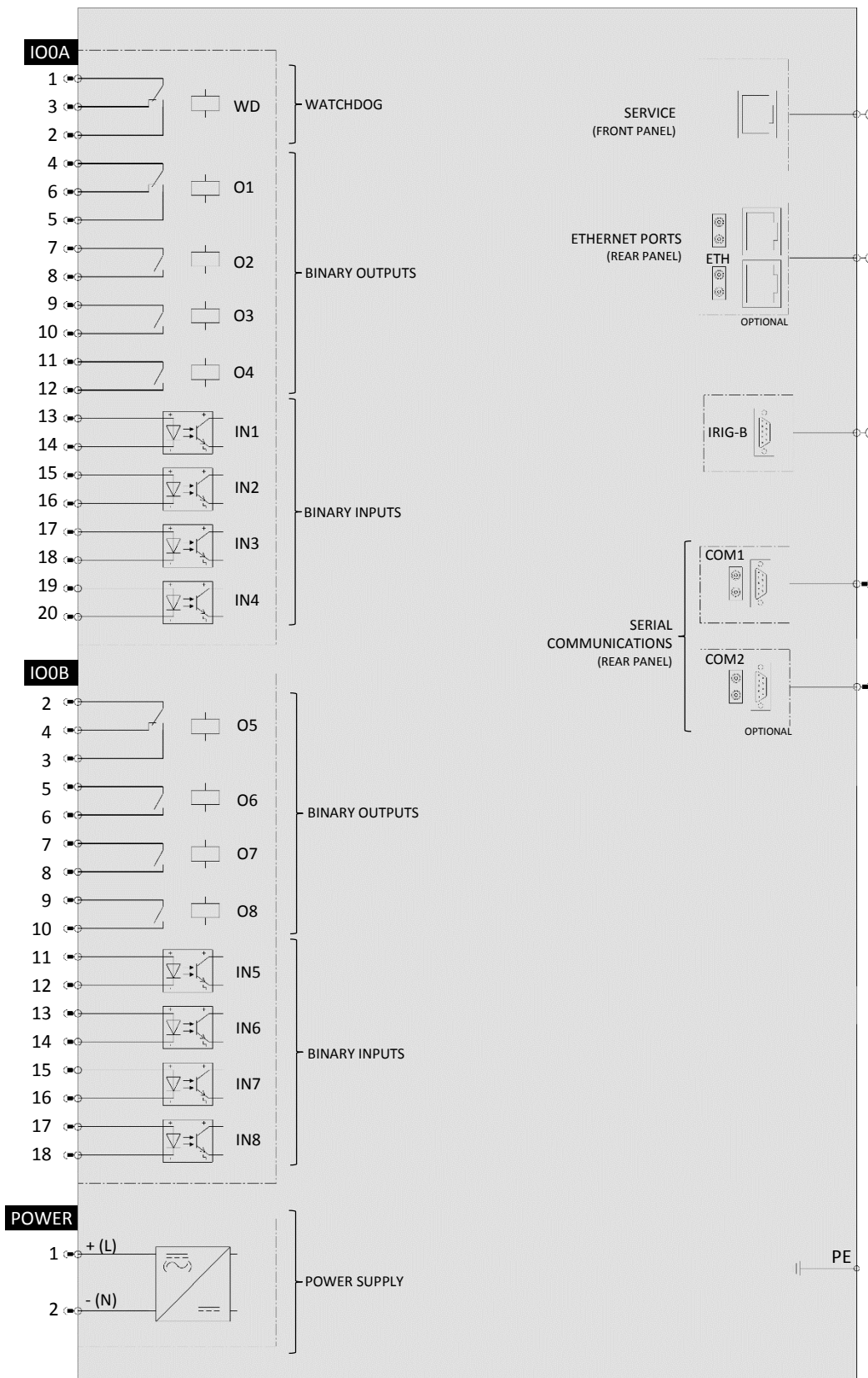


1/2 x 19" CASE WITH 8 A.C. ANALOGUE INPUTS BOARD, BACK SIDE VIEW

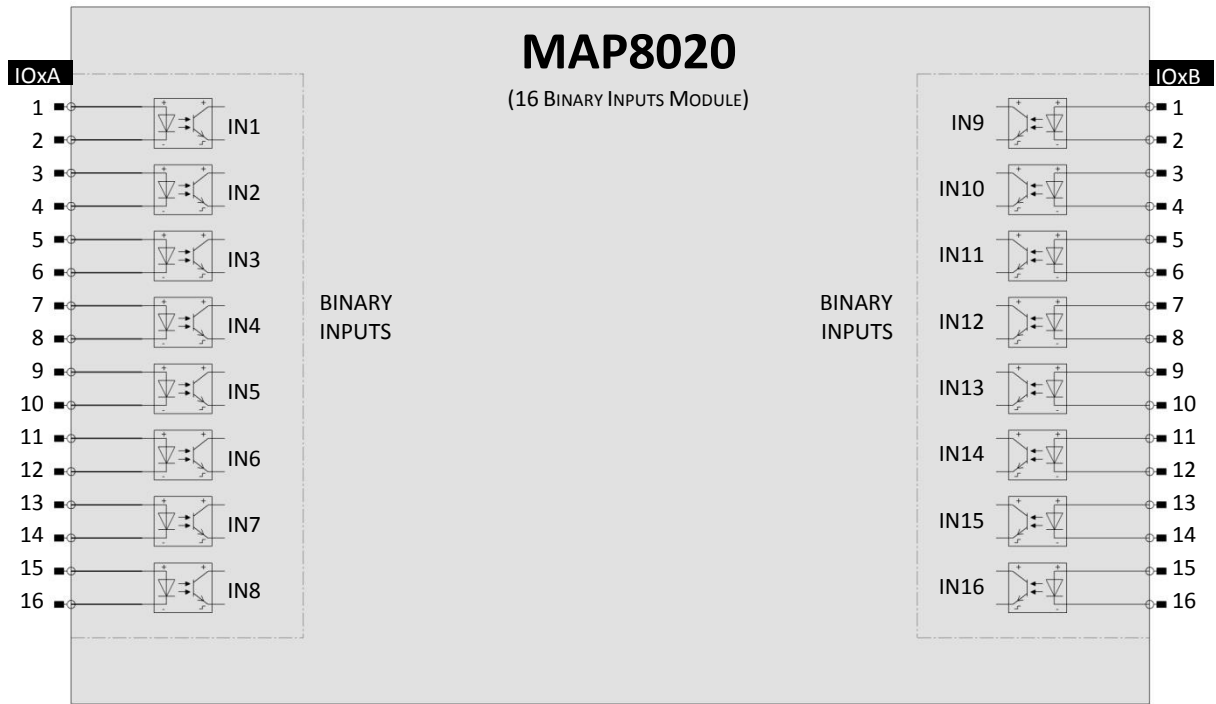


WIRING DIAGRAMS

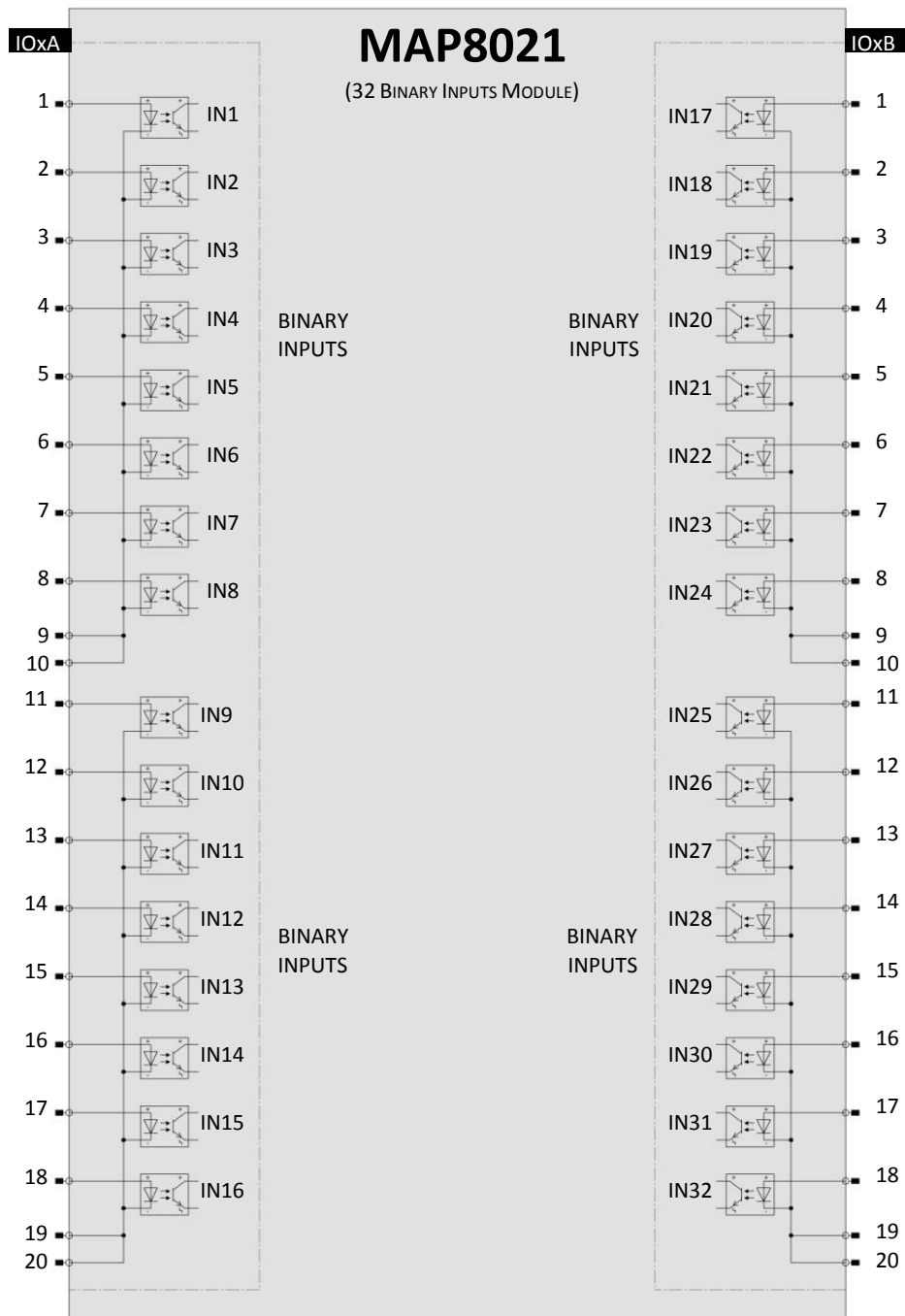
POWER SUPPLY, BASE I/O AND COMMUNICATIONS



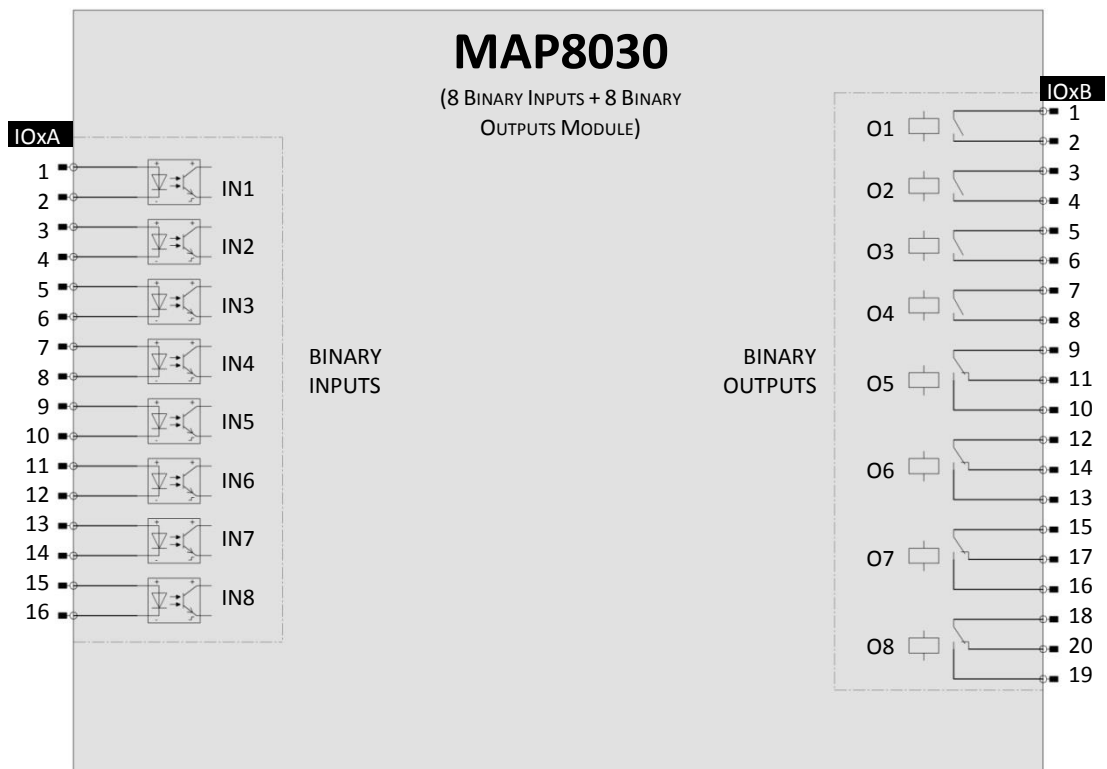
16 BINARY INPUTS MODULE (MAP8020, ORDER CODE A)



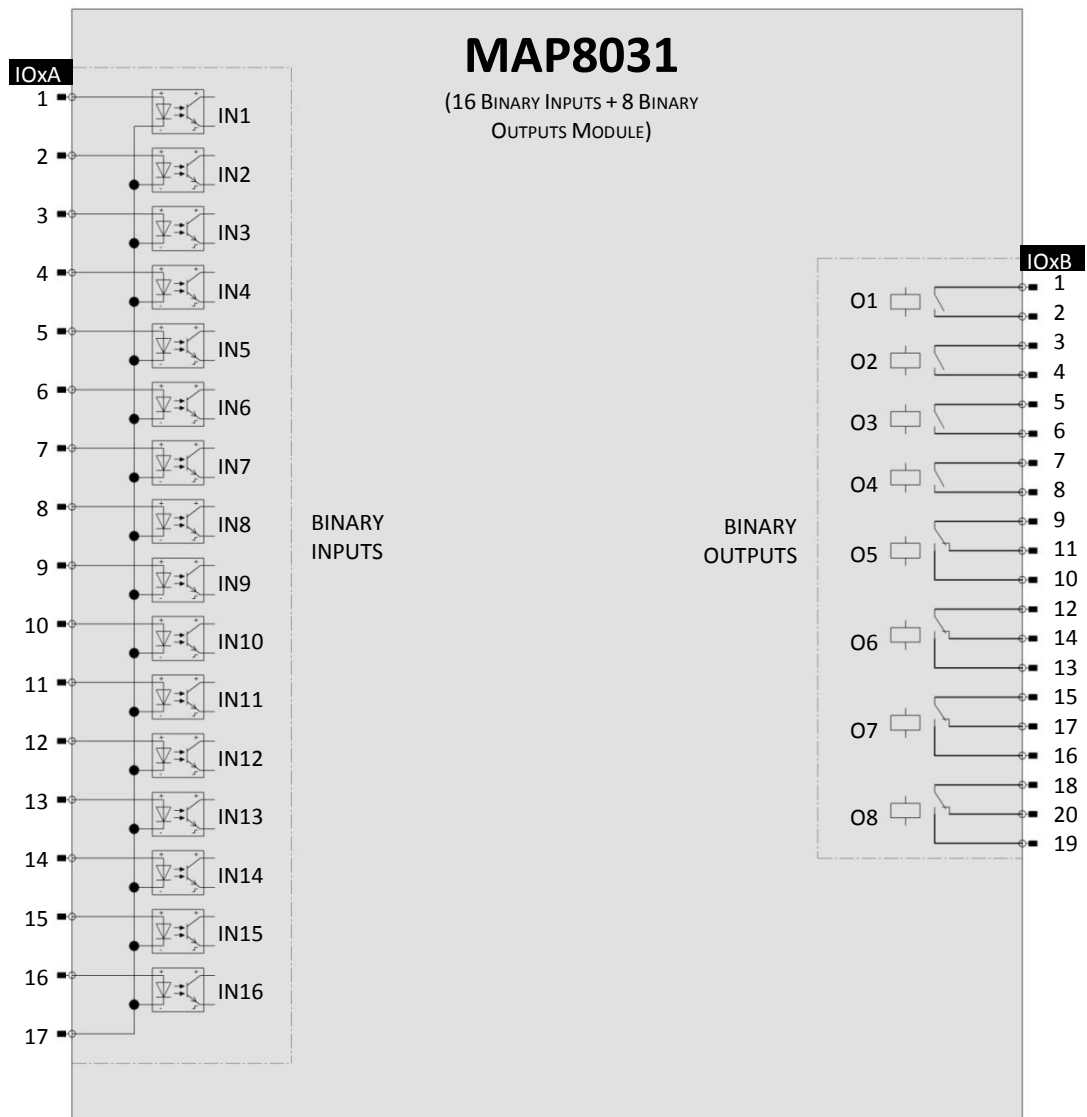
32 BINARY INPUTS MODULE (MAP8021, ORDER CODE B)



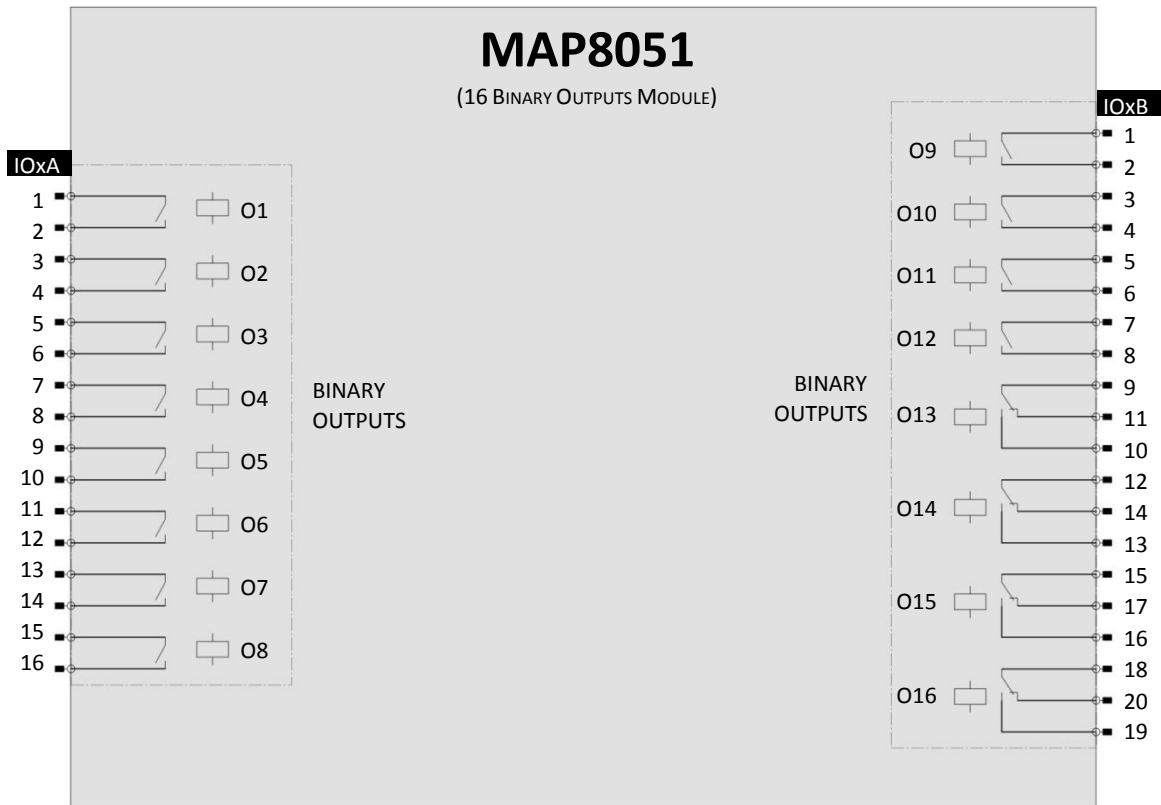
8 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8030, ORDER CODE C)



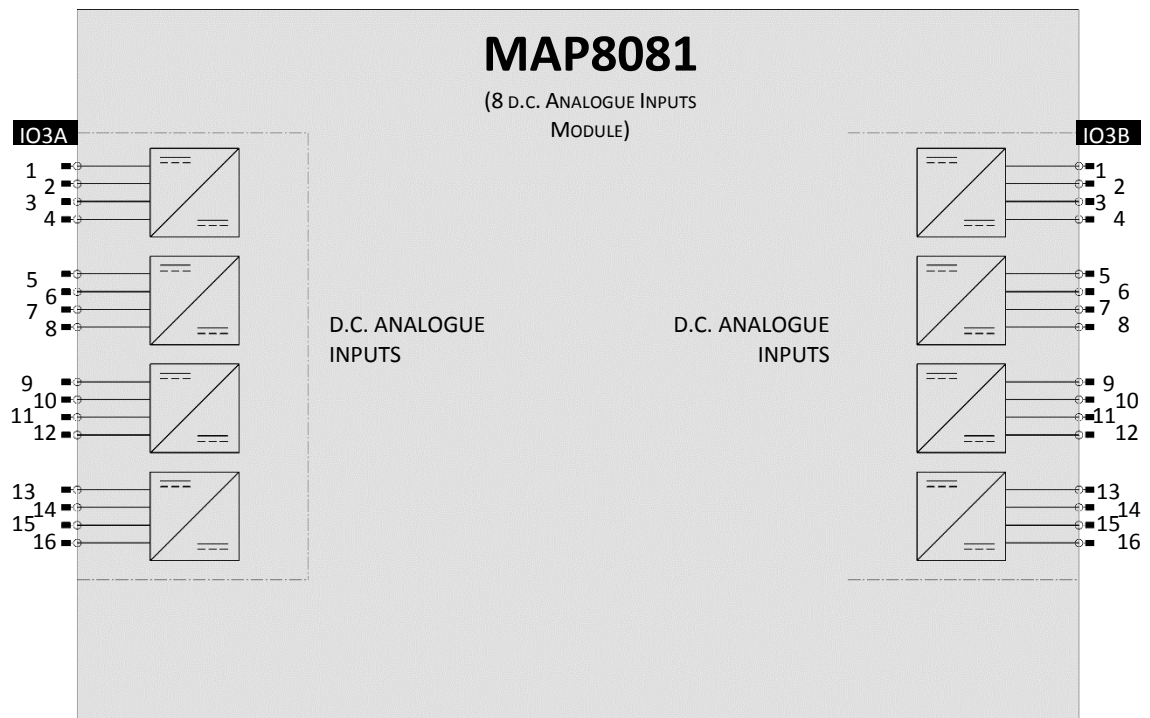
16 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8031, ORDER CODE D)



16 BINARY OUTPUTS MODULE (MAP8051, ORDER CODE E)



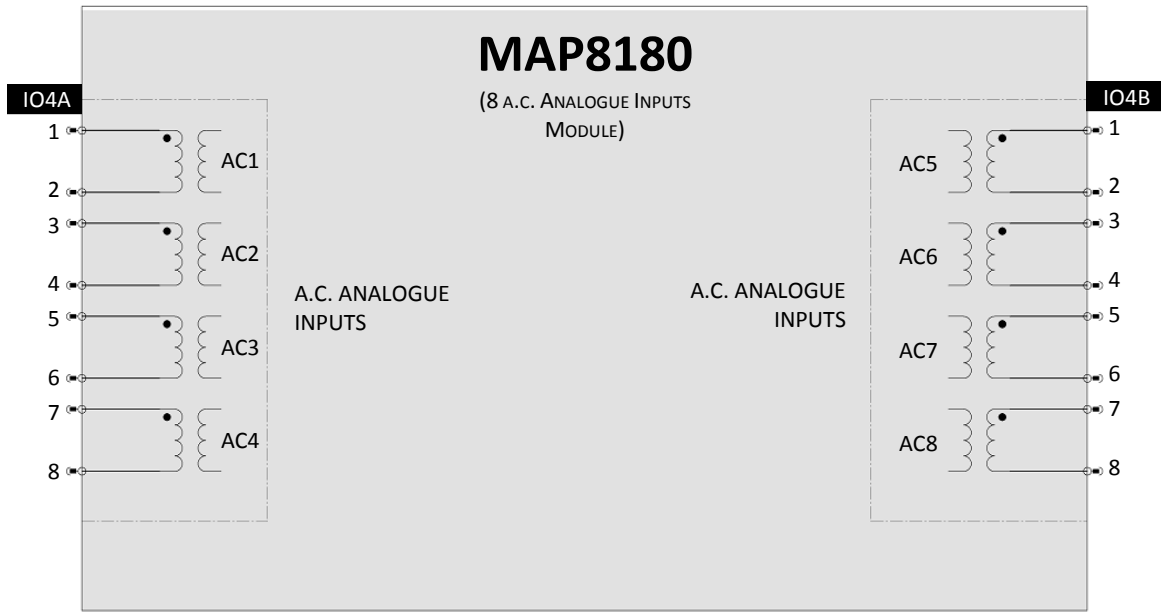
8 D.C. ANALOGUE INPUTS MODULE (MAP8081, ORDER CODE J)



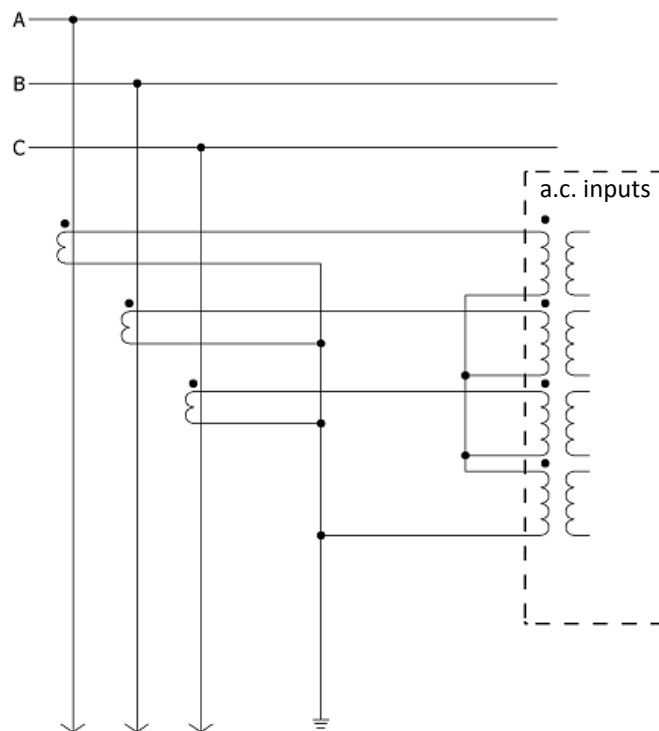
12 A.C. ANALOGUE INPUTS MODULE (MAP8082, ORDER CODES O & P)



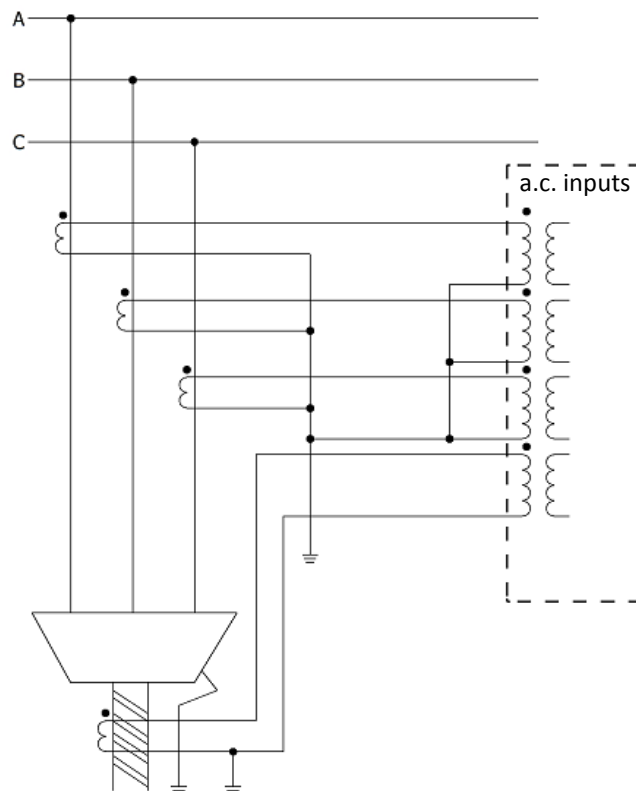
8 A.C. ANALOGUE INPUTS MODULE (MAP8180, ORDER CODES Q & R)



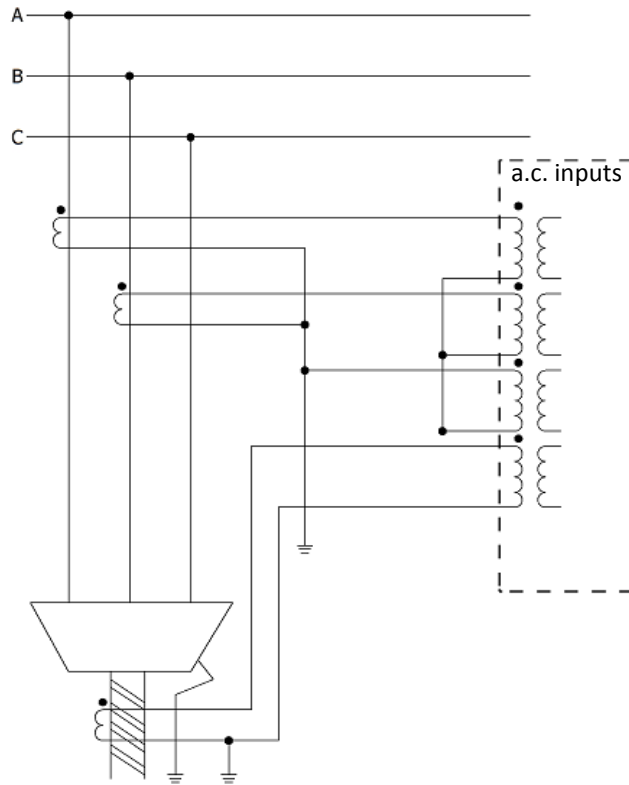
TYPICAL CONNECTIONS FOR A.C. CURRENT INPUTS



Phase and earth current inputs connection, with residual current obtained from the three phase currents by external Holmgreen circuit. Typical for low-impedance earthed systems.

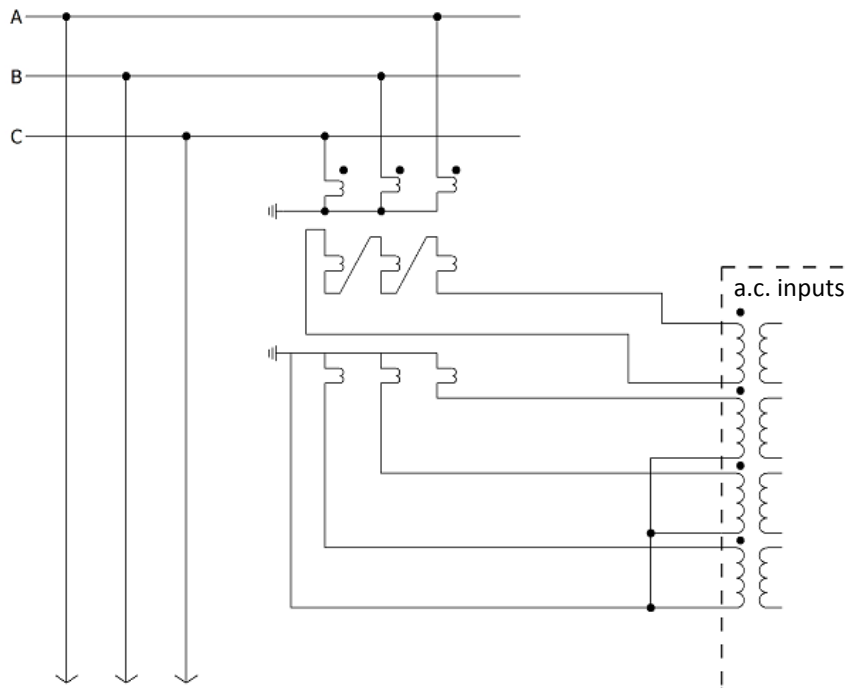


Phase and earth current inputs connection, with an independent phase-balance neutral current transformer for earth current measurement. Required in the case of isolated or compensated networks and for sensitive earth-fault detection.

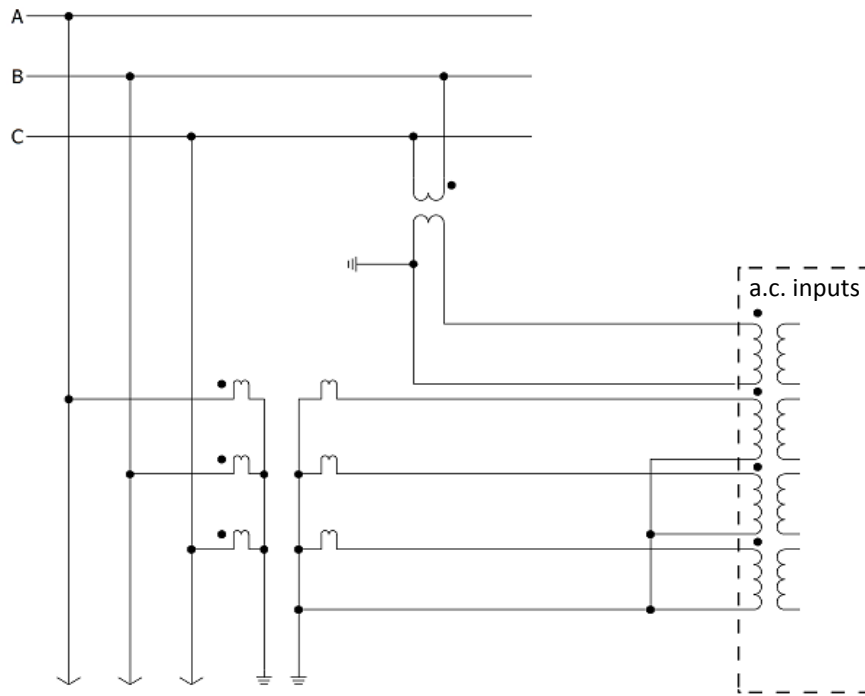


Phase and earth current inputs connection, with current transformers in only two phases. An independent neutral current transformer is required for earth current measurement. Optionally, the third phase current can be obtained from the other two by external circuitry.

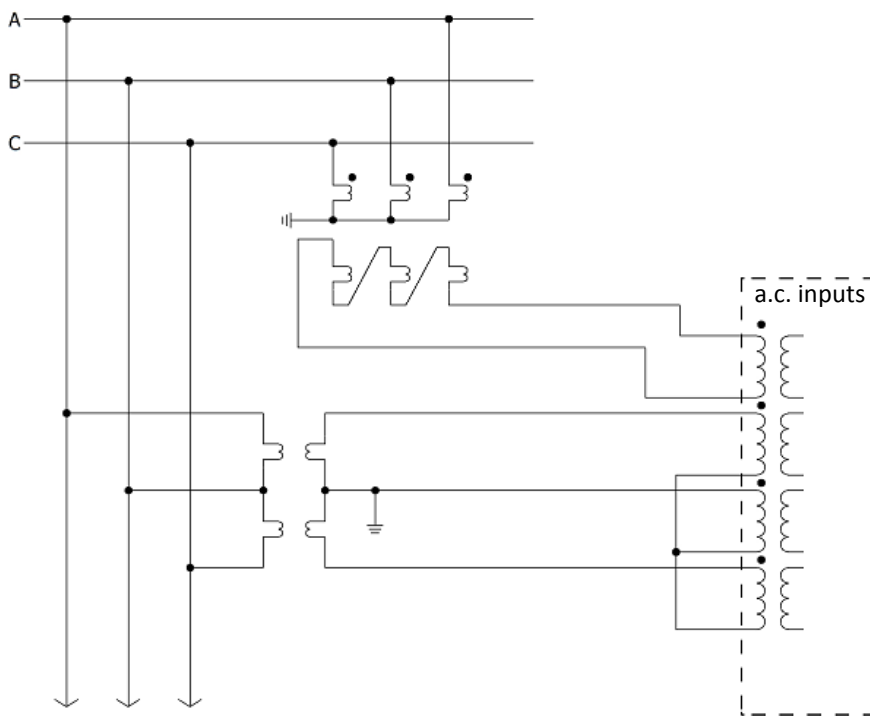
TYPICAL CONNECTIONS FOR A.C. VOLTAGE INPUTS



Three phase-to-earth voltage transformer connection, with an independent open-delta connected winding for residual voltage measurement. The fourth voltage input can provide polarization for directional earth-fault protection.



Three phase-to-earth voltage transformer connection and an additional phase-to-phase voltage input for busbar voltage measurement. Fourth voltage connection required for synchronism check applications. Polarization for directional earth-fault protection can be obtained from the internal sum of phase-to-earth voltages.



Alternative voltage transformer connection, with three phase-to-earth voltages obtained from two phase-to-phase voltage transformers (Aron circuit). Independent open-delta connected winding is required for residual voltage measurement.

PINOUT TABLES

POWER SUPPLY

POWER	
1	Power Supply + (L)
2	Power Supply - (N)

BASE BINARY I/O MODULE (MAP8100)

Base Binary I/O Module (MAP8100), see connectors description below				
IO0A			IO0B	
1		Common	1	Not Connected
2	Watchdog Output	Normally Open	2	
3		Normally Closed	3	Binary Output 5
4		Common	4	
5	Normally Open	5	Normally Open	
6	Binary Output 1	Normally Closed	6	Binary Output 6
7		Normally Open	7	
8	Binary Output 2	Normally Open	8	Binary Output 7
9		Normally Open	9	
10	Binary Output 3	Normally Open	10	Binary Output 8
11		Normally Open	11	
12	Binary Output 4	Normally Open	12	-
13		+	13	Binary Input 6
14	Binary Input 1	-	14	-
15		+	15	Binary Input 7
16	Binary Input 2	-	16	-
17		+	17	Binary Input 8
18	Binary Input 3	-	18	-
19		+		
20	Binary Input 4	-		

16 BINARY INPUTS MODULE (MAP8020)

16 Binary Inputs Module (MAP8020), see connectors description below				
IOxA			IOxB	
1		+	1	Binary Input 9
2	Binary Input 1	-	2	-
3		+	3	Binary Input 10
4	Binary Input 2	-	4	-
5		+	5	Binary Input 11
6	Binary Input 3	-	6	-
7		+	7	Binary Input 12
8	Binary Input 4	-	8	-
9		+	9	Binary Input 13
10	Binary Input 5	-	10	-
11		+	11	Binary Input 14
12	Binary Input 6	-	12	-
13		+	13	Binary Input 15
14	Binary Input 7	-	14	-
15		+	15	Binary Input 16
16	Binary Input 8	-	16	-
17			17	
18	Not connected		18	
19			19	
20			20	

32 BINARY INPUTS MODULE (MAP8021)

32 Binary Inputs Module (MAP8021), see connectors description below					
IOxA			IOxB		
1	Binary Input 1	+	1	Binary Input 17	+
2	Binary Input 2	+	2	Binary Input 18	+
3	Binary Input 3	+	3	Binary Input 19	+
4	Binary Input 4	+	4	Binary Input 20	+
5	Binary Input 5	+	5	Binary Input 21	+
6	Binary Input 6	+	6	Binary Input 22	+
7	Binary Input 7	+	7	Binary Input 23	+
8	Binary Input 8	+	8	Binary Input 24	+
9	Common to Binary Inputs 1 to 8	-	9	Common to Binary Inputs 17 to 24	-
10		-	10		-
11	Binary Input 9	+	11	Binary Input 25	+
12	Binary Input 10	+	12	Binary Input 26	+
13	Binary Input 11	+	13	Binary Input 27	+
14	Binary Input 12	+	14	Binary Input 28	+
15	Binary Input 13	+	15	Binary Input 29	+
16	Binary Input 14	+	16	Binary Input 30	+
17	Binary Input 15	+	17	Binary Input 31	+
18	Binary Input 16	+	18	Binary Input 32	+
19	Common to Binary Inputs 9 to 16	-	19	Common to Binary Inputs 25 to 32	-
20		-	20		-

8 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8030)

8 Binary Inputs + 8 Binary Outputs Module (MAP8030), see connectors description below					
IOxA			IOxB		
1	Binary Input 1	+	1	Binary Output 1	Normally Open
2		-	2		
3	Binary Input 2	+	3	Binary Output 2	Normally Open
4		-	4		
5	Binary Input 3	+	5	Binary Output 3	Normally Open
6		-	6		
7	Binary Input 4	+	7	Binary Output 4	Normally Open
8		-	8		
9	Binary Input 5	+	9	Binary Output 5	Common
10		-	10		Normally Open
11	Binary Input 6	+	11	Binary Output 6	Normally Closed
12		-	12		Common
13	Binary Input 7	+	13	Binary Output 7	Normally Open
14		-	14		Normally Closed
15	Binary Input 8	+	15	Binary Output 8	Common
16		-	16		Normally Open
17	Not connected		17	Binary Output 8	Normally Closed
18			18		Common
19			19		Normally Open
20			20		Normally Closed

16 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8031)

16 Binary Inputs + 8 Binary Outputs Module (MAP8031), see connectors description below					
IOxA			IOxB		
1	Binary Input 1	+	1	Binary Output 1	Normally Open
2	Binary Input 2	+	2		
3	Binary Input 3	+	3	Binary Output 2	Normally Open
4	Binary Input 4	+	4		
5	Binary Input 5	+	5	Binary Output 3	Normally Open
6	Binary Input 6	+	6		
7	Binary Input 7	+	7	Binary Output 4	Normally Open
8	Binary Input 8	+	8		
9	Binary Input 9	+	9		Common
10	Binary Input 10	+	10	Binary Output 5	Normally Open
11	Binary Input 11	+	11		Normally Closed
12	Binary Input 12	+	12		Common
13	Binary Input 13	+	13	Binary Output 6	Normally Open
14	Binary Input 14	+	14		Normally Closed
15	Binary Input 15	+	15		Common
16	Binary Input 16	+	16	Binary Output 7	Normally Open
17	Common to Binary Inputs 1 to 16	-	17		Normally Closed
18			18		Common
19	Not Connected		19	Binary Output 8	Normally Open
20			20		Normally Closed

16 BINARY OUTPUTS MODULE (MAP8051)

16 Binary Outputs Module (MAP8051), see connectors description below					
IOxA			IOxB		
1	Binary Output 1	Normally Open	1	Binary Output 9	Normally Open
2			2		
3	Binary Output 2	Normally Open	3	Binary Output 10	Normally Open
4			4		
5	Binary Output 3	Normally Open	5	Binary Output 11	Normally Open
6			6		
7	Binary Output 4	Normally Open	7	Binary Output 12	Normally Open
8			8		
9	Binary Output 5	Normally Open	9		Common
10			10	Binary Output 13	Normally Open
11	Binary Output 6	Normally Open	11		Normally Closed
12			12		Common
13	Binary Output 7	Normally Open	13	Binary Output 14	Normally Open
14			14		Normally Closed
15	Binary Output 8	Normally Open	15		Common
16			16	Binary Output 15	Normally Open
17			17		Normally Closed
18	Not Connected		18		Common
19		19	Binary Output 16	Normally Open	
20		20		Normally Closed	

8 D.C. ANALOGUE INPUTS MODULE (MAP8081)

8 d.c. Analogue Inputs Module (MAP8081), see connectors description below					
IO3A		IO3B			
1	d.c. Analogue Input 1	High Voltage (+)	1	d.c. Analogue Input 5	High Voltage (+)
2		Low Voltage (+)	2		Low Voltage (+)
3		Current (+)	3		Current (+)
4		Common (-)	4		Common (-)
5	d.c. Analogue Input 2	High Voltage (+)	5	d.c. Analogue Input 6	High Voltage (+)
6		Low Voltage (+)	6		Low Voltage (+)
7		Current (+)	7		Current (+)
8		Common (-)	8		Common (-)
9	d.c. Analogue Input 3	High Voltage (+)	9	d.c. Analogue Input 7	High Voltage (+)
10		Low Voltage (+)	10		Low Voltage (+)
11		Current (+)	11		Current (+)
12		Common (-)	12		Common (-)
13	d.c. Analogue Input 4	High Voltage (+)	13	d.c. Analogue Input 8	High Voltage (+)
14		Low Voltage (+)	14		Low Voltage (+)
15		Current (+)	15		Current (+)
16		Common (-)	16		Common (-)

12 A.C. ANALOGUE INPUTS MODULE (MAP8082)

12 a.c. Analogue Inputs Module (MAP8082), see connectors description below			
		Order Code	
IO4		O	P
1	a.c. Analogue Input 1	CT	CT
2			
3	a.c. Analogue Input 2	CT	CT
4			
5	a.c. Analogue Input 3	CT	CT
6			
7	a.c. Analogue Input 4	CT	CT
8			
9	a.c. Analogue Input 5	CT	CT
10			
11	a.c. Analogue Input 6	CT	Sensitive CT
12			
13	a.c. Analogue Input 7	VT	VT
14			
15	a.c. Analogue Input 8	VT	VT
16			
17	a.c. Analogue Input 9	VT	VT
18			
19	a.c. Analogue Input 10	VT	VT
20			
21	a.c. Analogue Input 11	VT	VT
22			
23	a.c. Analogue Input 12	VT	VT
24			

8 A.C. ANALOGUE INPUTS MODULE (MAP8180)

Order Code			
IO4A		Q	R
1	a.c. Analogue Input 1	CT	CT
2			
3	a.c. Analogue Input 2	CT	CT
4			
5	a.c. Analogue Input 3	CT	CT
6			
7	a.c. Analogue Input 4	CT	Sensitive CT
8			

Order Code		
IO4B		Q & R
1	a.c. Analogue Input 5	VT
2		
3	a.c. Analogue Input 6	VT
4		
5	a.c. Analogue Input 7	VT
6		
7	a.c. Analogue Input 8	VT
8		
9	Not Connected	
10		
11		
12		

SERIAL PORTS

COM1 & COM2	RS232	RS485
1	Not Connected	Not Connected
2	RxD <i>(Input Receive Data)</i>	DATA-
3	TxD <i>(Output Transmit Data)</i>	Not Connected
4	Not Connected	Not Connected
5	GND <i>(Ground)</i>	GND
6	Not Connected	Not Connected
7	RTS <i>(Output Request To Send)</i>	DATA+
8	CTS <i>(Input Clear To Send)</i>	Not Connected
9	Not Connected	Not Connected

IRIG-B

IRIG-B	
1	Not Connected
2	Not Connected
3	5 V Level Input
4	12 V Level Input
5	GND <i>(Ground)</i>
6	Not Connected
7	24 V Level Input
8	Not Connected
9	Not Connected

CONNECTORS DESCRIPTION

The next table lists all the external connectors included and supplied with the equipment:

CONNECTOR FOR POWER SUPPLY



Phoenix Front-GMSTB 2.5/2-STF-7.62 (1805987) type connector, 2 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR BINARY INPUTS AND STANDARD BINARY OUTPUTS (EXCEPT IO0B)



Phoenix Front-MSTB 2.5/20-STF-5.08 (1777976) type connector, 20 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR BINARY INPUTS AND STANDARD BINARY OUTPUTS (IO0B)



Phoenix Front-MSTB 2.5/18-STF-5.08 (1778140) type connector, 18 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR D.C. ANALOGUE INPUTS



Phoenix Front-MSTB 2.5/16-STF-5.08 (1777934) type connector, 16 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR A.C. VOLTAGE INPUTS (IO4B)



Phoenix Front-GMSTB 2.5/12-STF-7.62 (1806106) type connector, 12 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

TERMINAL FOR CONNECTION OF A.C. ANALOGUE INPUTS



Terminal Barrier type connector, 8 contacts. Accepts M3.5 or M4 ring-type lug terminals (max. 8 mm external diameter) for conductors with cross-sections from 1.5 to 4.0 mm². The connection is made by DIN 5.5 x 1.0 screwdriver or a PZ2 screwdriver. Tightening torque: 0.8 – 1.0 Nm.

TERMINAL FOR CONNECTION TO EARTH PROTECTION



Terminal to be fitted by M4 screw, for connection to Earth Protection. This connection is essential for the correct operation of the TPU S430. It should be solid for security reasons.

ORDER FORM

TPU S430 - 1 -										A	B	C	D	E	F	G	H	I	J	K	L	M	to next table...									
Region																																
Standard [⚡]															1																	
Eastern Europe and Central Asia															2																	
HMI																																
Graphic Display																B																
Power Supply																																
24 / 48 / 60 V d.c.																	1															
48 / 60 / 110 / 125 / 220 / 250 V d.c.;																	2															
115 / 230 V a.c. [⚡]																																
Binary Input Rated Voltage																																
24 V d.c.																		A														
48 / 60 V d.c.																		B														
110 / 125 V d.c.																		C														
220 / 250 V d.c.																		D														
Base Binary I/O																																
8 Binary Inputs + 8 Binary Outputs																				G												
Expansion I/O																																
Slot 1																					*											
Slot 2																						*										
Slot 3																							*									
Slot 4																								*								
COM1 Interface																																
RS-232 [⚡]																														1		
RS-485																														2		
COM2 Interface																																
Not used [⚡]																															X	
RS-232																															1	
RS-485																															2	
Plastic Optical Fibre																															3	
Glass Optical Fibre																															4	
Reserved																															XX	
ETH Interface																																
Not used																															X	
Single 10/100BASE-TX [⚡]																															1	
Single 100BASE-FX (MT-RJ connector)																															2	
Dual RSTP-enabled 10/100BASE-TX																															3	
Dual RSTP-enabled 100BASE-FX (MT-RJ connector)																															4	
Dual PRP/HSR-enabled 10/100BASE-TX **																															5	
Dual PRP/HSR-enabled 100BASE-FX **																															6	
Dual RSTP-enabled 100BASE-FX (LC Duplex connector)																															8	

...from previous table		N	O
Communication Protocols			
According to protocol list		XXX	
Application / Function Packages			
Without Restricted Earth-Fault		A1	
With Restricted Earth-Fault		A2	
Without Synchronism Check		B1	
With Synchronism Check		B2	
Without Capacitor Bank Protection and Control		C1	
With Capacitor Bank Protection and Control **		C2	
Without Voltage and VAR Control			D1
With Voltage and VAR Control			D2
Without Power Quality			E1
With Power Quality **			E2

* See Expansion boards option codes

** Currently under development

⊕ Preferred Options

EXPANSION BOARD CODES (FIELDS F TO I)

Expansion boards option codes table		
Board type	Board name	Code
16 Binary Inputs	MAP8020	A
32 Binary Inputs [♣]	MAP8021	B
8 Binary Inputs + 8 Binary Outputs	MAP8030	C
16 Binary Inputs + 8 Binary Outputs [♣]	MAP8031	D
16 Binary Outputs [♣]	MAP8051	E
8 d.c. Analogue Inputs	MAP8081	J
12 a.c. Analogue Inputs (6 CT + 6 VT)	MAP8082 OP5	O
12 a.c. Analogue Inputs (5 CT + 1 sensitive CT + 6 VT)	MAP8082 OP9	P
8 a.c. Analogue Inputs (4 CT + 4 VT)	MAP8180 OP3	Q
8 a.c. Analogue Inputs (3 CT + 1 sensitive CT + 4 VT) [♣]	MAP8180 OP4	R
Inexistent or unavailable slot	-	X

[♣] - preferred option

Notes:

- ◆ Slot 4 (field I) can only have one of four codes: 'O', 'P', 'Q' or 'R'.

MAXIMUM NUMBER OF ACCEPTABLE EXPANSION BOARDS

Maximum number of a.c. analogue input boards; Available slots	Maximum number of binary I/O expansion boards; Available slots	Maximum number of d.c. analogue input boards; Available slots
Max. 1 / slot 4	Max. 3 / slots 1 to 3	Max. 1 / slot 3

COMMUNICATION PROTOCOL CODES (FIELD N)

Slave / Server protocols	Code
None	X
IEC 60870-5-101/104	A
IEC 60870-5-103	B
IEC 61850-8-1 MMS Server and GOOSE publisher / subscriber	C
DNP 3.0 (Serial and/or TCP/IP)	D
Modbus (Serial and/or TCP/IP)	E
Others, please contact	

Notes:

- ◆ A maximum of 3 simultaneous protocols is allowed.

** - Currently under development

NOTES

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