



INTRODUCTION

TPU D500 is a state of the art high-end line differential protection relay prepared for multiple line arrangements, including two-end, three-end or multi-terminal overhead lines or underground cables, with option for in-zone transformer.

TPU D500 offers additional control, measurement and recording functions for easy and reliable power system management. TPU D500 further combines user programmability to deliver all the required functions for bay protection and control in a single unit.

Based on the 500 IED high-performance platform, TPU D500 provides flexible I/O options and has been designed with IEC 61850 and other open standards in mind, being future-proof and integration friendly.

As part of the Efacec CLP 500 family, TPU D500 provides object-oriented engineering, system tools and full IEC 61850 open design that allows users to straightforwardly apply the product in different system architectures.

PROTECTION

- Line Differential (up to 5 line ends)
- Distance
- Power Swing Blocking / OOS Tripping
- Distance / Directional Earth-Fault Teleprotection Schemes
- Remote Tripping
- Stub
- (Directional) Phase Overcurrent
- (Directional) Earth-Fault Overcurrent
- (Directional) Negative Seq. Overcurrent
- Thermal Overload
- Switch-Onto-Fault
- Broken Conductor Check
- Directional Earth-Fault Overcurrent for Non-Earthed Systems
- Directional Power
- Phase Undervoltage / Overvoltage
- Residual Overvoltage
- Negative Sequence Overvoltage
- Underfrequency / Overfrequency
- Frequency Rate-of-Change

CONTROL / SUPERVISION

- Three-Phase / Single-Phase Trip Logic
- Trip Circuit Supervision
- Circuit Breaker Failure
- Automatic Reclosing
- Synchronism and Voltage Check
- Lockout
- VT / CT Supervision
- Open Pole Detection
- Circuit Breaker Control / Supervision
- Circuit Switch Control / Supervision
- Distributed Automation
- Programmable Automation (IEC 61131-3 based)

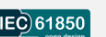


MONITORING / RECORDING

- Three-Phase Measurements
- Single-Phase Measurements
- Metering
- Fault Locator
- Disturbance Recorder
- Event Recorder / SOE
- Fault Report
- Self-tests and Watchdog

COMMUNICATION

- IEC 61850 Server / GOOSE
- IEC 60870-5-101/103/104
- DNP 3.0 (TCP/IP or Serial)
- Modbus (TCP/IP or Serial)
- Other serial and IP protocols available



TIME SYNCHRONIZATION

- IRIG-B Input
- SNTP Client



AUTOMATION STUDIO-READY

- Integrated configuration and programming
- Simplified engineering and handling

OVERVIEW

The TPU D500 is a high-end line differential protection relay that provides a high performing solution for power system protection while offering additional control, measurement and recording functions for an easy and reliable power system management.

The TPU D500 can be used as the main device for the protection of overhead lines and underground cables in transmission and sub-transmission networks. Its phase segregated line differential algorithm is suitable for two- or three- terminal lines, with possible complex breaker arrangements. It can also be used optionally in multi-terminal applications. The protection algorithm is prepared for applications where a transformer is included in the protection zone, in which case special measures are taken such as inrush restraint or vector group compensation.

Remote communication is based on IEEE C37.94 state-of-the-art standard, and communication channels can be optionally redundant. Sample synchronization can be achieved by GPS or by an alternative echo method, and includes compensation for route switching.

The TPU D500 integrates additional distance and overcurrent functions, which can be used as backup functions, for example when differential protection is unavailable due to communication failure. Several other current, voltage and frequency protection functions are also available.

Several control and supervision functions extend the application of the relay, with option for additional user-defined automation functions and logic (for example, interlocking logic or load transfer and restoration schemes). Accurate measured and metered values and a wide range of records and other stored information add value to the base application.

High configurability via flexible binary and analogue I/O configurations, advanced user-programmable functions and a comprehensive library of selectable built-in firmware functions allows the user to adapt the device to different substation topologies as well as protection and control schemes. Integration in a state of the art engineering toolset allows straightforward engineering throughout the system life-cycle without compromising user requirements.

Designed with IEC 61850 and other open standards in mind the TPU D500 is flexible, future-proof and can be seamlessly integrated in multivendor distributed protection, automation and control systems.

FEATURE SUMMARY

| TPU D500 | |
|---|------------------|
| Size | |
| 1 x 19" rack / height 6U | ● |
| A.C. Analogue Inputs | |
| Maximum Number of Inputs | 24 |
| Maximum Number of Current Inputs | 24 |
| Maximum Number of Voltage Inputs | 12 |
| D.C. Analogue Inputs | |
| Maximum Number of Inputs | 32 |
| Binary Inputs / Outputs | |
| Maximum Number of Inputs | 264 |
| Maximum Number of Outputs | 135 |
| High-speed, High Breaking Capacity Outputs | ○ |
| Base I/O | |
| 8 Binary Inputs + 7 Binary Outputs + Watchdog Output | ● |
| Availability | |
| Hardware Watchdog and Auto-reset | ● |
| Software Failure Detection and Recovery | ● |
| User Interface | |
| 640 x 480 Graphic Colour LCD | ○ |
| Programmable Alarms / Indication LEDs | 16 |
| Function Keys | 9 |
| Relay Status LEDs | 3 |
| Integrated Webservice | ● |
| Time Synchronization | |
| IRIG-B Input | ○ |
| SNTP Client | ● |
| By Communication Protocol | ● |
| Communication Interfaces (Rear Panel) | |
| 3 RS-232 / RS-485 / Glass / Plastic Fibre | ○ |
| Dual Ethernet 10/100BASE-TX or 100BASE-FX Interface | ● |
| RSTP-enabled Interface ** | ○ |
| PRP-enabled Interface | ○ |
| Single Ethernet 10/100BASE-TX or 100BASE-FX Interface | ● |
| Remote End Communication | |
| Maximum Number of Channels | 4 |
| Multi-mode Optical Fibre, up to 2 km | ○ |
| Single-mode Optical Fibre, up to 40 km | ○ |
| Single-mode Optical Fibre, up to 60 km | ○ |
| Single-mode Optical Fibre, up to 100 km | ○ |
| IEC 61850 Communications | |
| IEC 61850-8-1 Server and GOOSE | ○ |
| Communication Protocols | |
| Maximum Number of Simultaneous Protocols | 4 |
| Protocol Up / Slave | |
| IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial) | ○ |
| IEC 60870-5-103 (Serial) | ○ |
| DNP 3.0 (TCP/IP or Serial) | ○ |
| Modbus (TCP/IP or Serial) | ○ |
| Others available | (please contact) |
| Protocol Down / Master | |
| IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial) ** | ○ |
| IEC 60870-5-103 (Serial) | ○ |
| DNP 3.0 (TCP/IP or Serial) ** | ○ |
| Modbus (TCP/IP or Serial) | ○ |
| Others available | (please contact) |
| Configuration, Operational Support & Programming | |
| Automation Studio (Automation Studio license not included) | ● |
| Industry-specific function libraries | (please contact) |

● - Base feature

○ - Optional feature

** - Currently under development

| | | | Three-Phase Tripping (option A1) | | Single-Phase Tripping (option A2) | | |
|---|----------------------------|------------------------|-------------------------------------|------------------------------|--------------------------------------|------------------------------|-----|
| | | | Single-Breaker (option B1) | Multi-Breaker (option B2) | Single-Breaker (option B1) | Multi-Breaker (option B2) | |
| General | | | | | | | |
| | | | ● | ● | ● | ● | |
| | | | | | ● | ● | |
| | | | ● | ● | ● | ● | |
| | | | | ● | | ● | |
| Protection Functions | | | | | | | |
| | ANSI | IEC 61850 | | | | | |
| Line Differential (up to 5 line ends) | 87L | PDIF, PHAR | ■(1) | ■(1) | ■(1) | ■(1) | (a) |
| Line + Transformer Differential (up to 5 line ends) | 87L/87T | PDIF, PHAR | ■(1) | ■(1) | ■(1) | ■(1) | (b) |
| Distance | 21 | PDIS | ○(1) | ○(1) | ○(1) | ○(1) | (c) |
| Load Encroachment and Phase Selection | 21LE | PDIS | ○(1) | ○(1) | ○(1) | ○(1) | (c) |
| Power Swing Blocking / Out-Of-Step Tripping | 68/78 | RPSB | ○(1) | ○(1) | ○(1) | ○(1) | (d) |
| Distance Teleprotection Schemes | 85(21) | PSCH | ○(1) | ○(1) | ○(1) | ○(1) | (c) |
| Echo and Weak End Infeed Logic – Distance | 85/27WI | PSCH | ○(1) | ○(1) | ○(1) | ○(1) | (c) |
| Directional Earth-Fault Teleprotection Schemes | 85(67N) | PSCH | ●(1) | ●(1) | ●(1) | ●(1) | |
| Echo and Weak End Infeed Logic – Directional Earth-Fault | 85/59NWI | PSCH | ●(1) | ●(1) | ●(1) | ●(1) | |
| Remote Tripping | 85 | PSCH | ●(1) | ●(1) | ●(1) | ●(1) | |
| Stub | 87STB | PDIF | | ●(1) | | ●(1) | |
| (Directional) Phase Overcurrent | 50/51/67 | PTOC, RDIR | ●(1) | ●(1) | ●(1) | ●(1) | |
| (Directional) Earth-Fault Overcurrent | 50N/51N/67N 50G/51G/67G | PTOC, RDIR | ●(2) | ●(2) | ●(2) | ●(2) | |
| (Directional) Negative Sequence Overcurrent | 46/67 | PTOC, RDIR | ●(1) | ●(1) | ●(1) | ●(1) | |
| Editable Time-Current Curves | | | ● | ● | ● | ● | |
| Inrush Restraint | 68 | PHAR | ● | ● | ● | ● | |
| Thermal Overload | 49 | PTTR | ●(1) | ●(1) | ●(1) | ●(1) | |
| Switch-onto-Fault | 50HS | RSOF, PIOC | ●(1) | ●(1) | ●(1) | ●(1) | |
| Broken Conductor Check / Phase Unbalance | 46BC | RBCD | ●(1) | ●(1) | ●(1) | ●(1) | |
| Directional Earth-Fault Overcurrent for Non-Earthed Systems | 32N | PSDE | ●(2) | ●(2) | ●(2) | ●(2) | |
| Directional Power | 32 | PDOP, PDUP | ●(1) | ●(1) | ●(1) | ●(1) | |
| Phase Undervoltage | 27 | PTUV | ●(1) | ●(1) | ●(1) | ●(1) | |
| Phase Overvoltage | 59 | PTOV | ●(1) | ●(1) | ●(1) | ●(1) | |
| Residual Overvoltage | 59N | PTOV | ●(1) | ●(1) | ●(1) | ●(1) | |
| Negative Sequence Overvoltage | 47 | PTOV | ●(1) | ●(1) | ●(1) | ●(1) | |
| Underfrequency | 81U | PTUF | ●(1) | ●(1) | ●(1) | ●(1) | |
| Overfrequency | 81O | PTOF | ●(1) | ●(1) | ●(1) | ●(1) | |
| Frequency Rate-of-Change | 81RC | PFRC | ●(1) | ●(1) | ●(1) | ●(1) | |
| Control and Supervision Functions | | | | | | | |
| | ANSI | IEC 61850 | | | | | |
| Trip Logic | 94 | PTRC | ●(1) | ●(1) | ●(1) | ●(1) | |
| Trip Circuit Supervision | 74TC | STRC | ●(3) | ●(6) | ●(3) | ●(6) | |
| Circuit Breaker Failure | 50BF | RBRF | ●(1) | ●(2) | ●(1) | ●(2) | |
| Automatic Reclosing | 79 | RREC | ●(1) | ●(2) | ●(1) | ●(2) | |
| Synchronism and Voltage Check | 25 | RSYN | ○(1) | ○(2) | ○(1) | ○(2) | (e) |
| Circuit Breaker Close Lock / Lockout | 86 | RCBL | ●(1) | ●(1) | ●(1) | ●(1) | |
| Fuse Failure / VT Supervision | 60 | RVTS | ●(1) | ●(1) | ●(1) | ●(1) | |
| CT Supervision | | RCCS | ●(1) | ●(2) | ●(1) | ●(2) | |
| Open Pole Detection | | ROPD | | | ●(1) | ●(1) | |
| Circuit Breaker Control / Supervision | 52 | CSWI, XCBR | ●(1) | ●(2) | ●(1) | ●(2) | |
| Circuit Breaker Condition Monitoring | | SCBR | ○ | ○ | ○ | ○ | (f) |
| Circuit Switch Control / Supervision | 89 | CSWI, XSWI | ○(10) | ○(10) | ○(10) | ○(10) | (f) |
| Distributed Automation | | GGIO (or user defined) | ● | ● | ● | ● | |
| Programmable Automation (IEC 61131-3) | | GAPC (or user defined) | ● | ● | ● | ● | |
| Monitoring and Recording Functions | | | | | | | |
| | ANSI | IEC 61850 | | | | | |
| Three-Phase Measurements | | MMXU, MSQI | ●(1) | ●(1) | ●(1) | ●(1) | |
| Single-Phase Measurements | | MMXN | ●(3) | ●(3) | ●(3) | ●(3) | |
| Metering | | MMTR | ○(1) | ○(1) | ○(1) | ○(1) | (f) |
| Statistics ** | | MMXU (or user defined) | ○ | ○ | ○ | ○ | (f) |

| | | | | | | | |
|----------------------------------|------|------|------|------|------|------|-----|
| Sags and Swells ** | | QVVR | ○ | ○ | ○ | ○ | (f) |
| Harmonics ** | | MHAI | ○ | ○ | ○ | ○ | (f) |
| Fault Locator | 21FL | RFLO | ●(1) | ●(1) | ●(1) | ●(1) | |
| Disturbance Recorder | | RDRE | ● | ● | ● | ● | |
| Chronological Event Log / SOE | | | ● | ● | ● | ● | |
| Fault Report | | | ● | ● | ● | ● | |
| Load Diagram / Trend Recorder ** | | | ○ | ○ | ○ | ○ | (f) |
| Histogram ** | | | ○ | ○ | ○ | ○ | (f) |
| Power Quality Event Recorder ** | | | ○ | ○ | ○ | ○ | (f) |
| Self-tests and Watchdog | | | ● | ● | ● | ● | |

- - Base feature
- - Optional feature
- - Base mutual-exclusive feature
- ** - Currently under development
- (n) - Maximum number of instances

- Functional restrictions according to order code:
- (a) Line Differential (option D1)
 - (b) Line Differential with In-Zone Transformer (option D2)
 - (c) With Distance or Distance and PSB/OOS (options E2 or E3)
 - (d) With Distance and PSB/OOS (option E3)
 - (e) With Synchronism Check (option F2)
 - (f) Protection and Control (option C2)

TECHNICAL SPECIFICATIONS

| A.C. Analogue Inputs (General Data) | | |
|-------------------------------------|--|--|
| Number | Max. 24 | |
| Rated frequency | $f_r = 50$ or 60 Hz (configurable by user) | |
| Angular reference | Any of the AC analogue inputs (configurable by user) | |
| Acquisition | ADC type | Sigma-Delta |
| | Resolution | 24 bit |
| | Sampling rate | 160 samples per cycle at rated frequency (8 kHz @ $f_r = 50$ Hz; 9.6 kHz @ $f_r = 60$ Hz) |

| A.C. Current Inputs | | |
|---------------------|--|--|
| Number | Max. 24 (depends on the number and type of expansion boards) | |
| Standard option | Rated current | $I_r = 1$ or 5 A (configurable by user) |
| | Operation range | $[0.05 \dots 50.0] \times I_r$ |
| | Thermal withstand | 500 A for 1 s |
| | | 150 A for 10 s |
| | | 20 A continuous |
| | Dynamic load-carrying withstand | 1250 A one half wave |
| Burden | < 0.05 VA @ $I_r = 1$ A < 0.15 VA @ $I_r = 5$ A | |
| Sensitive option | Rated current | $I_r = 1$ or 5 A (configurable by user) |
| | Operation range | $[0.005 \dots 5.0] \times I_r$ |
| | Thermal withstand | 250 A for 1 s |
| | | 10 A continuous |
| | Dynamic load-carrying withstand | 750 A one half wave |
| | Burden | < 0.05 VA @ $I_r = 1$ A < 0.25 VA @ $I_r = 5$ A |

| A.C. Voltage Inputs | | |
|---------------------------------------|--|---|
| Number | Max. 12 (depends on the number and type of expansion boards) | |
| Standard range (configurable by user) | Rated voltage | $U_r = 100/3, 110/3, 115/3$ or $120/3$ V (residual) |
| | | $U_r = 100/\sqrt{3}, 110/\sqrt{3}, 115/\sqrt{3}$ or $120/\sqrt{3}$ V (phase-earth) |
| | | $U_r = 100, 110, 115$ or 120 V (phase-phase) |
| | Operation range | $[0.25 \dots 220] V_{rms}$ |
| | Thermal withstand | 500 V for 1 s 460 V continuous |
| Burden | < 0.05 VA @ U_r | |
| Extended range (configurable by user) | Rated voltage | $U_r = 100/\sqrt{3}, 110/\sqrt{3}, 115/\sqrt{3}$ or $120/\sqrt{3}$ V (residual) |
| | | $U_r = 100, 110, 115, 120$ V or 230 V (phase-earth) |
| | | $U_r = 100 \times \sqrt{3}, 110 \times \sqrt{3}, 115 \times \sqrt{3}, 120 \times \sqrt{3}$ V or 400 V (phase-phase) |
| | Operation range | $[0.5 \dots 440] V_{rms}$ |
| | Thermal withstand | 500 V for 1 s 460 V continuous |
| Burden | < 0.25 VA @ U_r | |

| D.C. Analogue Inputs | | |
|----------------------|---|--|
| Number | Max. 32 | |
| Current ranges | Operation ranges (configurable by user) | $\pm 1 \text{ mA}; \pm 5 \text{ mA}; \pm 10 \text{ mA}; \pm 20 \text{ mA};$ $0 \dots 1 \text{ mA}; 0 \dots 5 \text{ mA}; 0 \dots 10 \text{ mA}; 0 \dots 20 \text{ mA}; 4 \dots 20 \text{ mA}$ |
| | Thermal withstand | 0.1 A continuous 0.5 A for 1 s |
| | Input impedance | 50 Ω |
| Low voltage ranges | Operation ranges (configurable by user) | $\pm 5 \text{ V}; \pm 10 \text{ V}$ |
| | Thermal withstand | 20 V continuous 50 V for 1 s |
| | Input impedance | 45 k Ω |
| High voltage ranges | Operation ranges (configurable by user) | $\pm 150 \text{ V}; \pm 300 \text{ V}$ |
| | Thermal withstand | 360 V continuous 420 V for 1 s |
| | Input impedance | 1.3 M Ω |
| Acquisition | ADC type | Sigma-Delta, auto-ranging with PGA |
| | Resolution | 16 bit + sign |
| | Accuracy | < 0.2 % full-range |
| | Normal-mode rejection ratio | > 110 dB |
| | Common-mode rejection ratio | > 130 dB |
| | Scan cycle | 100 ms |

| Power Supply | | |
|---------------------------------------|--|---------------------------------------|
| Rated values / voltage ranges | 24 / 48 / 60 V d.c. | (19 .. 72 V d.c.) |
| | 110 / 125 / 220 / 250 V d.c. 115 / 230 V a.c. | (88 .. 350 V d.c. / 80 .. 265 V a.c.) |
| | 48 / 60 / 110 / 125 V d.c. | (38 .. 150 V d.c.) |
| | | |
| Burden | Quiescent state (maximum configuration) | < 50 W (d.c.) < 80 VA (a.c.) |
| | Additional burden per actuated binary output | 0.3 W |
| Ripple at d.c. auxiliary power supply | | $\leq 12\%$ |
| Earthing arrangements for d.c. supply | Floating (free from earth) | Class EF |

| Binary Inputs | | |
|---|------------------------|---|
| Number | Base | 8 |
| | Maximum | 264 |
| Rated values / voltage thresholds (configurable by user) | 24 V d.c. | $V_{LOW} \leq 8 \text{ V d.c.}$ $V_{HIGH} \geq 20 \text{ V d.c.}$ |
| | 48 / 60 V d.c. | $V_{LOW} \leq 26 \text{ V d.c.}$ $V_{HIGH} \geq 38 \text{ V d.c.}$ |
| | 110 / 125 V d.c. | $V_{LOW} \leq 66 \text{ V d.c.}$ $V_{HIGH} \geq 85 \text{ V d.c.}$ |
| | 220 / 250 V d.c. | $V_{LOW} \leq 132 \text{ V d.c.}$ $V_{HIGH} \geq 170 \text{ V d.c.}$ |
| Maximum permitted voltage | | 300 V d.c. |
| Burden | 24 V d.c. | < 0.05 W (1.5 mA @ 24 V d.c.) |
| | 48 / 60 V d.c. | < 0.1 W (1.5 mA @ 48 V d.c.) |
| | 110 / 125 V d.c. | < 0.2 W (1.5 mA @ 125 V d.c.) |
| | 220 / 250 V d.c. | < 0.4 W (1.5 mA @ 250 V d.c.) |
| Inrush current | Peak | 50 mA \pm 20% @ V_r |
| | Impulse time constant | 10 ms \pm 20% |
| | Total impulse duration | Approx. 50 ms |
| Filtering | Debounce time | [1 .. 128] ms |
| | Oscillation filter | Max [2 .. 255] changes in [2 .. 10000] ms |

| Binary Outputs | | | |
|---------------------|--------------------------------------|------------------------------|--|
| Number | Base | 7 + Watchdog | |
| | Maximum | 135 + Watchdog | |
| Standard option | Rated voltage | 250 V a.c./ d.c. | |
| | Rated current | 8 A | |
| | Making capacity | | 1 s @ 10 A 0.2 s @ 30 A |
| | | Breaking capacity | d.c.: 1 / 0.4 / 0.2 A @ 48 / 110 / 220 V; L/R < 40 ms a.c.: 1250 VA (250 V / 5 A); $\cos \varphi > 0,4$ |
| | Voltage across open contacts (1 min) | 1 kV _{rms} | |
| High-speed option | Rated voltage | 250 V a.c./ d.c. | |
| | Rated current | 8 A | |
| | Making capacity | | 2 s @ 10 A 0.5 s @ 30 A |
| | | Breaking capacity | d.c.: 10 A; L/R < 40 ms |
| | Operating time | < 50 μ s; resistive load | |
| Pulse configuration | Pulse time | [0 .. 60000] ms | |
| | Delay time | [0 .. 60000] ms | |
| | Reset time | [0 .. 60000] ms | |

| Serial Ports - System Interface | | |
|---------------------------------|--|---|
| Number | Max. 3 (RS-232/RS-485, Plastic FO or Glass FO) | |
| Transmission rate | Setting range | 600 to 57600 baud |
| RS-232 option | Connector | D9 male connector |
| RS-485 option | Connector | D9 male connector |
| Plastic fibre optics option | Fibre type | Plastic fibre optics (POF) 1mm |
| | Wavelength | 650 nm |
| | Connector | Snap-in type |
| | Maximum distance | 45 m |
| | Optical power budget with 1 mm POF | 10.4 dB (min.) |
| Glass fibre optics option | Fibre type | Multimode glass fibre optics 50/125 µm or 62.5/125 µm |
| | Wavelength | 820 nm |
| | Connector | ST |
| | Maximum distance | 1.7 km using an optical fibre 62.5/125 µm |
| | Optical power budget with 50/125 µm fibre | 4.2 dB (min.) |
| | Optical power budget with 62.5/125 µm fibre | 8.0 dB (min.) |

| Clock Synchronization Ports - IRIG-B Interface | | |
|--|---|---|
| Number | 1 (Galvanic or Glass FO) | |
| Galvanic option | Connector | D9 female connector |
| | Input voltage level | 5 V, 12 V or 24 V |
| | Voltage range | ± 20% of input voltage level |
| Glass fibre optics option | Fibre type | Multimode glass fibre optics 50/125 µm or 62.5/125 µm |
| | Wavelength | 820 nm |
| | Connector | ST |
| | Maximum distance | 1.7 km using an optical fibre 62.5/125 µm |
| | Optical power budget with 50/125 µm fibre | 4.2 dB (min.) |
| | Optical power budget with 62.5/125 µm fibre | 8.0 dB (min.) |

| Rear Ethernet Ports - System Interface | | |
|--|---|---|
| Number | Dual-interface (10/100BASE-TX or 100BASE-FX) + Single-interface (10/100BASE-TX or 100BASE-FX) | |
| Copper interface option | Media type | 10/100BASE-TX |
| | Connector | RJ-45 |
| Fibre interface option (100 Mbps) | Media type | 100BASE-FX |
| | Fibre type | Multimode glass fibre optics 50/125 µm or 62.5/125 µm |
| | Wavelength | 1300 nm |
| | Connector | LC Duplex |
| | Maximum distance | 2 km |
| | Output optical power (62.5/125 µm, NA = 0.275) | -20.0 dBm ... -14.0 dBm |
| | Output optical power (50/125 µm, NA = 0.20) | -23.5 dBm ... -14.0 dBm |
| | Receiver sensitivity | -31.0 dBm (max.) |
| | Receiver overload | -14.0 dBm (min.) |

| Front Ethernet Port - Service Interface | | |
|---|------------|---------------|
| Copper interface | Media type | 10/100BASE-TX |
| | Connector | RJ-45 |

| Remote End Communication Ports | | |
|--|--|---|
| Communication interface | Number of channels | Up to 4 |
| | Protocol | IEEE C37.94 |
| | Supported applications | Peer-to-peer fibre optics link / G.703 (64 kbit/s) or G.703 E1 (2 Mbit/s) with external multiplexer |
| | Transmission rate | 64 kbit/s to 2 Mbit/s (max. data rate 768 kbit/s) |
| Multi-mode fibre optics option, maximum distance 2 km | Fibre type | Multi-mode glass fibre optics 50/125 µm or 62.5/125 µm |
| | Wavelength | 800 nm |
| | Connector | ST |
| | Maximum distance | 2 km |
| Single-mode fibre optics option, maximum distance 40 km | Fibre type | Single-mode glass fibre optics 9/125 µm |
| | Wavelength | 1310 nm |
| | Connector | LC Duplex |
| | Operation range | 0 to 40 km |
| | Transmitter power coupled in optical fibre | -5.0 dBm ... 0 dBm |
| | Receiver sensitivity | -34.0 dBm (max.) |
| | Receiver overload | 0 dBm (min.) |
| | Optical power budget | 29 dB |
| Single-mode fibre optics option, maximum distance 60 km | Fibre type | Single-mode glass fibre optics 9/125 µm |
| | Wavelength | 1310 nm |
| | Connector | LC Duplex |
| | Operation range | 30 to 60 km |
| | Transmitter power coupled in optical fibre | -5.0 dBm ... 0 dBm |
| | Receiver sensitivity | -35.0 dBm (max.) |
| | Receiver overload | 0 dBm (min.) |
| | Optical power budget | 30 dB |
| Single-mode fibre optics option, maximum distance 100 km | Fibre type | Single-mode glass fibre optics 9/125 µm |
| | Wavelength | 1511 nm |
| | Connector | LC Duplex |
| | Operation range | 50 to 100 km |
| | Transmitter power coupled in optical fibre | 0 dBm ... +5.0 dBm |
| | Receiver sensitivity | -34.0 dBm (max.) |
| | Receiver overload | -8.0 dBm (min.) |
| | Optical power budget | 34 dB |

| Case | | |
|--------|------------|------------------|
| Design | Dimensions | 6U, 1 x 19" rack |
| | Weight | < 13 kg |

| Environmental Conditions | |
|-----------------------------|---|
| Operating temperature range | - 10 °C to + 60 °C, temporarily can be up to 70 °C (tested for 72 hours); Recommended: - 5 °C to + 55 °C |
| Storage temperature range | - 25 °C to + 70 °C |
| Relative humidity | 10 to 95% |
| Pollution degree | 2 |
| Altitude | < 2000 m |

| CE Marking | | |
|--|----------|---|
| Electromagnetic Compatibility Directive (2004/108/CE) | Immunity | EN 61000-6-2: 2005 EN 60870-2-1: 1996 EN 60255-26: 2009 EN 50263: 1999 |
| | Emission | EN 61000-6-4: 2007 + A1: 2011 EN 60870-2-1: 1996 EN 60255-26: 2009 EN 50263: 1999 |
| Low Voltage Directive (2006/95/CE) | | EN 60950-1: 2006 + A1: 2010 + A11: 2009 + A12: 2011 EN 60255-27: 2005 EN 60255-5: 2001 |

| Insulation Tests | | |
|------------------------------------|---------------------------|----------------------------------|
| High voltage test | EN 60255-5 | 2.0 kV a.c. 1 min 50 Hz |
| | EN 60255-27 | 2.8 kV d.c. 1 min (power supply) |
| Impulse voltage test | EN 60255-5 EN 60255-27 | 5 kV 1.2/50 μ s, 0.5 J |
| Insulation resistance test | EN 60255-5 EN 60255-27 | > 100 M Ω @ 500 V d.c. |
| Protective bonding resistance test | EN 60255-27 | < 0.1 Ω |

| EMC – Immunity Tests | | |
|--|--------------------------------|---|
| Electrostatic discharge immunity test | EN 61000-4-2 EN 60255-22-2 | 8 kV contact; 15 kV air |
| Electromagnetic field immunity test | EN 61000-4-3 EN 60255-22-3 | 80 MHz – 1000 MHz; 30 V/m 1000 MHz – 3000 MHz; 10 V/m |
| Fast transient disturbance immunity test | EN 61000-4-4 EN 60255-22-4 | 4 kV, 5/50 ns |
| Surge immunity test | EN 61000-4-5 EN 60255-22-5 | 4/2 kV, 1.2/50 μ s |
| Conducted RF disturbance test | EN 61000-4-6 EN 60255-22-6 | 10 V r.m.s., 150 kHz – 80 MHz @ 1 kHz 80% am |
| Power frequency magnetic field immunity test | EN 61000-4-8 | 100 A/m, cont; 1000 A/m, 3 s |
| Damped oscillatory magnetic field immunity test | EN 61000-4-10 | 100 A/m, 0.1 MHz and 1 MHz |
| Voltage variations immunity test | EN 61000-4-11 EN 60255-11 | 500 ms @ 70%; 200 ms @ 40% 500 ms @ 40%; |
| | EN 61000-4-29 EN 60255-11 | 500 ms @ 70%; 200 ms @ 40% 500 ms @ 40%; |
| Voltage interruptions immunity test | EN 61000-4-11 EN 60255-11 | 5, 10, 20, 50, 100, 200 and 500 ms |
| | EN 61000-4-29 EN 60255-11 | 5, 10, 20, 50, 100, 200 and 500 ms |
| Ring waves immunity test | EN 61000-4-12 | 4 kV common mode |
| Conducted, common mode disturbances in the frequency range 0 Hz to 150 kHz | EN 1000-4-16 EN 60255-22-7 | 150 V (differential mode) 100 Ω , 0.1 μ F 300 V (common mode) 220 Ω , 0.47 μ F |
| Damped oscillatory waves immunity test | EN 61000-4-18 EN 60255-22-1 | 2.5 kV common mode 1 kV differential mode |

| EMC – Emission Tests | | |
|---|-------------------------|-----------------------|
| Radiated emission | EN 55022 EN 60255-25 | 30 – 1000 MHz class A |
| Conducted emission | EN 55022 EN 60255-25 | 0.15 – 30 MHz class A |
| Harmonic currents emission test | EN 61000-3-2 | Class A |
| Voltage fluctuation and flicker emission test | EN 61000-3-3 | Class A |

| Mechanical Tests | | |
|---|---------------|-------------------------------|
| Vibration tests | EN 60255-21-1 | Class 2, 2 g, 10 Hz to 150 Hz |
| | EN 60870-2-2 | Class Cm, 2 g, 9 Hz to 200 Hz |
| Shock tests | EN 60255-21-2 | Class 2, 30 g, 11ms |
| | EN 60870-2-2 | Class Cm, 30 g, 11 ms |
| Bump tests | EN 60255-21-2 | Class 1, 10 g, 16ms |
| Free fall test | EN 60870-2-2 | Class Cm, 0.25 m |
| | EN 60068-2-31 | Method 1, 0.25 m |
| Degrees of protection provided by enclosures for electrical equipment against external mechanical impacts (IK code) | EN 50102 | IK07 |

| Environmental Tests | | | |
|--|---------------|-------------|--|
| Cold test | EN 60068-2-1 | Operational | - 10 °C, 72h (Test Ad) |
| | | Storage | - 25 °C, 72h (Test Ab) |
| Dry heat test | EN 60068-2-2 | Operational | + 70 °C, 72h (Test Bd) |
| | | Storage | + 85 °C, 72h (Test Bb) |
| Damp heat test, cyclic (12h+12h cycle) | EN 60068-2-30 | | + 25 °C (97%) to + 40 °C (93%), 6 cycles |
| Damp heat test, steady state | EN 60068-2-78 | | + 40 °C, 93% RH, 10 days |
| Degree of protection frontal side, flush mounted | EN 60529 | | IP50 |
| Degree of protection, rear side | EN 60529 | | IP30 |

FUNCTIONAL SPECIFICATIONS

| Line Differential | | |
|---------------------------------|--|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 2 stages |
| Line characteristics | Number of line ends | Maximum 5 |
| | In-zone transformer | Optional (maximum 2) |
| Unrestrained stage | Setting range | $[0.1 \dots 40.0] \times I_r$; step 0.01 |
| | Accuracy | $\pm 5\% I_{op}$ (minimum $\pm 5\% I_r$) |
| | Dropout ratio | > 96% |
| | Pickup time | 10 ms min. < 15 ms typ. for $I > 2 \times I_{op}$ |
| | Reset time | 40 ms typ. |
| Restrained stage | Minimum operate current | $[0.1 \dots 20.0] \times I_r$; step 0.01 |
| | Raised operate current | $[0.1 \dots 20.0] \times I_r$; step 0.01 |
| | Slope (section 2) | $[0.1 \dots 1.0] I_{diff}/I_{bias}$; step 0.01 |
| | Slope (section 3) | $[0.3 \dots 1.0] I_{diff}/I_{bias}$; step 0.01 |
| | Slope switch current | $[1.0 \dots 20.0] \times I_r$; step 0.01 |
| | Accuracy | $\pm 3\% I_{op}$ (minimum $\pm 3\% I_r$) |
| | Dropout ratio | > 96% |
| | Pickup time | 20 ms min. < 25 ms typ. for $I > 2 \times I_{op}$ < 35 ms typ. for $I > 2 \times I_{op}$ and in-zone transformer |
| | Time delay | $[0 \dots 60000]$ ms; step 1 |
| | Maximum time with raised operate current | $[0 \dots 60000]$ ms; step 1 |
| | Time accuracy | $\pm 3\%$ (minimum ± 10 ms) |
| | Reset time | 40 ms typ. |
| Inrush blocking | Restriction mode | Second harmonic |
| | Second harmonic ratio | $[0.1 \dots 1.0] I_{2h}/I_{1h}$; step 0.01 |
| | Cross-block | One phase out of three, two phases out of three or disabled |
| | Cross-block maximum time | $[0 \dots 15000]$ ms; step 1 |
| Overexcitation blocking | Restriction mode | Fifth harmonic |
| | Fifth harmonic ratio | $[0.1 \dots 1.0] I_{5h}/I_{1h}$; step 0.01 |
| | Cross-block | One phase out of three, two phases out of three or disabled |

| Distance | | |
|---------------------------------|---|--|
| Number of independent functions | | 1 function |
| Number of zones (per function) | | 6 zones |
| Measuring zones | Measuring loops per zone | 3 phase-to-phase and 3 phase-to-earth |
| | Phase and fault loop selection | Full-scheme |
| | Phase-to-phase-to-earth faults loop selection | Phase-to-phase loops / all loops |
| | Type of characteristic | Quadrilateral, mho or both (mho for phase-to-phase loops and quadrilateral for phase-to-earth loops) |
| | Zone 6 activation | Enabled by logic (zone extension schemes) |
| Quadrilateral characteristic | Reactance reach | [0.05 .. 500.0] Ω ; step 0.01 |
| | Resistive reach (phase-to-phase loops) | [0.05 .. 500.0] Ω ; step 0.01 |
| | Resistive reach (phase-to-earth loops) | [0.05 .. 500.0] Ω ; step 0.01 |
| | Reactance reach in the reverse direction (zone 5) | [0.05 .. 500.0] Ω ; step 0.01 |
| | Accuracy | \pm 5% reach |
| | Dropout ratio | > 95% |
| Mho characteristic | Zone reach | [0.05 .. 500.0] Ω ; step 0.01 |
| | Zone offset | [0.05 .. 500.0] Ω ; step 0.01 |
| | Accuracy | \pm 5% reach |
| | Dropout ratio | > 95% |
| Directionality | Direction options | Non-directional, forward or reverse (independent zone selection) |
| | Polarization | Positive-sequence voltage and voltage memory, according to actual fault condition |
| | Minimum angle in forward direction | [-60.0 .. 0.0] $^{\circ}$; step 1.0 |
| | Maximum angle in forward direction | [90.0 .. 150.0] $^{\circ}$; step 1.0 |
| | Additional mho directional element | Optional |
| | Series compensated operation | Optional |
| Load encroachment | Phase-to-phase resistive reach | [0.1 .. 600.0] Ω ; step 0.01 (independent for forward and reverse load flows) |
| | Phase-to-earth resistive reach | [0.1 .. 600.0] Ω ; step 0.01 (independent for forward and reverse load flows) |
| | Load angle | [5.0 .. 45.0] $^{\circ}$; step 1.0 (independent for phase-to-phase and phase-to-earth loops) |
| Definite time (all zones) | Pickup time (zone 1 and 6) | 11 ms typ. for $X < 0.30 X_{zone}$ and line differential protection disabled |
| | | 16 ms typ. for $X < 0.60 X_{zone}$ |
| | | 26 ms typ. for $X < 0.95 X_{zone}$ |
| | Pickup time (zones 2, 3, 4 and 5) | 26 ms typ. for $X < 0.95 X_{zone}$ |
| | Time delay (phase-to-phase loops) | [0 .. 60000] ms ; step 1 |
| | Time delay (phase-to-earth loops) | [0 .. 60000] ms ; step 1 |
| | Simultaneous start of stage timers | Optional |
| | Time accuracy | \pm 3% (minimum \pm 10 ms) |
| Reset time | 25 ms typ. | |
| Line characteristics | Line angle | [30.0 .. 90.0] $^{\circ}$; step 1.0 |
| | Earth compensation factor magnitude (per zone) | [0.0 .. 4.0] ; step 0.01 |
| | Earth compensation factor phase angle (per zone) | [-180.0 .. 180.0] $^{\circ}$; step 1.0 |
| | Parallel line compensation | Optional |
| | Mutual compensation factor magnitude | [0.0 .. 4.0] ; step 0.01 |
| | Mutual compensation factor phase angle | [-180.0 .. 180.0] $^{\circ}$; step 1.0 |
| Minimum current | Phase current | [0.05 .. 1.0] $\times I_r$; step 0.01 |
| | Residual current | [0.05 .. 1.0] $\times I_r$; step 0.01 |

| Power Swing Blocking / Out-Of-Step Tripping | | |
|---|-----------------------|---|
| Number of independent functions | | 1 function |
| Power swing blocking | Measuring principle | Variation of the swing centre voltage |
| | Application | Symmetrical or open pole conditions |
| | Power swing frequency | [0.3 .. 10.0] Hz |
| | Maximum block time | [0 .. 60000] ms ; step 1 |
| | Unblock time | [0 .. 10000] ms ; step 1 |
| Out-of-step tripping | Mode | Trip on-the-way in (TOWI) or Trip on-the-way out (TOWO) |
| | System angle | [30.0 .. 90.0]° ; step 1.0 |
| | TOWI angle | [30.0 .. 180.0]° ; step 1.0 |
| | TOWO angle | [30.0 .. 180.0]° ; step 1.0 |

| Distance Teleprotection Schemes | | |
|---------------------------------|---------------------------------------|--|
| Number of independent functions | | 1 function |
| Communication schemes | Options | PUTT / POTT / DCB |
| | Current reversal logic | Optional |
| | Unblocking logic | Optional (supervision of the guard signal) |
| | Echo and weak infeed trip logic | Off / Echo / Weak infeed trip / Both |
| | Signal transmission prolongation time | [0 .. 10000] ms ; step 1 |
| | Coordination time (for DCB) | [0 .. 10000] ms ; step 1 |
| Current reversal logic | Confirmation time | [20 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| Unblocking logic | Security time | [20 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| | Fail time | [50 .. 60000] ms ; step 1 |
| Echo logic | Confirmation time | [20 .. 10000] ms ; step 1 |
| | Echo duration time | [0 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| Weak infeed trip logic | Principle | Phase undervoltage |
| | Voltage threshold | [0.2 .. 1.0] × U _r ; step 0.01 |
| | Operate time delay | [0 .. 10000] ms ; step 1 |

| Directional Earth-Fault Teleprotection Schemes | | |
|--|---------------------------------------|--|
| Number of independent functions | | 1 function |
| Communication schemes | Options | DC / DCB |
| | Current reversal logic | Optional |
| | Unblocking logic | Optional (supervision of the guard signal) |
| | Echo and weak infeed trip logic | Off / Echo / Weak infeed trip / Both |
| | Signal transmission prolongation time | [0 .. 10000] ms ; step 1 |
| | Coordination time (for DCB) | [0 .. 10000] ms ; step 1 |
| Current reversal logic | Confirmation time | [20 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| Unblocking logic | Security time | [20 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| | Fail time | [50 .. 60000] ms ; step 1 |
| Echo logic | Confirmation time | [20 .. 10000] ms ; step 1 |
| | Echo duration time | [0 .. 10000] ms ; step 1 |
| | Block time | [20 .. 10000] ms ; step 1 |
| Weak infeed trip logic | Principle | Residual overvoltage |
| | Voltage threshold | $[0.05 .. 0.7] \times U_r$; step 0.01 (phase-earth rated voltage) |
| | Operate time delay | [0 .. 10000] ms ; step 1 |

| Remote Tripping | | |
|---------------------------------|---------------------------------------|--------------------------|
| Number of independent functions | | 1 function |
| Operation | Signal transmission prolongation time | [0 .. 10000] ms ; step 1 |
| | Operate time delay | [0 .. 10000] ms ; step 1 |
| | Time accuracy | ± 3% (minimum ± 10 ms) |

| Stub | | |
|---------------------------------|-------------------------|---|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 1 stage |
| Restrained stage | Operation | Independent settings for phase and earth-fault currents |
| | Minimum operate current | $[0.05 .. 10.0] \times I_r$; step 0.01 |
| | Slope (section 2) | $[0.1 .. 1.0] I_{diff}/I_{bias}$; step 0.01 |
| | Accuracy | ± 3% I_{op} (minimum ± 3% I_r) |
| | Dropout ratio | > 96% |
| | Pickup time | 11 ms typ. for $I > 2 \times I_{op}$ |
| | Time delay | [0 .. 60000] ms ; step 1 |
| | Time accuracy | ± 3% (minimum ± 10 ms) |
| | Reset time | 25 ms typ. |

| (Directional) Phase Overcurrent | | |
|--|-------------------------------------|---|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 4 stages |
| Operational current | Setting range | [0.05 .. 40.0] × I _r ; step 0.01 (stages 1 and 2) [0.05 .. 20.0] × I _r ; step 0.01 (stages 3 and 4) |
| | Accuracy | ± 1% I _{op} (minimum ± 1% I _r) |
| | Dropout ratio | > 96% |
| | Maximum cold load pickup multiplier | [1.0 .. 20.0] ; step 0.01 (independent per stage) |
| Definite time (all stages) | Pickup time | 27 ms typ. for I > 2 × I _{op} |
| | Time delay | [0 .. 60000] ms ; step 1 |
| | Time accuracy | ± 3% (minimum ± 20 ms) |
| | Reset type | Instantaneous or delayed |
| | Reset time | 30 ms typ. |
| | Dropout delay | [0 .. 60000] ms ; step 1 |
| Inverse time (stages 3 and 4 only) | Curve types (ANSI/ IEEE) | Extremely Inverse, Very Inverse, Normal Inverse, Moderately Inverse, Long Time Extremely Inverse, Long Time Very Inverse, Long Time Inverse |
| | Curve types (IEC) | Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse |
| | User defined curves | 6 to 25 points |
| | Time multiplier | [0.05 .. 15.0] ; step 0.01 |
| | Constant time adder | [0 .. 30000] ms ; step 1 |
| | Minimum operation time | [0 .. 60000] ms ; step 10 |
| | Maximum operation time | [0 .. 60000] ms ; step 10 |
| | Start value | [1.0 .. 4.0] × I _{op} ; step 0.01 |
| | Accuracy class | ANSI/ IEEE C37.112, Class 5 IEC 60255-3, Class 5 |
| | Reset type | Instantaneous or dynamic |
| | Reset time | 30 ms typ. |
| Directionality | Direction options | Non-directional, forward or reverse (independent stage selection) |
| | Polarization | Negative-sequence voltage, positive-sequence voltage and voltage memory, according to actual fault condition; Cross phase-phase voltage and voltage memory, according to actual fault condition, in option |
| | Characteristic angle | [-90.0 .. 90.0]° ; step 1.0 |
| | Phase angle accuracy | ± 2° |
| | VT failure action | Non-directional trip or function block |
| Inrush restraint | Operation | Disabled / enabled (independent stage selection) |
| | Restriction mode | Second harmonic |
| | Second harmonic ratio | [0.1 .. 1.0] I _{2h} /I _{1h} ; step 0.01 |
| | Cross-block | One phase out of three, two phases out of three or disabled |

| (Directional) Earth-Fault Overcurrent | | |
|--|-------------------------------------|---|
| Number of independent functions | | 2 functions |
| Number of stages (per function) | | 4 stages |
| Operational current | Quantity | Residual current (calculated sum of three phase currents) or neutral current (independent input) |
| | Setting range (normal CT input) | [0.05 .. 40.0] × I _r ; step 0.001 (stages 1 and 2) [0.05 .. 20.0] × I _r ; step 0.001 (stages 3 and 4) |
| | Setting range (sensitive CT input) | [0.005 .. 4.0] × I _r ; step 0.001 |
| | Accuracy | ± 1% I _{op} (minimum ± 1% I _r) |
| | Dropout ratio | > 96% |
| | Maximum cold load pickup multiplier | [1.0 .. 20.0] ; step 0.01 (independent per stage) |
| Definite time (all stages) | Pickup time | 27 ms typ. for I > 2 × I _{op} |
| | Time delay | [0 .. 60000] ms ; step 1 (stages 1 and 2) [0 .. 300000] ms ; step 1 (stages 3 and 4) |
| | Time accuracy | ± 3% (minimum ± 10 ms) |
| | Reset type | Instantaneous or delayed |
| | Reset time | 30 ms typ. |
| | Dropout delay | [0 .. 60000] ms ; step 1 |
| Inverse time (stages 3 and 4 only) | Curve types (ANSI/ IEEE) | Extremely Inverse, Very Inverse, Normal Inverse, Moderately Inverse, Long Time Extremely Inverse, Long Time Very Inverse, Long Time Inverse |
| | Curve types (IEC) | Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse |
| | Curve types (other) | Logarithmic |
| | User defined curves | 6 to 25 points |
| | Time multiplier | [0.05 .. 15.0] ; step 0.01 |
| | Constant time adder | [0 .. 30000] ms ; step 1 |
| | Minimum operation time | [0 .. 60000] ms ; step 10 |
| | Maximum operation time | [0 .. 60000] ms ; step 10 |
| | Start value | [1.0 .. 4.0] × I _{op} ; step 0.01 |
| | Accuracy class | ANSI/ IEEE C37.112, Class 5 IEC 60255-3, Class 5 |
| | Reset type | Instantaneous or dynamic |
| | Reset time | 30 ms typ. |
| | Directionality | Direction options |
| Polarization | | Residual voltage and/or neutral current; negative-sequence voltage/current in option |
| Characteristic angle | | [-90.0 .. 90.0]° ; step 1.0 |
| Minimum polarization voltage | | [0.01 .. 1.0] × U _r ; step 0.005 (phase-earth rated voltage) |
| Minimum polarization current | | [0.05 .. 1.0] × I _r ; step 0.01 |
| Accuracy | | ± 1% U _{pol} (minimum ± 1% U _r) ± 1% I _{pol} (minimum ± 1% I _r) |
| Phase angle accuracy | | ± 2° |
| VT failure action | | Non-directional trip or function block |
| Inrush restraint | Operation | Disabled / enabled (independent stage selection) |
| | Restriction mode | Second harmonic |
| | Second harmonic ratio | [0.1 .. 1.0] I _{2h} /I _{1h} ; step 0.01 |

| (Directional) Negative Sequence Overcurrent | | |
|--|------------------------------|---|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 4 stages |
| Operational current | Setting range | $[0.05 \dots 4.0] \times I_r$; step 0.01 |
| | Accuracy | $\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$) |
| | Dropout ratio | > 96% |
| Definite time (all stages) | Pickup time | 27 ms typ. for $I > 2 \times I_{op}$ |
| | Time delay | $[0 \dots 60000]$ ms; step 1 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset type | Instantaneous or delayed |
| | Reset time | 30 ms typ. |
| | Dropout delay | $[0 \dots 60000]$ ms; step 1 |
| Inverse time (stages 3 and 4 only) | Curve types (ANSI/IEEE) | Extremely Inverse, Very Inverse, Normal Inverse, Moderately Inverse, Long Time Extremely Inverse, Long Time Very Inverse, Long Time Inverse |
| | Curve types (IEC) | Normal Inverse, Very Inverse, Extremely Inverse, Short Time Inverse, Long Time Inverse |
| | User defined curves | 6 to 25 points |
| | Time multiplier | $[0.05 \dots 15.0]$; step 0.01 |
| | Constant time adder | $[0 \dots 30000]$ ms; step 1 |
| | Minimum operation time | $[0 \dots 60000]$ ms; step 10 |
| | Maximum operation time | $[0 \dots 60000]$ ms; step 10 |
| | Start value | $[1.0 \dots 4.0] \times I_{op}$; step 0.01 |
| | Accuracy class | ANSI/IEEE C37.112, Class 5 IEC 60255-3, Class 5 |
| | Reset type | Instantaneous or dynamic |
| | Reset time | 30 ms typ. |
| Directionality | Direction options | Non-directional, forward or reverse (independent stage selection) |
| | Polarization | Negative-sequence voltage |
| | Characteristic angle | $[-90.0 \dots 90.0]^\circ$; step 1.0 |
| | Minimum polarization voltage | $[0.01 \dots 1.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{pol}$ (minimum $\pm 1\% U_r$) |
| | Phase angle accuracy | $\pm 2^\circ$ |
| | VT failure action | Non-directional trip or function block |

| Thermal Overload | | |
|---------------------------------|----------------------------|---|
| Number of independent functions | | 1 function |
| Thermal characteristics | Time constant | $[1 \dots 60000]$ s; step 1 |
| | Maximum continuous current | $[0.0 \dots 999999.9]$ A; step 0.1 |
| | Maximum temperature rise | $[0.0 \dots 250.0]$ °C; step 1.0 |
| | Environment temperature | $[-50.0 \dots 200.0]$ °C; step 1.0 |
| Operate levels | Curve types | IEC 60255-8 |
| | Initial temperature option | Environment or steady-state temperature |
| | Alarm temperature level | $[0.0 \dots 250.0]$ °C; step 1.0 |
| | Trip temperature level | $[0.0 \dots 250.0]$ °C; step 1.0 |
| | Reclose temperature level | $[0.0 \dots 250.0]$ °C; step 1.0 |
| | Accuracy class | Class 5 |

| Switch-Onto-Fault | | |
|---------------------------------|---|---|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 1 independent overcurrent stage; association with other protection function stages via trip logic |
| Operational current | Setting range | $[0.5 \dots 40.0] \times I_r$; step 0.01 |
| | Accuracy | $\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$) |
| | Dropout ratio | > 96% |
| Instantaneous time | Pickup time | 11 ms typ. for $I > 2 \times I_{op}$ |
| | Reset time | 30 ms typ. |
| Activation | Origin | External order (CB close command) or dead line detection |
| | Maximum activation time (after CB closed) | [40 .. 60000] ms ; step 10 |
| Dead line detection | Maximum dead current | $[0.05 \dots 1.5] \times I_r$; step 0.01 |
| | Maximum dead voltage | $[0.05 \dots 0.8] \times U_r$; step 0.01 |
| | Confirmation time | [40 .. 10000] ms ; step 10 |

| Broken Conductor Check / Phase Unbalance | | | |
|---|---|---|-----------------------------------|
| Number of independent functions | | 1 function | |
| Detection | Principle | Negative-sequence current / positive-sequence current ratio | |
| | Ratio I_2/I_1 | [0.2 .. 1.0] ; step 0.01 | |
| | Minimum operating negative-sequence current | 2.5% I_r | |
| | Accuracy | 2% $(I_2/I_1)_{op}$ | |
| | Dropout ratio | | > 97% ($I_2 > 0.05 \times I_r$) |
| | | | > 94% ($I_2 < 0.05 \times I_r$) |
| Minimum phase current | | $[0.05 \dots 0.3] \times I_r$; step 0.01 | |
| Operation time | Alarm delay | [100 .. 60000] ms ; step 1 | |
| | Reset delay | [0 .. 60000] ms ; step 1 | |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) | |

| Directional Earth-Fault Overcurrent for Non-Earthed Systems | | |
|--|------------------------------------|---|
| Number of independent functions | | 2 functions |
| Principle | Operation quantities | Residual (or neutral) voltage; Residual (or neutral) voltage and residual (or neutral) current |
| Operational voltage | Setting range | $[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage) |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout ratio | > 96% |
| Operational current | Quantity | Residual (or neutral) current |
| | Setting range (normal CT input) | $[0.05 \dots 1.0] \times I_r$; step 0.001 |
| | Setting range (sensitive CT input) | $[0.005 \dots 1.0] \times I_r$; step 0.001 |
| | Accuracy | $\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$) |
| | Dropout ratio | > 96% |
| Definite time | Pickup time | 27 ms typ. |
| | Pickup time delay | $[0 \dots 300000]$ ms; step 1 |
| | Operation time delay | $[0 \dots 300000]$ ms; step 1 |
| | Time accuracy | $\pm 3\%$ (minimum ± 10 ms) |
| | Reset time | 35 ms typ. |
| Directionality | Direction options | Non-directional, forward or reverse |
| | Polarization | Residual voltage |
| | Measuring principle | Wattmetric (minimum power) or current phase angle (minimum current magnitude) |
| | Characteristic angle | $[0.0 \dots 90.0]^\circ$; step 1.0 |
| | Open angle | $[10.0 \dots 90.0]^\circ$; step 1.0 |
| | Phase angle accuracy | $\pm 2^\circ$ |
| Alarm | Principle | Voltage unbalance |
| | Minimum voltage | $[0.1 \dots 2.0] \times U_r$; step 0.01 |
| | Maximum voltage | $[0.1 \dots 2.0] \times U_r$; step 0.01 |

| Directional Power | | |
|---------------------------------|----------------------|---|
| Number of independent functions | | 1 function |
| Number of stages (per function) | Overpower stages | 2 stages |
| | Underpower stages | 2 stages |
| Overpower stages | Operational power | $[0.001 \dots 1000.0]$ MVA; step 0.001 |
| | Accuracy | $\pm 3\% S_{op}$ (minimum $\pm 1\% S_r$) |
| | Dropout ratio | $[0.80 \dots 0.96] \times S_{op}$; step 0.01 |
| | Characteristic angle | $[0.0 \dots 360.0]^\circ$; step 1.0 |
| Underpower stages | Operational power | $[0.001 \dots 1000.0]$ MVA; step 0.001 |
| | Accuracy | $\pm 3\% S_{op}$ (minimum $\pm 1\% S_r$) |
| | Dropout ratio | $[1.04 \dots 1.20] \times S_{op}$; step 0.01 |
| | Characteristic angle | $[0.0 \dots 360.0]^\circ$; step 1.0 |
| Definite time (all stages) | Pickup time | 30 ms typ. for $I > 2 \times I_{op}$ |
| | Time delay | $[0 \dots 60000]$ ms; step 1 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | 35 ms typ. |
| | Dropout delay | $[0 \dots 60000]$ ms; step 1 |

| Phase Undervoltage | | |
|---------------------------------|-----------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 2 stages |
| Operational voltage | Quantity | Phase-phase or phase-earth voltages, in option |
| | Setting range | $[0.01 \dots 2.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout ratio | < 104% |
| Definite time (all stages) | Pickup time | 30 ms typ. |
| | Time delay | $[0 \dots 300000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | 35 ms typ. |
| Inverse time (stage 2 only) | Time multiplier | $[0.05 \dots 15.0]$; step 0.01 |
| | Accuracy class | Class 5 |
| | Reset type | Instantaneous |

| Phase Overvoltage | | |
|---------------------------------|-----------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 2 stages |
| Operational voltage | Quantity | Phase-phase or phase-earth voltages, in option |
| | Setting range | $[0.01 \dots 2.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout ratio | > 96% |
| Definite time (all stages) | Pickup time | 30 ms typ. |
| | Time delay | $[0 \dots 300000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | 35 ms typ. |
| Inverse time (stage 2 only) | Time multiplier | $[0.05 \dots 15.0]$; step 0.01 |
| | Accuracy class | Class 5 |
| | Reset type | Instantaneous |

| Residual Overvoltage | | |
|---------------------------------|-----------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 2 stages |
| Operational voltage | Quantity | Residual voltage (calculated or open-delta VT) or neutral voltage |
| | Setting range | $[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage) |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout ratio | > 96% |
| Definite time (all stages) | Pickup time | 30 ms typ. |
| | Time delay | $[0 \dots 300000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | 35 ms typ. |
| Inverse time (stage 2 only) | Time multiplier | $[0.05 \dots 15.0]$; step 0.01 |
| | Accuracy class | Class 5 |
| | Reset type | Instantaneous |

| Negative Sequence Overvoltage | | |
|---------------------------------|-----------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 2 stages |
| Operational voltage | Quantity | Negative sequence voltage |
| | Setting range | $[0.01 \dots 3.0] \times U_r$; step 0.005 (phase-earth rated voltage) |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout ratio | > 96% |
| Definite time (all stages) | Pickup time | 30 ms typ. |
| | Time delay | $[0 \dots 300000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | 35 ms typ. |
| Inverse time (stage 2 only) | Time multiplier | $[0.05 \dots 15.0]$; step 0.01 |
| | Accuracy class | Class 5 |
| | Reset type | Instantaneous |

| Underfrequency | | |
|---------------------------------|----------------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 5 stages |
| Operational frequency | Quantity | Phase-phase or phase-earth voltages |
| | Setting range | $[0.8 \dots 1.2] \times f_r$; step 0.0001 |
| | Accuracy | ± 10 mHz |
| | Dropout differential | < 20 mHz |
| Definite time (all stages) | Pickup time | 70 ms typ. |
| | Time delay | $[0 \dots 120000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | < 100 ms |
| Block voltage | Setting range | $[0.15 \dots 1.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |

| Overfrequency | | |
|---------------------------------|----------------------|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 5 stages |
| Operational frequency | Quantity | Phase-phase or phase-earth voltages |
| | Setting range | $[0.8 \dots 1.2] \times f_r$; step 0.0001 |
| | Accuracy | ± 10 mHz |
| | Dropout differential | < 20 mHz |
| Definite time (all stages) | Pickup time | 70 ms typ. |
| | Time delay | $[0 \dots 120000]$ ms; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | < 100 ms |
| Block voltage | Setting range | $[0.15 \dots 1.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |

| Frequency Rate-of-Change | | |
|----------------------------------|---|--|
| Number of independent functions | | 1 function |
| Number of stages (per function) | | 5 stages |
| Rate-of-change of frequency | Quantity | Phase-phase or phase-earth voltages |
| | Setting range | $[-10.0 \dots -0.1] \cup [0.1 \dots 10.0]$ Hz/s; step 0.05 |
| | Accuracy | ± 0.1 Hz/s |
| | Dropout differential | < 0.1 Hz/s |
| Definite time (all stages) | Pickup time | 100 ms typ. for $ df/dt > 2 \times df/dt_{op}$ |
| | Observation time interval for average calculation | [10 .. 50] cycles ; step 1 |
| | Time delay | [0 .. 120000] ms ; step 10 |
| | Time accuracy | $\pm 3\%$ (minimum ± 20 ms) |
| | Reset time | < 100 ms |
| Frequency supervision (optional) | Setting range | $[0.8 \dots 1.2] \times f_r$; step 0.0001 |
| | Accuracy | ± 10 mHz |
| Block voltage | Setting range | $[0.15 \dots 1.0] \times U_r$; step 0.005 |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |

| Trip Logic | | |
|---------------------------------|-------------------------------|--|
| Number of independent functions | | 1 function |
| Operation | Number of circuit breakers | 1 or 2 |
| | Trip mode | Only three-phase or three-phase / single-phase |
| | Switch-onto-fault interaction | Instantaneous trip with SOTF active (for selected protection relay stages) |
| | Additional outputs | General and per-phase protection pickup and trip |

| Trip Circuit Supervision | | |
|---------------------------------|-------------------------------|---------------------|
| Number of independent functions | | 6 functions |
| Supervision | Number of supervised circuits | 2 (main and backup) |
| | Alarm delay | [500 .. 60000] ms |
| | Reset time | [500 .. 60000] ms |

| Circuit Breaker Failure | | |
|---------------------------------|--------------------------|---|
| Number of independent functions | | 2 functions |
| Number of stages | | 1 or 2 (only external trip / re-trip and external trip) |
| Operation principles | | Current and / or circuit breaker status supervision |
| Operational current | Start range | $[0.05 \dots 20.0] \times I_r$ |
| | Operational range | $[0.05 \dots 1.5] \times I_r$ |
| | Accuracy | $\pm 1\% I_{op}$ (minimum $\pm 1\% I_r$) |
| Operation time | Re-trip time delay | [0 .. 30000] ms |
| | External trip time delay | [50 .. 30000] ms |
| | Time accuracy | $\pm 3\%$ (minimum ± 10 ms) |
| | Reset time | 15 ms typ. |

| Automatic Reclosing | | |
|---------------------------------|--|--|
| Number of independent functions | | 2 functions |
| Number of reclose shots | | Maximum 5 shots |
| Operation | Operation modes | Defined times / dead line check / live line check / wait for master |
| | Trip mode | Three-phase / single-phase / both (independent per cycle) |
| | Dead time configuration | Three-phase trip, single-phase trip and evolving fault (independent per cycle) |
| | Dead time | [100 .. 180000] ms |
| | Reclaim time | [100 .. 300000] ms |
| Dead / live voltage check | Maximum dead voltage | $[0.05 .. 0.8] \times U_r$ |
| | Minimum live voltage | $[0.2 .. 1.2] \times U_r$ |
| | Minimum time for voltage evaluation | [100 .. 60000] ms |
| Block conditions | Maximum CB open time | [10 .. 1000] ms |
| | Maximum CB close time | [10 .. 1000] ms |
| | Maximum wait time for protection trip | [10 .. 300000] ms |
| | Synchronism check | Disabled / enabled |
| | Maximum wait time for synchronism | [0 .. 60000] ms |
| | Maximum dead time (three-phase trip) | [500 .. 3000000] ms |
| | Maximum dead time (single-phase trip) | [500 .. 3000000] ms |
| | CB ready for OFO evaluation | Disabled / before start of auto-reclose sequence / before close command / before start of auto-reclose sequence and before close command |
| | Block time after successful reclose sequence | [0 .. 300000] ms |
| | Block time after manual close command | [0 .. 300000] ms |
| Evolving fault | Disabled / enabled | |

| Synchronism and Voltage Check | | |
|---------------------------------|---------------------------------|---|
| Number of independent functions | | 2 functions |
| Operation | Operating modes | U ₁ dead / U ₂ dead U ₁ live / U ₂ dead U ₁ dead / U ₂ live U ₁ live / U ₂ live (synchronous) U ₁ live / U ₂ live (asynchronous) Unconditional release |
| | Command origin | Independent settings for manual and automatic CB close commands |
| Voltage check | Quantity | Phase-phase or phase-earth voltages |
| | Maximum dead voltage | $[0.05 \dots 0.8] \times U_r$ |
| | Minimum live voltage | $[0.2 \dots 1.2] \times U_r$ |
| | Maximum voltage | $[0.5 \dots 1.5] \times U_r$ |
| | Accuracy | $\pm 1\% U_{op}$ (minimum $\pm 1\% U_r$) |
| | Dropout differential | $< 2\% U_r$ |
| Frequency check | Permitted operating range | $f_r \pm 3 \text{ Hz}$ |
| Magnitude difference | Setting range | $[0.01 \dots 0.5] \times U_r$ |
| | Accuracy | $\pm 1\% U_r$ |
| Phase angle difference | Setting range | $[2.0 \dots 80.0]^\circ$ |
| | Accuracy | $\pm 2^\circ$ |
| Frequency difference | Setting range | $[0.01 \dots 1.0] \text{ Hz}$ |
| | Accuracy | $\pm 10 \text{ mHz}$ |
| Asynchronous operation | Maximum frequency difference | $[0.02 \dots 2.0] \text{ Hz}$ |
| | CB close time | $[10 \dots 500] \text{ ms}$ |
| Confirmation time | Minimum measuring time | 70 ms |
| | Time delay | $[0 \dots 60000] \text{ ms}$ |
| | Time accuracy | $\pm 3\%$ (minimum $\pm 10 \text{ ms}$) |
| Measurements | Magnitude difference accuracy | $1\% U_r$ |
| | Phase angle difference accuracy | 2° |
| | Frequency difference accuracy | 20 mHz |

| Circuit Breaker Close Lock / Lockout | | |
|--------------------------------------|---------------------------------|--|
| Number of independent functions | | 1 function |
| Lock | Mode | Latched (resettable by user); unlatched; timed |
| | Reset time (for unlatched lock) | $[0 \dots 3600] \text{ s}$ |
| | Lock time (for timed lock) | $[1 \dots 3600] \text{ s}$ |

| Fuse Failure / VT Supervision | | |
|--------------------------------------|-------------------------------------|---|
| Number of independent functions | | 1 function |
| Operation principles | | MCB status supervision; analogue signal validation (asymmetrical / symmetrical failures) |
| Asymmetrical failure detection | Principle | Voltage and current unbalance (residual and negative-sequence components) |
| | Residual voltage threshold | $[0.01 \dots 1.0] \times U_r$ (phase-earth rated voltage) |
| | Residual current threshold | $[0.05 \dots 1.0] \times I_r$ |
| | Negative-sequence voltage threshold | $[0.01 \dots 1.0] \times U_r$ (phase-earth rated voltage) |
| | Negative-sequence current threshold | $[0.05 \dots 1.0] \times I_r$ |
| | Operation time | 16 ms typ. if line differential protection enabled 11 ms typ. if line differential protection disabled |
| | Latch time | [1000 .. 20000] ms |
| Symmetrical failure detection | Principle | Three-phase undervoltage and current variation |
| | Voltage threshold | $[0.01 \dots 1.0] \times U_r$ |
| | Current variation | $[0.1 \dots 1.0] \times I_r$ |
| | Operation time | 16 ms typ. if line differential protection enabled 11 ms typ. if line differential protection disabled |
| Voltage measurement evaluation | Alarms | Voltage absence check; polarity and sequence check |
| | Evaluation time | [1000 .. 60000] ms |
| Minimum current | Setting range | $[0.05 \dots 1.0] \times I_r$ |

| CT Supervision | | |
|--|--------------------------------------|--|
| Number of independent functions | | 2 functions |
| Operation principles | | Analogue signal validation (asymmetrical / symmetrical failures) |
| Asymmetrical failure detection | Principle | Comparison with reference current and/or voltage |
| | Residual current threshold | $[0.05 \dots 4.0] \times I_r$ |
| | Reference residual current threshold | $[0.05 \dots 4.0] \times I_r$ |
| | Reference residual voltage threshold | $[0.01 \dots 1.0] \times U_r$ |
| | Operation time | 11 ms typ. |
| Symmetrical failure detection | Principle | Three-phase current drop and variation of reference current and/or voltage |
| | Pre-fault current threshold | $[0.1 \dots 1.0] \times I_r$ |
| | Operation time | 11 ms typ. |
| CT circuit failure detection based on remote end signals | Principle | Comparison of negative-sequence current / positive-sequence current ratio between local and remote end current signals |
| | Ratio I_2/I_1 | [0.05 .. 1.0] |
| | Minimum positive-sequence current | $[0.05 \dots 4.0] \times I_r$ |
| Alarm time | Time delay | [0 .. 60000] ms |
| Current measurement evaluation | Alarms | Polarity and sequence check |
| | Evaluation time | [1000 .. 60000] ms |
| | Minimum current | $[0.05 \dots 1.0] \times I_r$ |

| Open Pole Detection | | |
|---------------------------------|--|---|
| Number of independent functions | | 1 function |
| Operation | Principle | Current unbalance and residual current / current unbalance and voltage unbalance / current unbalance and circuit breaker position |
| | Line information (multiple breaker topologies) | At least one circuit breaker in open pole condition / both circuit breakers in open pole condition |
| | Minimum current | $[0.05 \dots 1.0] \times I_r$ |
| | Minimum voltage | $[0.05 \dots 1.0] \times U_r$ |

| Circuit Breaker Control | | |
|---------------------------------|--|--|
| Number of independent functions | | 2 functions |
| Blocking / release conditions | Block inputs (per type of command) | Independent for open and close commands |
| | Block inputs (per origin) | Independently defined for: general block, local manual command block, remote manual command block, automatic command block |
| | Interlocking | Freely programmed by user |
| | Synchronism check (for close commands) | Interaction with synchronism check function (disabled / enabled) |
| | Maximum wait time for synchronism | $[0 \dots 600000]$ ms |
| Block / interlocking bypass | Mode | Latched / timed |
| | Bypass time | $[0 \dots 3600]$ s |
| Hit & run | Open command delay | $[0 \dots 300]$ s |
| | Close command delay | $[0 \dots 300]$ s |

| Circuit Breaker Supervision | | |
|---------------------------------|-------------------------------------|--|
| Number of independent functions | | 2 functions |
| CB command | Minimum open command time | $[0 \dots 60000]$ ms |
| | Minimum close command time | $[0 \dots 60000]$ ms |
| | Adaptive pulse | Disabled / enabled |
| | Number of close (re)tries | $[1 \dots 500]$ |
| | Retry interval | $[1 \dots 60]$ s |
| CB status supervision | Intermediate state filtering | Disabled / enabled |
| | Filter time for intermediate state | $[0 \dots 60000]$ ms |
| CB operation supervision | Maximum start time | $[0 \dots 60000]$ ms |
| | Maximum operation time | $[0 \dots 60000]$ ms |
| | Maximum open pole time | $[0 \dots 60000]$ ms |
| Condition monitoring | Contact travel time monitoring | Independent for open and close operations |
| | Open operation time correction | $[0 \dots 500]$ ms |
| | Close operation time correction | $[0 \dots 500]$ ms |
| | Maximum operation counter | $[0 \dots 100000]$ |
| | Switched current exponent | $[1.0 \dots 3.0]$ |
| | Maximum switched square current sum | $[1.0 \dots 99999.0]$ kA ² |
| | Contact wear monitoring criterion | Disabled / remaining operations alarm / remaining operations warning / contact wear alarm / contact wear warning |
| | Contact wear warning level | $[10000 \dots 1]$ opening operations $[1 \dots 10000] \times 0.01 \%$ |
| | Contact wear alarm level | $[10000 \dots 1]$ opening operations $[1 \dots 10000] \times 0.01 \%$ |

| Circuit Switch Control | | |
|---------------------------------|------------------------------------|--|
| Number of independent functions | | 10 functions |
| Blocking / release conditions | Block inputs (per type of command) | Independent for open and close commands |
| | Block inputs (per origin) | Independently defined for: general block, local manual command block, remote manual command block, automatic command block |
| | Interlocking | Freely programmed by user |

| Circuit Switch Supervision | | |
|---------------------------------|------------------------------------|--------------------|
| Number of independent functions | | 10 functions |
| SW command | Minimum open command time | [0 .. 60000] ms |
| | Minimum close command time | [0 .. 60000] ms |
| | Adaptive pulse | Disabled / enabled |
| SW status supervision | Intermediate state filtering | Disabled / enabled |
| | Filter time for intermediate state | [0 .. 60000] ms |
| SW operation supervision | Maximum start time | [0 .. 60000] ms |
| | Maximum operation time | [0 .. 60000] ms |
| | Maximum operation counter | [0 .. 100000] |

| Three-Phase Measurements | | |
|---------------------------------|----------------------|---|
| Number of independent functions | | 1 function |
| Orientation | | Forward or reverse |
| Current | Measurements | Phase, residual, neutral, symmetrical components |
| | Magnitude accuracy | 0.25% I_r |
| | Phase angle accuracy | 0.2° |
| | Range | $[0.05 .. 2.0] \times I_r$ |
| Voltage | Measurements | Phase-earth, phase-phase, residual, neutral, symmetrical components |
| | Magnitude accuracy | 0.25% U_r |
| | Phase angle accuracy | 0.2° |
| | Range | $[0.05 .. 2.0] \times U_r$ |
| Power | Measurements | Active, reactive, apparent and power factor (total and per phase) |
| | Accuracy | 0.5% S_r |
| | Range | $[0.05 .. 2.0] \times S_r$ |
| Frequency | Accuracy | 10 mHz |
| | Range | $f_r \pm 3$ Hz |

| Single-Phase Measurements | | |
|---------------------------------|----------------------|---|
| Number of independent functions | | 3 functions |
| Orientation | | Forward or reverse |
| Current | Measurements | Phase, residual or neutral |
| | Magnitude accuracy | 0.25% I_r |
| | Phase angle accuracy | 0.2° |
| | Range | $[0.05 \dots 2.0] \times I_r$ |
| Voltage | Measurements | Phase-earth, phase-phase, residual or neutral |
| | Magnitude accuracy | 0.25% U_r |
| | Phase angle accuracy | 0.2° |
| | Range | $[0.05 \dots 2.0] \times U_r$ |
| Power | Measurements | Active, reactive, apparent and power factor |
| | Accuracy | 0.5% S_r |
| | Range | $[0.05 \dots 2.0] \times S_r$ |
| Frequency | Accuracy | 10 mHz |
| | Range | $f_r \pm 3 \text{ Hz}$ |

| Metering | | |
|---------------------------------|----------|----------------------------|
| Number of independent functions | | 1 function |
| Orientation | | Forward or reverse |
| Energy counters | Active | Forward, reverse and total |
| | Reactive | Forward, reverse and total |
| | Apparent | Total |
| Accuracy | | 0.5% |

| Fault Locator | | |
|---------------------------------|------------------------------|--|
| Number of independent functions | | 1 function |
| Line parameters | Number of line sections | Maximum 3 |
| | Line section length | $[0.1 \dots 1000.0]$ length units |
| | Length units | km / miles |
| | Positive sequence resistance | $[0.01 \dots 500.0] \Omega$ |
| | Positive sequence reactance | $[0.01 \dots 500.0] \Omega$ |
| | Zero sequence resistance | $[0.01 \dots 500.0] \Omega$ |
| | Zero sequence reactance | $[0.01 \dots 500.0] \Omega$ |
| | Parallel line compensation | Optional |
| | Mutual resistance | $[0.01 \dots 500.0] \Omega$ |
| | Mutual reactance | $[0.01 \dots 500.0] \Omega$ |
| Fault location | Measuring principle | Local quantities (phase currents and voltages) / local and remote end quantities (if remote end communication channel available) |
| | Outputs | Fault type, fault loop, fault impedance, fault loop resistance and reactance, fault resistance, fault distance |
| | Fault distance | In ohm, km, miles and percentage of total line length |
| | Accuracy | 2% of total line length ($30^\circ < \varphi < 90^\circ$) |

| Disturbance Recorder | | |
|----------------------|--|---|
| Recording | Number of records | Max. 250 |
| | Sampling rate | 80 samples per cycle at rated frequency (4 kHz @ $f_r = 50$ Hz; 4.8 kHz @ $f_r = 60$ Hz) |
| | Trigger options | External (user command), internal (analogue and binary channel supervision) or both |
| | Retrigger | Disabled / enabled |
| | Pre-fault time | [50 .. 500] ms |
| | Post-fault time | [50 .. 2000] ms |
| | Maximum record duration | [200 .. 10000] ms |
| | Maximum record duration (manual trigger) | [200 .. 10000] ms |
| | Action when memory is full | Overwrite older records |
| Analogue channels | Number | Up to 48 channels |
| | Trigger options | Defined by trigger levels (high / low) or none (only register) |
| | High trigger level | [0.0 .. 999999.9] (in A for currents, kV for voltages) |
| | Low trigger level | [0.0 .. 999999.9] (in A for currents, kV for voltages) |
| Binary channels | Number | Up to 96 channels |
| | Trigger options | Rising edge, falling edge, none (only register) |

| Event Log | | |
|-----------|-------------------------------|---|
| Recording | Total number of events | Max. 25000 |
| | Chronological order of events | Ascendant / descendant |
| | Time resolution | 1 ms |
| | Local HMI visualization | Last 100 events |
| | Action when memory is full | Overwrite older records |
| Entities | Number | Max. 3000 |
| | Reason for inclusion | Configurable (data-change, quality-change, data-update, range-change) |

| Fault Report | | |
|--------------|----------------------------|---|
| Recording | Total number of reports | Max. 50 |
| | Trigger | General protection pickup (trip logic) |
| | Fault type | Record a report every time a fault occurs or only in case a protection function tripped |
| | Recorded information | Fault summary, timeline, pre-fault and fault measurements, correlated disturbance records |
| | Local HMI visualization | Last report |
| | Action when memory is full | Overwrite older records |

| User Programmable Automation / Logic | |
|---|---|
| Maximum number of tasks | 8 |
| Scheduling | Preemptive multi-tasking (1 thread per task) |
| Distinct task priority levels | 5 |
| Maximum number of programs | 150 |
| Code area size | 512 KB |
| Global area size (data and stack) | 1024 KB |
| On-event program execution | Yes, multi-event |
| Execution triggering events | Multiple device data changes / updates High-performance timers Control execution Cycle |
| Basic data types | Boolean, Floating points (32, 64 bits) and Integers (8, 16, 32, 64 bits) |
| Date / time | Yes |
| Programming languages | IEC 61131-3 ST and FBD |
| Standard library | Full |
| User function block libraries | Yes |
| In-tool code simulation | Available |
| Logical device association | Free association of user functions to logical devices |
| Setting groups | Settings freely defined for user functions |

| Input / Output Processing | | |
|----------------------------------|--|---|
| AC analogue inputs | Channel inputs | Phase-earth, phase-phase or neutral inputs |
| | Optional channel arithmetic | Sum / selection / transformer compensation / magnitude and phase angle correction |
| | Orientation | Forward or reverse |
| | Primary rated value | [0.0 .. 10000.0] (in A for currents, kV for voltages) |
| | External measuring transformer ratio | [1.0 .. 20000.0] |
| DC analogue inputs | Conversion function | Polynomial / piecewise linear |
| | Number of coefficients (polynomial function) | Up to 8 |
| | Number of points (piecewise linear function) | Up to 8 |
| Binary inputs | Types of entities | Single status / double status / integer status / pulse counters |
| | Intermediate state filtering (double status) | Disabled / enabled |
| | Filter time for intermediate state (double status) | [0 .. 30000] ms |
| | Code (integer status) | Binary / Gray / BCD / 1-of-N / Signed BCD |
| | Number of inputs (integer status) | Max. 32 bits (1-of-N code) Max. 6 bits (other codes) |
| | Pulse type (pulse counters) | Rising edge, falling edge or both |
| Binary outputs | Types of entities | Single / double (status or controls) |
| | Number of entities per output | Max. 16 entities per output (logical OR) |

| Device and Function Management | | |
|---------------------------------------|----------------------------|--|
| Logical devices | Number | Max. 16 |
| | Mode | Off / On / Test |
| | Set of functions | Free association of functions (built-in or user-defined) |
| Setting groups | Number of groups | 8 (per logical device) |
| | Switchover | Via engineering tool, local HMI, remote control or logical condition (freely programmed by user) |
| Switching hierarchy | Switching authority levels | Process, bay, station and control centre |
| | Multilevel control | Disabled (only one switching authority allowed) / enabled (more than one switching authority) |

| Human-Machine Interface | | |
|-------------------------|---------------------------|--|
| IED status indications | Available indications | POWER, RUN and COMM |
| | Blinking (RUN indication) | Configurable by user |
| Alarms | Number | 16 |
| | Colour | Red or yellow (configurable by user) |
| | Entities | Max. 16 entities per alarm (logical OR) |
| | Mode of operation | Unlatched or latched (resettable by user) |
| | Blinking (latched alarms) | Configurable by user |
| Function keys | Number | 9 |
| | Mode of operation | Status and/ or control, shortcut, selection from a list of options |
| Display | Type | 640 × 480 graphic colour LCD |
| | Language | Portuguese / English / Spanish / French / Russian Others available (please contact) |
| | Information handling | Menu and mimic oriented |
| | Available information | Operation and control, management of operational settings, active setting groups and operating modes, IED status monitoring, access to measurements and records, among other actions, are available in the menu structure. The mimic structure is defined by the user. |
| Web interface | Access | Local (via service front Ethernet port) or remote (via system rear Ethernet ports) |
| | Available information | Visualization of operational settings, active setting groups and operating modes, IED status monitoring, access to measurements and records, among other actions. |

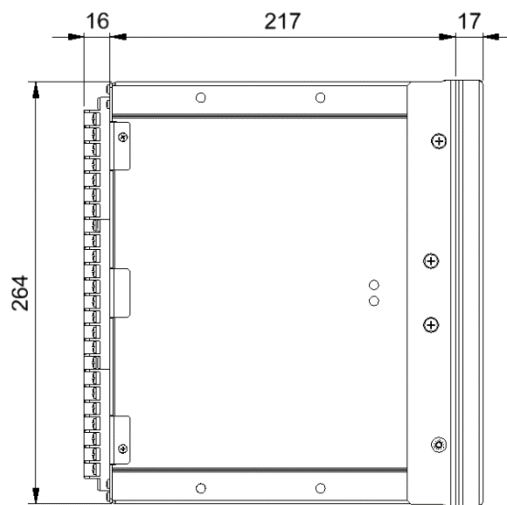
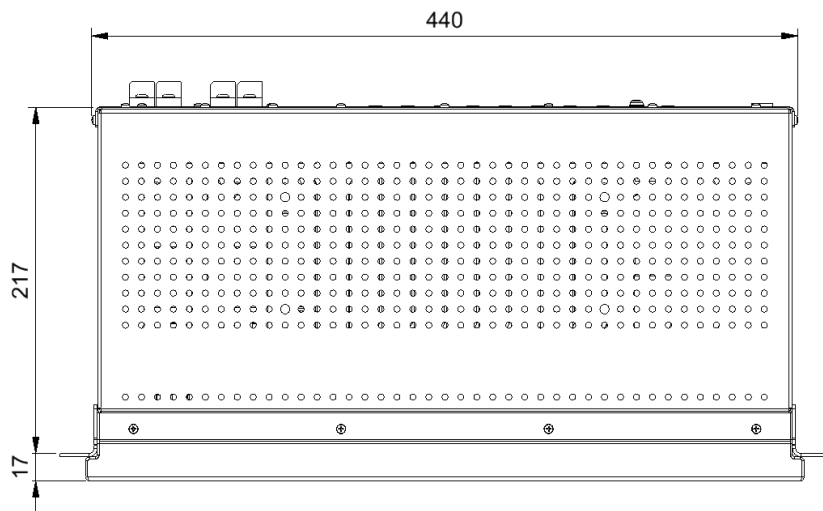
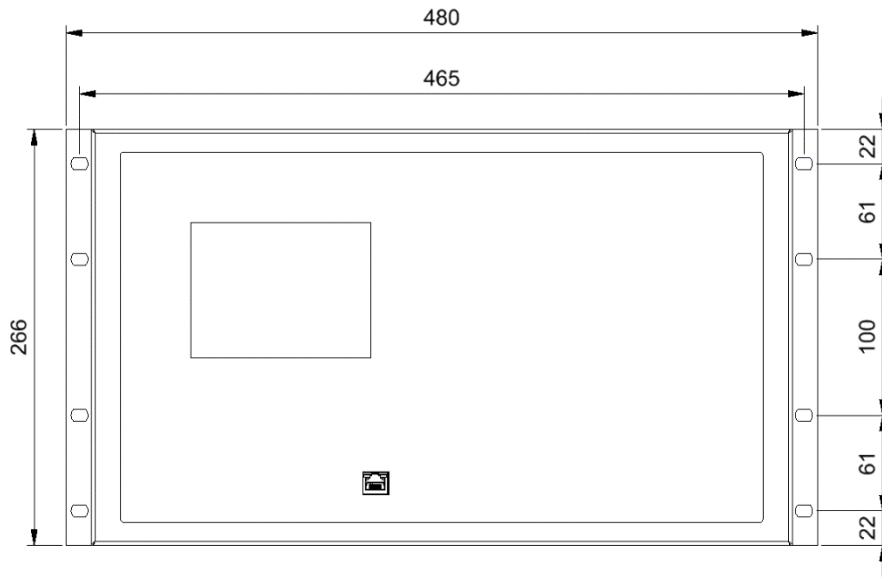
| RTC and Clock Synchronization | | |
|-------------------------------|---------------------------------|--|
| Application clock | Resolution | 1 ms |
| | Time deviation (internal clock) | Max. 0.003% |
| | Synchronization | IRIG-B, NTP/ SNTP time slave or through communication protocol |
| | Backup power | Yes, lithium battery |
| | Local time offset | Adjustable |
| | Daylight savings configuration | Adjustable |

| IEC 61850 | | |
|----------------------|---|----------|
| IEC 61850-8-1 Server | Number of simultaneous clients | Max. 6 |
| | Number of datasets | Max. 128 |
| | Number of data attributes per dataset | Max. 128 |
| | Maximum report control blocks (RCB) | Max. 128 |
| | Buffered / unbuffered reports | Yes |
| IEC 61850-8-1 GOOSE | Number of published GOOSE control blocks | 64 |
| | Number of subscribed GOOSE control blocks | 64 |

| Other Communication Protocols | |
|-------------------------------|---|
| Protocols Up/ Slave | IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial) IEC 60870-5-103 (Serial) DNP 3.0 (TCP/IP or Serial) Modbus (TCP/IP or Serial) Others available (Please Contact) |
| Protocols Down / Master | IEC 60870-5-104 (TCP/IP) / IEC 60870-5-101 (Serial) IEC 60870-5-103 (Serial) DNP 3.0 (TCP/ IP or Serial) Modbus (TCP/ IP or Serial) Courier (Serial) Others available (Please Contact) |

| Automation Studio Engineering Software Integration | |
|--|--|
| IED configuration editors | Yes |
| IEC 61131-3 programming | Yes |
| Advanced 2D mimic design tools | Yes |
| System Engineering tools | Yes |
| Compound mimic symbols | Available |
| SVG and raster import | Available |
| Library projects | Yes |
| Device templates | Available |
| Settings static validation | Yes |
| Microsoft Excel® iterative import / export | Yes |
| Settings comparison | Yes |
| In-tool simulation | Available for user defined functions, mimics and RTDB |
| IEC 61850 SCL import / export | Yes |
| IEC 61850 user logical node designer | Available |
| SCL cross-validator integration | Available |
| Online monitoring integration | Available (IEC 61850 based and proprietary protocol) |
| Logics monitoring | Available |
| Add live device to project | Yes |
| Deploy / extract configuration settings | Yes |
| Extract records | Yes |
| Integrated analysis tools | COMTRADE, Fault Reports, SOE, System Logs, Statistical Data Trends |
| Team revision control system | Yes |
| Auto data retrieval and handling | Yes |

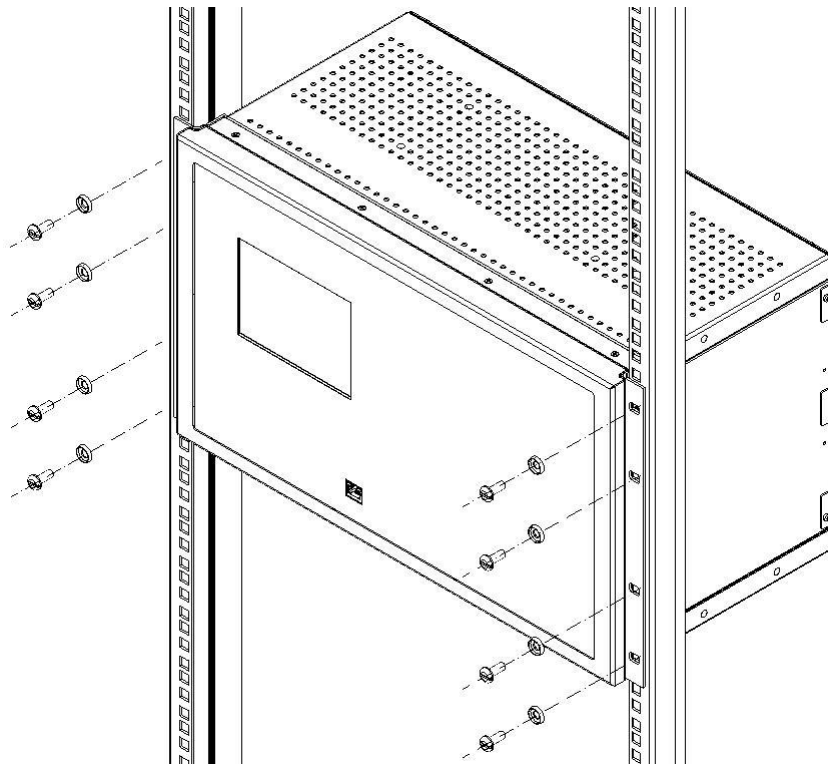
DIMENSIONS



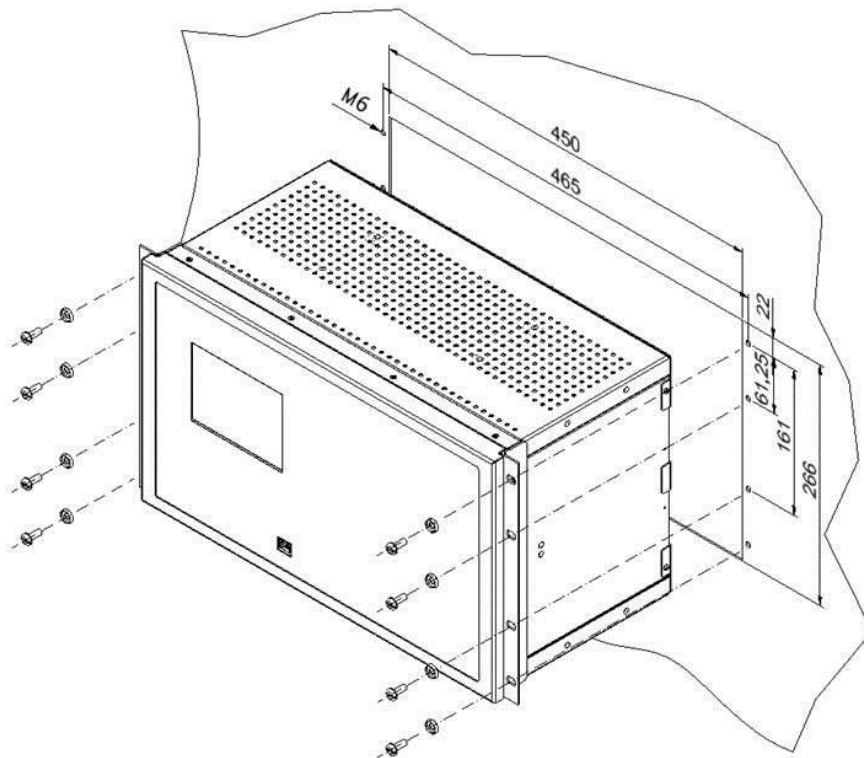
All dimensions in millimetres

MOUNTING

MOUNTING IN A 19" PANEL RACK



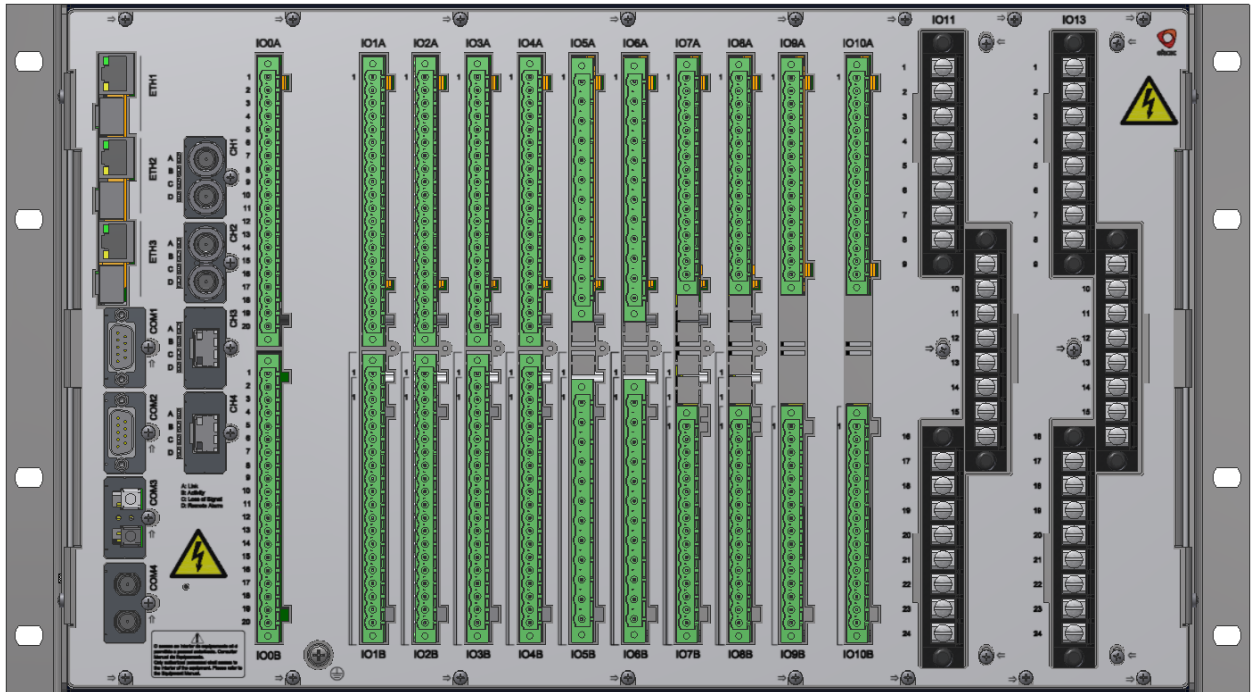
FLUSH-MOUNTING



All dimensions in millimetres

CONNECTORS IDENTIFICATION

1 x 19" CASE WITH 2 A.C. ANALOGUE INPUTS BOARDS, BACK SIDE VIEW

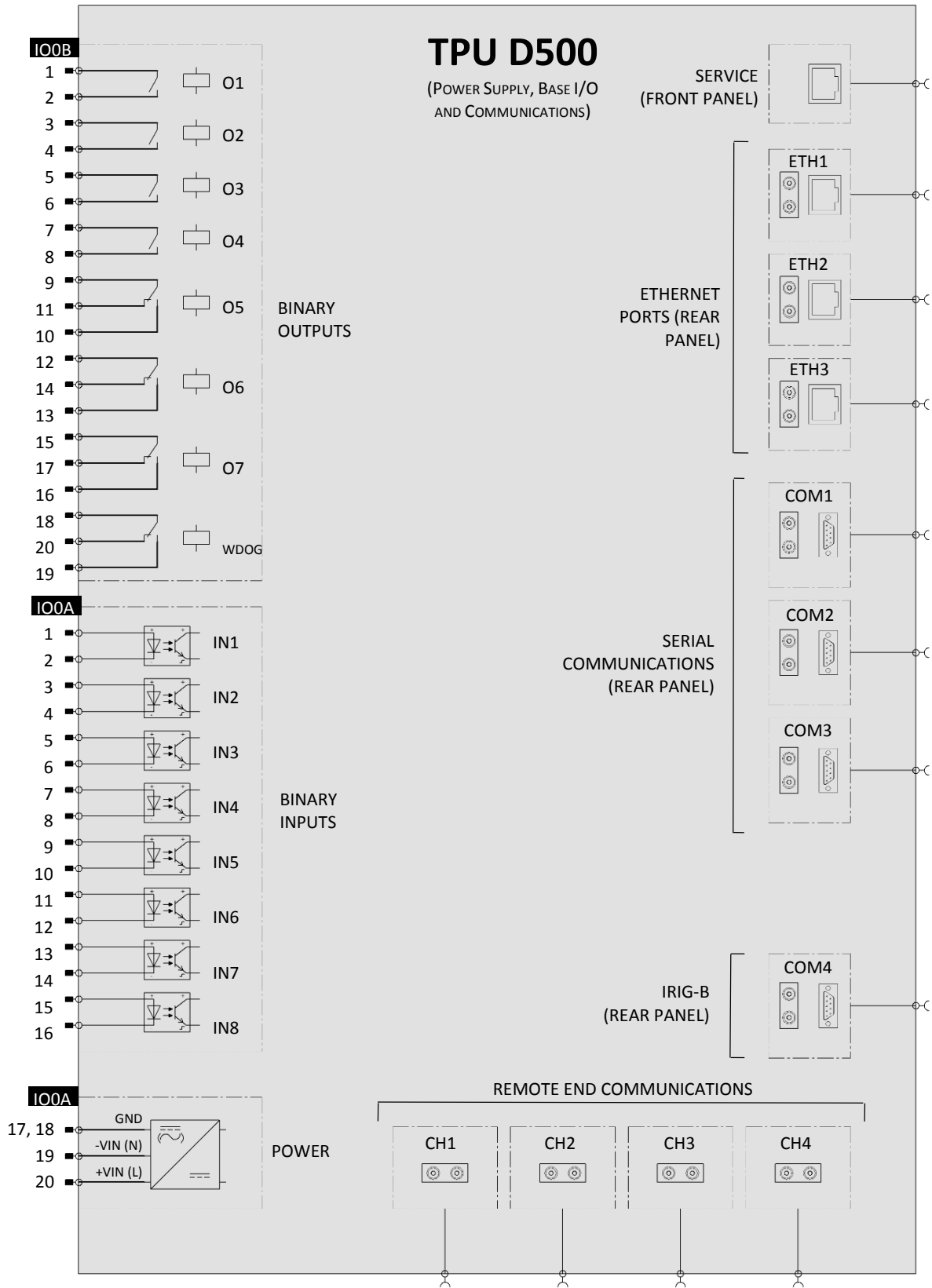


1 x 19" CASE WITH 1 A.C. ANALOGUE INPUTS BOARD, BACK SIDE VIEW



WIRING DIAGRAMS

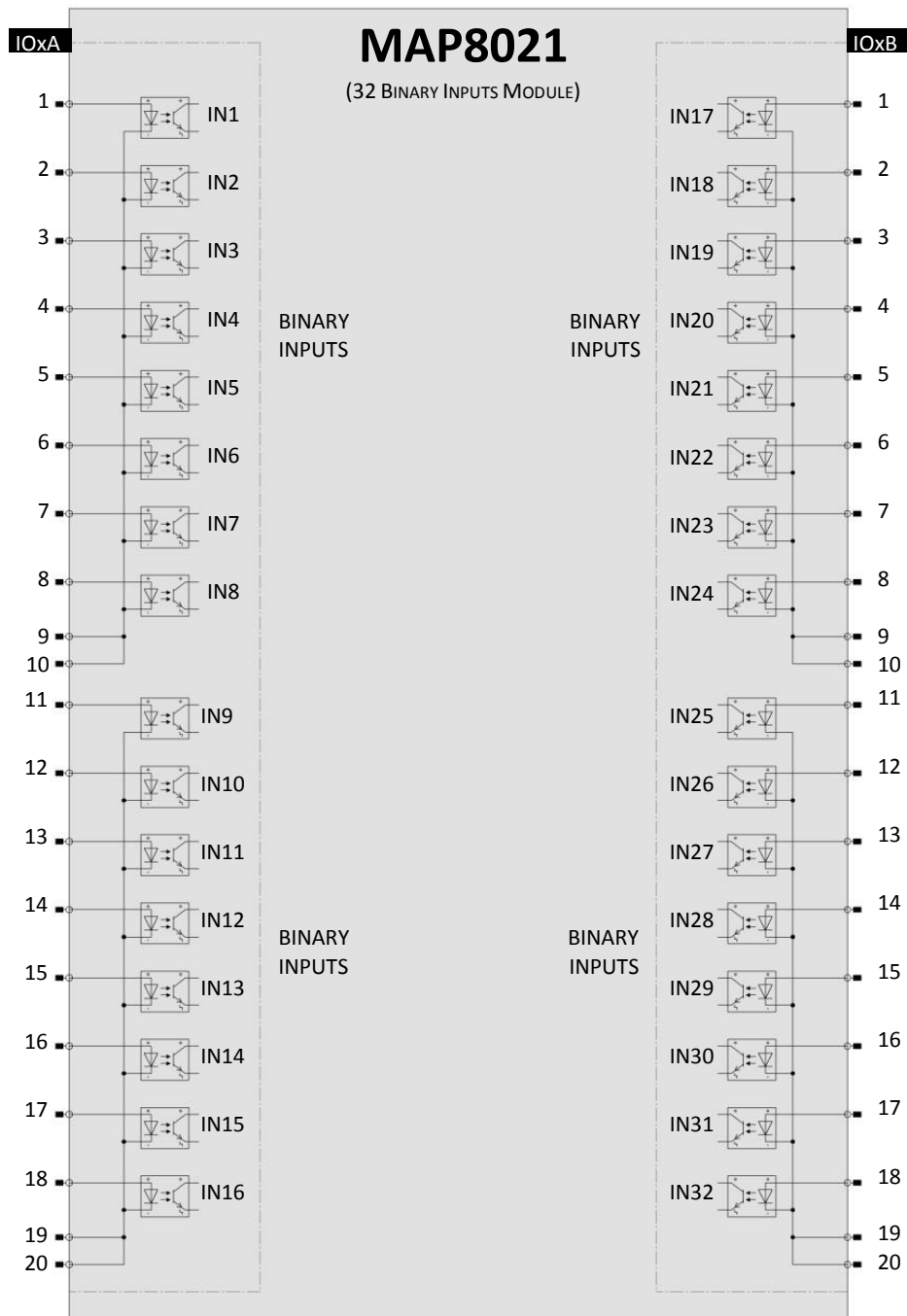
POWER SUPPLY, BASE I/O AND COMMUNICATIONS



16 BINARY INPUTS MODULE (MAP8020, ORDER CODE A)



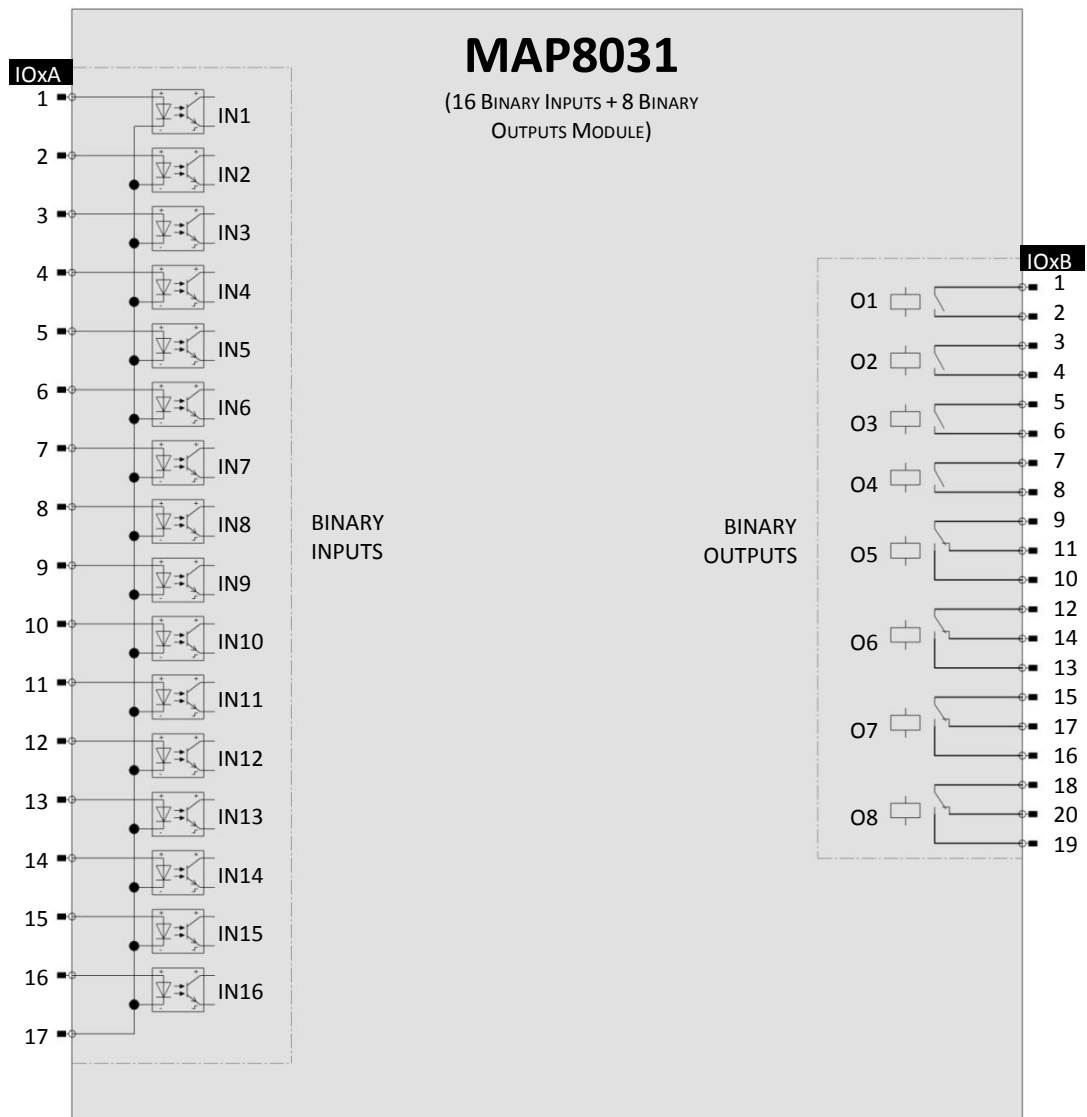
32 BINARY INPUTS MODULE (MAP8021, ORDER CODE B)



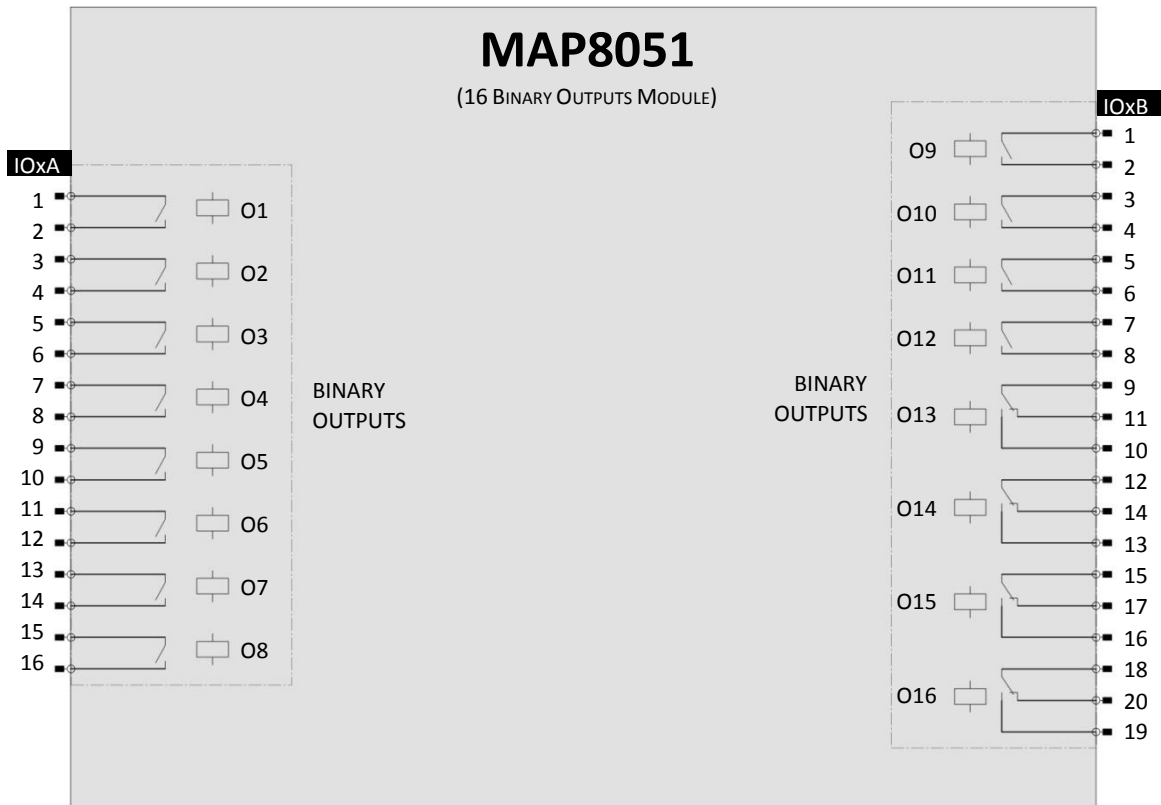
8 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8030, ORDER CODE C)



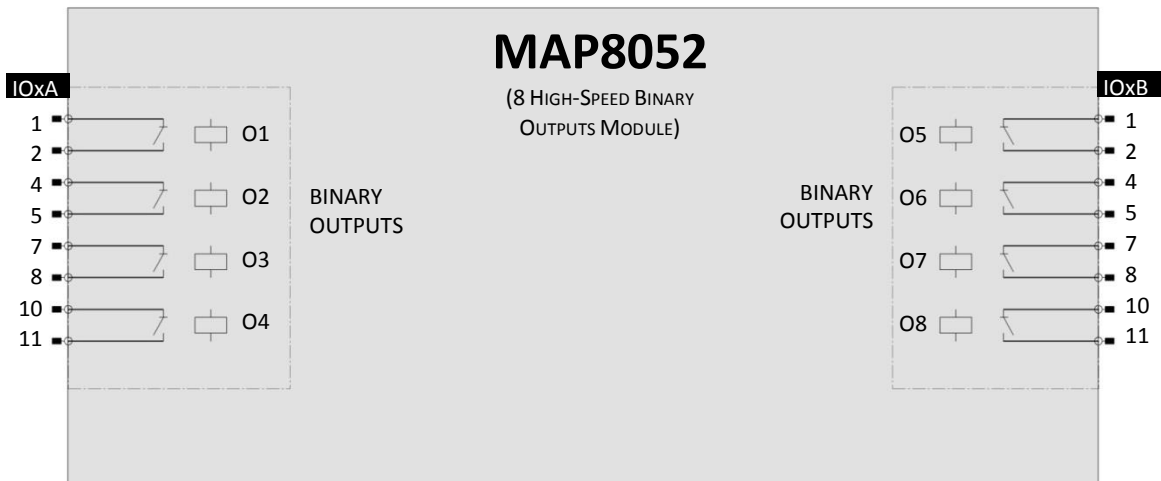
16 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8031, ORDER CODE D)



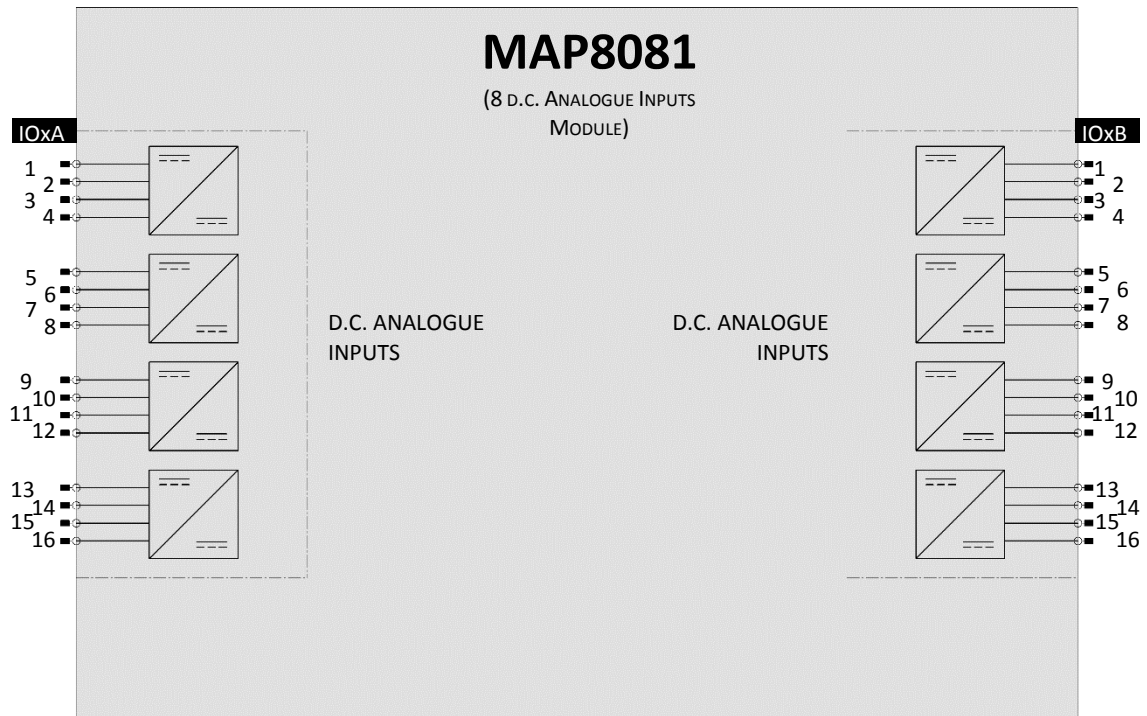
16 BINARY OUTPUTS MODULE (MAP8051, ORDER CODE E)



8 HIGH-SPEED BINARY OUTPUTS MODULE (MAP8052, ORDER CODE F)



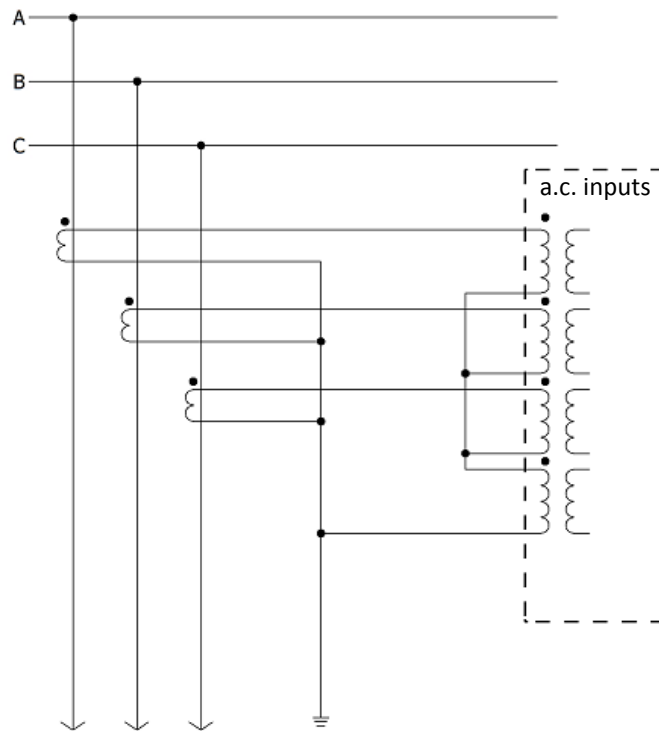
8 D.C. ANALOGUE INPUTS MODULE (MAP8081, ORDER CODE J)



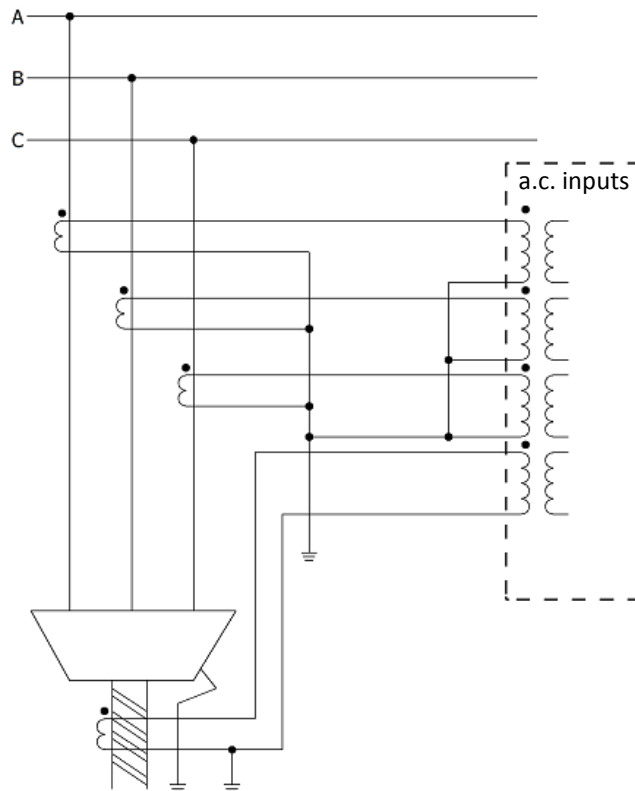
12 A.C. ANALOGUE INPUTS MODULE (MAP8082, ORDER CODES O, P, Q, R & S)



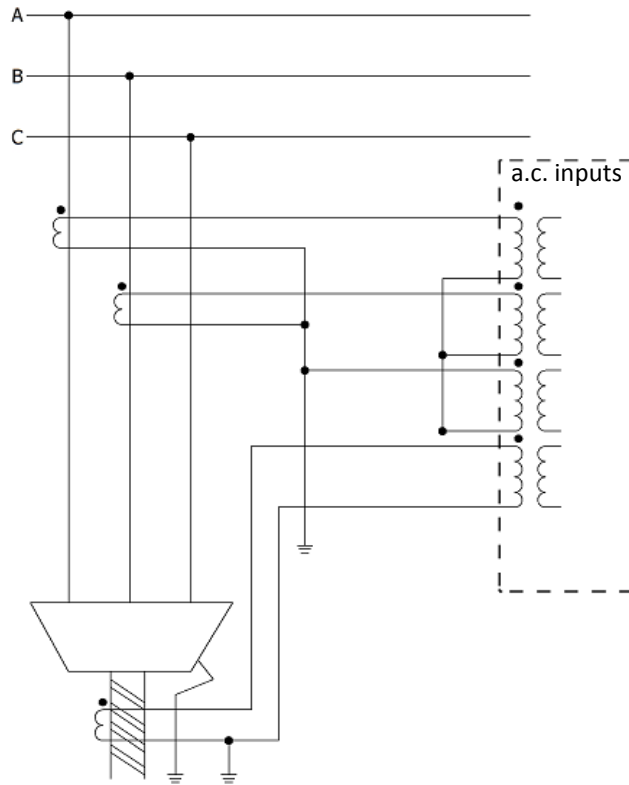
TYPICAL CONNECTIONS FOR A.C. CURRENT INPUTS



Phase and earth current inputs connection, with residual current obtained from the three phase currents by external Holmgreen circuit. Typical for low-impedance earthed systems.

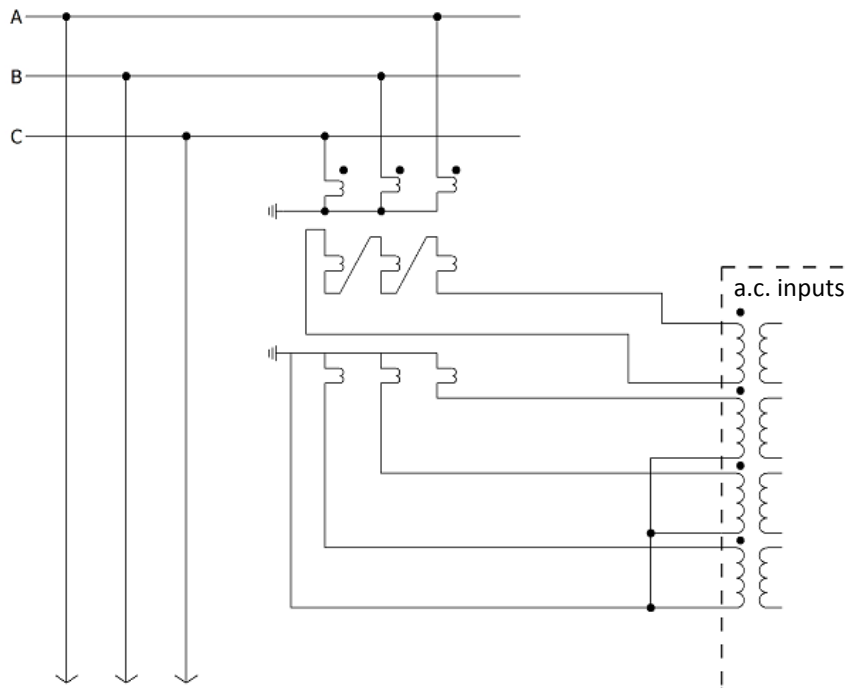


Phase and earth current inputs connection, with an independent phase-balance neutral current transformer for earth current measurement. Required in the case of isolated or compensated networks and for sensitive earth-fault detection.

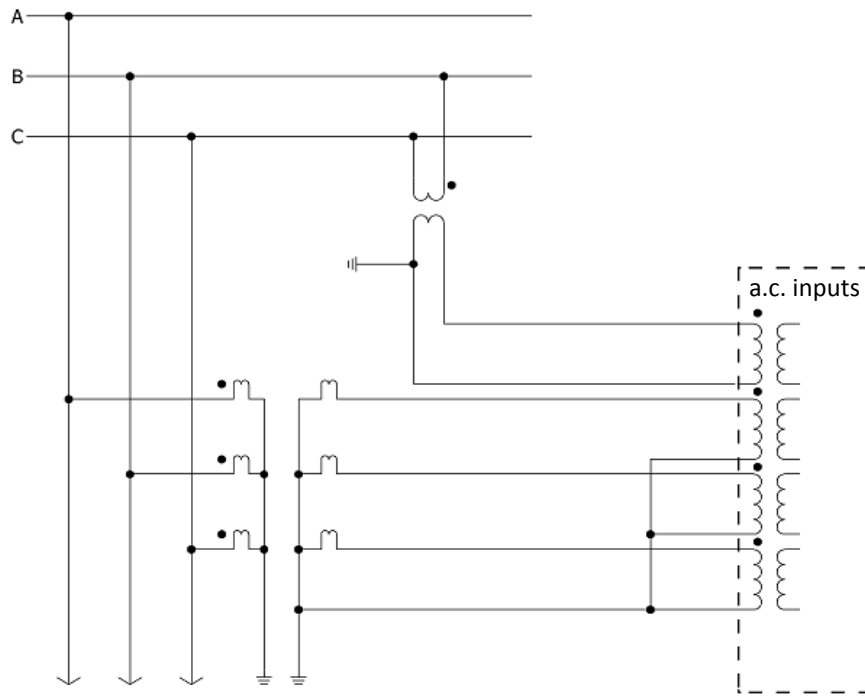


Phase and earth current inputs connection, with current transformers in only two phases. An independent neutral current transformer is required for earth current measurement. Optionally, the third phase current can be obtained from the other two by external circuitry.

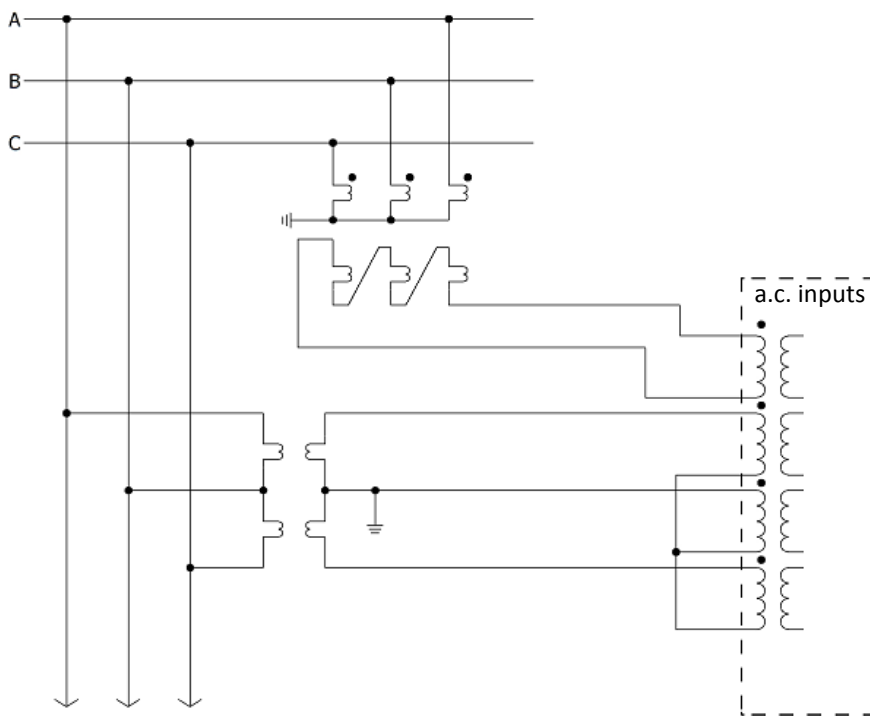
TYPICAL CONNECTIONS FOR A.C. VOLTAGE INPUTS



Three phase-to-earth voltage transformer connection, with an independent open-delta connected winding for residual voltage measurement. The fourth voltage input can provide polarization for directional earth-fault protection.



Three phase-to-earth voltage transformer connection and an additional phase-to-phase voltage input for busbar voltage measurement. Fourth voltage connection required for synchronism check applications. Polarization for directional earth-fault protection can be obtained from the internal sum of phase-to-earth voltages.



Alternative voltage transformer connection, with three phase-to-earth voltages obtained from two phase-to-phase voltage transformers (Aron circuit). Independent open-delta connected winding is required for residual voltage measurement.

PINOUT TABLES

POWER SUPPLY AND BASE I/O MODULE (MAP8011)

| Power Supply and Base I/O Module (MAP8011), see connectors description below | | | | | |
|--|--------------------|---|------|------------------------|-----------------|
| IO0A | | | IO0B | | |
| 1 | | + | 1 | Binary Output 1 | Normally Open |
| 2 | Binary Input 1 | - | 2 | | |
| 3 | | + | 3 | Binary Output 2 | Normally Open |
| 4 | Binary Input 2 | - | 4 | | |
| 5 | | + | 5 | Binary Output 3 | Normally Open |
| 6 | Binary Input 3 | - | 6 | | |
| 7 | | + | 7 | Binary Output 4 | Normally Open |
| 8 | Binary Input 4 | - | 8 | | |
| 9 | | + | 9 | | Common |
| 10 | Binary Input 5 | - | 10 | Binary Output 5 | Normally Open |
| 11 | | + | 11 | | Normally Closed |
| 12 | Binary Input 6 | - | 12 | | Common |
| 13 | | + | 13 | Binary Output 6 | Normally Open |
| 14 | Binary Input 7 | - | 14 | | Normally Closed |
| 15 | | + | 15 | | Common |
| 16 | Binary Input 8 | - | 16 | Binary Output 7 | Normally Open |
| 17 | Power Supply GND | | 17 | | Normally Closed |
| 18 | Power Supply GND | | 18 | | Common |
| 19 | Power Supply - (N) | | 19 | Watchdog Binary Output | Normally Open |
| 20 | Power Supply + (L) | | 20 | | Normally Closed |

16 BINARY INPUTS MODULE (MAP8020)

| 16 Binary Inputs Module (MAP8020), see connectors description below | | | | | |
|---|----------------|---|------|-----------------|---|
| IOxA | | | IOxB | | |
| 1 | | + | 1 | Binary Input 9 | + |
| 2 | Binary Input 1 | - | 2 | | - |
| 3 | | + | 3 | Binary Input 10 | + |
| 4 | Binary Input 2 | - | 4 | | - |
| 5 | | + | 5 | Binary Input 11 | + |
| 6 | Binary Input 3 | - | 6 | | - |
| 7 | | + | 7 | Binary Input 12 | + |
| 8 | Binary Input 4 | - | 8 | | - |
| 9 | | + | 9 | Binary Input 13 | + |
| 10 | Binary Input 5 | - | 10 | | - |
| 11 | | + | 11 | Binary Input 14 | + |
| 12 | Binary Input 6 | - | 12 | | - |
| 13 | | + | 13 | Binary Input 15 | + |
| 14 | Binary Input 7 | - | 14 | | - |
| 15 | | + | 15 | Binary Input 16 | + |
| 16 | Binary Input 8 | - | 16 | | - |
| 17 | | | 17 | | |
| 18 | Not connected | | 18 | Not connected | |
| 19 | | | 19 | | |
| 20 | | | 20 | | |

32 BINARY INPUTS MODULE (MAP8021)

| 32 Binary Inputs Module (MAP8021), see connectors description below | | | | | |
|---|---------------------------------|---|------|----------------------------------|---|
| IOxA | | | IOxB | | |
| 1 | Binary Input 1 | + | 1 | Binary Input 17 | + |
| 2 | Binary Input 2 | + | 2 | Binary Input 18 | + |
| 3 | Binary Input 3 | + | 3 | Binary Input 19 | + |
| 4 | Binary Input 4 | + | 4 | Binary Input 20 | + |
| 5 | Binary Input 5 | + | 5 | Binary Input 21 | + |
| 6 | Binary Input 6 | + | 6 | Binary Input 22 | + |
| 7 | Binary Input 7 | + | 7 | Binary Input 23 | + |
| 8 | Binary Input 8 | + | 8 | Binary Input 24 | + |
| 9 | Common to Binary Inputs 1 to 8 | - | 9 | Common to Binary Inputs 17 to 24 | - |
| 10 | | - | 10 | | - |
| 11 | Binary Input 9 | + | 11 | Binary Input 25 | + |
| 12 | Binary Input 10 | + | 12 | Binary Input 26 | + |
| 13 | Binary Input 11 | + | 13 | Binary Input 27 | + |
| 14 | Binary Input 12 | + | 14 | Binary Input 28 | + |
| 15 | Binary Input 13 | + | 15 | Binary Input 29 | + |
| 16 | Binary Input 14 | + | 16 | Binary Input 30 | + |
| 17 | Binary Input 15 | + | 17 | Binary Input 31 | + |
| 18 | Binary Input 16 | + | 18 | Binary Input 32 | + |
| 19 | Common to Binary Inputs 9 to 16 | - | 19 | Common to Binary Inputs 25 to 32 | - |
| 20 | | - | 20 | | - |

8 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8030)

| 8 Binary Inputs + 8 Binary Outputs Module (MAP8030), see connectors description below | | | | | |
|---|----------------|---|------|-----------------|-----------------|
| IOxA | | | IOxB | | |
| 1 | Binary Input 1 | + | 1 | Binary Output 1 | Normally Open |
| 2 | | - | 2 | | |
| 3 | Binary Input 2 | + | 3 | Binary Output 2 | Normally Open |
| 4 | | - | 4 | | |
| 5 | Binary Input 3 | + | 5 | Binary Output 3 | Normally Open |
| 6 | | - | 6 | | |
| 7 | Binary Input 4 | + | 7 | Binary Output 4 | Normally Open |
| 8 | | - | 8 | | |
| 9 | Binary Input 5 | + | 9 | Binary Output 5 | Common |
| 10 | | - | 10 | | Normally Open |
| 11 | Binary Input 6 | + | 11 | | Normally Closed |
| 12 | | - | 12 | Common | |
| 13 | Binary Input 7 | + | 13 | Binary Output 6 | Normally Open |
| 14 | | - | 14 | | Normally Closed |
| 15 | Binary Input 8 | + | 15 | Binary Output 7 | Common |
| 16 | | - | 16 | | Normally Open |
| 17 | Not connected | | 17 | | Normally Closed |
| 18 | | | 18 | Common | |
| 19 | | | 19 | Binary Output 8 | Normally Open |
| 20 | | | 20 | Normally Closed | |

16 BINARY INPUTS + 8 BINARY OUTPUTS MODULE (MAP8031)

| 16 Binary Inputs + 8 Binary Outputs Module (MAP8031), see connectors description below | | | | | |
|--|---------------------------------|---|------|-----------------|-----------------|
| IOxA | | | IOxB | | |
| 1 | Binary Input 1 | + | 1 | Binary Output 1 | Normally Open |
| 2 | Binary Input 2 | + | 2 | | |
| 3 | Binary Input 3 | + | 3 | Binary Output 2 | Normally Open |
| 4 | Binary Input 4 | + | 4 | | |
| 5 | Binary Input 5 | + | 5 | Binary Output 3 | Normally Open |
| 6 | Binary Input 6 | + | 6 | | |
| 7 | Binary Input 7 | + | 7 | Binary Output 4 | Normally Open |
| 8 | Binary Input 8 | + | 8 | | |
| 9 | Binary Input 9 | + | 9 | | Common |
| 10 | Binary Input 10 | + | 10 | Binary Output 5 | Normally Open |
| 11 | Binary Input 11 | + | 11 | | Normally Closed |
| 12 | Binary Input 12 | + | 12 | | Common |
| 13 | Binary Input 13 | + | 13 | Binary Output 6 | Normally Open |
| 14 | Binary Input 14 | + | 14 | | Normally Closed |
| 15 | Binary Input 15 | + | 15 | | Common |
| 16 | Binary Input 16 | + | 16 | Binary Output 7 | Normally Open |
| 17 | Common to Binary Inputs 1 to 16 | - | 17 | | Normally Closed |
| 18 | | | 18 | | Common |
| 19 | Not Connected | | 19 | Binary Output 8 | Normally Open |
| 20 | | | 20 | | Normally Closed |

16 BINARY OUTPUTS MODULE (MAP8051)

| 16 Binary Outputs Module (MAP8051), see connectors description below | | | | | |
|--|-----------------|---------------|------|------------------|-----------------|
| IOxA | | | IOxB | | |
| 1 | Binary Output 1 | Normally Open | 1 | Binary Output 9 | Normally Open |
| 2 | | | 2 | | |
| 3 | Binary Output 2 | Normally Open | 3 | | |
| 4 | | | 4 | Binary Output 10 | Normally Open |
| 5 | Binary Output 3 | Normally Open | 5 | | |
| 6 | | | 6 | Binary Output 11 | Normally Open |
| 7 | Binary Output 4 | Normally Open | 7 | | |
| 8 | | | 8 | Binary Output 12 | Normally Open |
| 9 | Binary Output 5 | Normally Open | 9 | | Common |
| 10 | | | 10 | Binary Output 13 | Normally Open |
| 11 | Binary Output 6 | Normally Open | 11 | | Normally Closed |
| 12 | | | 12 | | Common |
| 13 | Binary Output 7 | Normally Open | 13 | Binary Output 14 | Normally Open |
| 14 | | | 14 | | Normally Closed |
| 15 | Binary Output 8 | Normally Open | 15 | | Common |
| 16 | | | 16 | Binary Output 15 | Normally Open |
| 17 | | | 17 | | Normally Closed |
| 18 | Not Connected | | 18 | | Common |
| 19 | | | 19 | Binary Output 16 | Normally Open |
| 20 | | | 20 | | Normally Closed |

8 HIGH-SPEED BINARY OUTPUTS MODULE (MAP8052)

| 8 High-Speed Binary Outputs Module (MAP8052), see connectors description below | | | | | |
|--|-----------------|-------------------|------|-----------------|-------------------|
| IOxA | | | IOxB | | |
| 1 | Binary Output 1 | Normally Open (+) | 1 | Binary Output 5 | Normally Open (+) |
| 2 | | Normally Open (-) | 2 | | Normally Open (-) |
| 3 | Not Connected | | 3 | Not Connected | |
| 4 | Binary Output 2 | Normally Open (+) | 4 | Binary Output 6 | Normally Open (+) |
| 5 | | Normally Open (-) | 5 | | Normally Open (-) |
| 6 | Not Connected | | 6 | Not Connected | |
| 7 | Binary Output 3 | Normally Open (+) | 7 | Binary Output 7 | Normally Open (+) |
| 8 | | Normally Open (-) | 8 | | Normally Open (-) |
| 9 | Not Connected | | 9 | Not Connected | |
| 10 | Binary Output 4 | Normally Open (+) | 10 | Binary Output 8 | Normally Open (+) |
| 11 | | Normally Open (-) | 11 | | Normally Open (-) |
| 12 | Not Connected | | 12 | Not Connected | |

8 D.C. ANALOGUE INPUTS MODULE (MAP8081)

| 8 d.c. Analogue Inputs Module (MAP8081), see connectors description below | | | | | | |
|---|-----------------------|------------------|------|-----------------------|------------------|--|
| IOxA | | | IOxB | | | |
| 1 | d.c. Analogue Input 1 | High Voltage (+) | 1 | d.c. Analogue Input 5 | High Voltage (+) | |
| 2 | | Low Voltage (+) | 2 | | Low Voltage (+) | |
| 3 | | Current (+) | 3 | | Current (+) | |
| 4 | | Common (-) | 4 | | Common (-) | |
| 5 | d.c. Analogue Input 2 | High Voltage (+) | 5 | d.c. Analogue Input 6 | High Voltage (+) | |
| 6 | | Low Voltage (+) | 6 | | Low Voltage (+) | |
| 7 | | Current (+) | 7 | | Current (+) | |
| 8 | | Common (-) | 8 | | Common (-) | |
| 9 | d.c. Analogue Input 3 | High Voltage (+) | 9 | d.c. Analogue Input 7 | High Voltage (+) | |
| 10 | | Low Voltage (+) | 10 | | Low Voltage (+) | |
| 11 | | Current (+) | 11 | | Current (+) | |
| 12 | | Common (-) | 12 | | Common (-) | |
| 13 | d.c. Analogue Input 4 | High Voltage (+) | 13 | d.c. Analogue Input 8 | High Voltage (+) | |
| 14 | | Low Voltage (+) | 14 | | Low Voltage (+) | |
| 15 | | Current (+) | 15 | | Current (+) | |
| 16 | | Common (-) | 16 | | Common (-) | |

12 A.C. ANALOGUE INPUTS MODULE (MAP8082)

| 12 a.c. Analogue Inputs Module (MAP8082), see connectors description below | | | | | | |
|--|------------------------|----|----|----|--------------|--------------|
| IO11 and IO13 | | O | P | Q | R | S |
| 1 | a.c. Analogue Input 1 | CT | CT | CT | CT | CT |
| 2 | | | | | | |
| 3 | a.c. Analogue Input 2 | CT | CT | CT | CT | CT |
| 4 | | | | | | |
| 5 | a.c. Analogue Input 3 | CT | CT | CT | CT | CT |
| 6 | | | | | | |
| 7 | a.c. Analogue Input 4 | CT | CT | CT | CT | Sensitive CT |
| 8 | | | | | | |
| 9 | a.c. Analogue Input 5 | CT | CT | CT | CT | CT |
| 10 | | | | | | |
| 11 | a.c. Analogue Input 6 | CT | CT | CT | Sensitive CT | CT |
| 12 | | | | | | |
| 13 | a.c. Analogue Input 7 | VT | CT | CT | VT | CT |
| 14 | | | | | | |
| 15 | a.c. Analogue Input 8 | VT | CT | CT | VT | Sensitive CT |
| 16 | | | | | | |
| 17 | a.c. Analogue Input 9 | VT | CT | VT | VT | VT |
| 18 | | | | | | |
| 19 | a.c. Analogue Input 10 | VT | CT | VT | VT | VT |
| 20 | | | | | | |
| 21 | a.c. Analogue Input 11 | VT | CT | VT | VT | VT |
| 22 | | | | | | |
| 23 | a.c. Analogue Input 12 | VT | CT | VT | VT | VT |
| 24 | | | | | | |

SERIAL PORTS

| COM1 to COM3 | RS232 | RS485 |
|--------------|--|---------------|
| 1 | Not Connected | Not Connected |
| 2 | RxD <i>(Input Receive Data)</i> | DATA- |
| 3 | TxD <i>(Output Transmit Data)</i> | Not Connected |
| 4 | Not Connected | Not Connected |
| 5 | GND <i>(Ground)</i> | GND |
| 6 | Not Connected | Not Connected |
| 7 | RTS <i>(Output Request To Send)</i> | DATA+ |
| 8 | CTS <i>(Input Clear To Send)</i> | Not Connected |
| 9 | Not Connected | Not Connected |

IRIG-B

| COM4 | IRIG-B, Galvanic Option |
|------|-------------------------|
| 1 | Not Connected |
| 2 | Not Connected |
| 3 | 5 V Level Input |
| 4 | 12 V Level Input |
| 5 | GND <i>(Ground)</i> |
| 6 | Not Connected |
| 7 | 24 V Level Input |
| 8 | Not Connected |
| 9 | Not Connected |

CONNECTORS DESCRIPTION

The next table lists all the external connectors included and supplied with the equipment:

CONNECTOR FOR POWER SUPPLY, BINARY INPUTS AND STANDARD BINARY OUTPUTS



Phoenix Front-MSTB 2.5/20-STF-5.08 (1777976) type connector, 20 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR HIGH-SPEED BINARY OUTPUTS



Phoenix Front-GMSTB 2.5/12-STF-7.62 (1806106) type connector, 12 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

CONNECTOR FOR D.C. ANALOGUE INPUTS



Phoenix Front-MSTB 2.5/16-STF-5.08 (1777934) type connector, 16 contacts. Accepts conductors with section from 0.2 mm² to 2.5 mm². The connection is made by screw with the help of a screw driver size 0.6 x 3.5 mm. Tightening torque: 0.5 – 0.6 Nm.

TERMINAL FOR CONNECTION OF A.C. ANALOGUE INPUTS



Terminal Barrier type connector, 8 contacts. Accepts M3.5 or M4 ring-type lug terminals (max. 8 mm external diameter) for conductors with cross-sections from 1.5 to 4.0 mm². The connection is made by DIN 5.5 x 1.0 screwdriver or a PZ2 screwdriver. Tightening torque: 0.8 – 1.0 Nm.

TERMINAL FOR CONNECTION TO EARTH PROTECTION



Terminal to be fitted by M4 screw, for connection to Earth Protection. This connection is essential for the correct operation of the TPU D500. It should be solid for security reasons.

ORDER FORM

| TPU D500 - 1 - | | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | <i>to next table...</i> | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|-------------------------|--|
| Region | | | | | | | | | | | | | | | | | | | | |
| Standard ☺ | 1 | | | | | | | | | | | | | | | | | | | |
| Eastern Europe and Central Asia | 2 | | | | | | | | | | | | | | | | | | | |
| HMI | | | | | | | | | | | | | | | | | | | | |
| Alphanumeric Display ** | A | | | | | | | | | | | | | | | | | | | |
| Graphic Display | B | | | | | | | | | | | | | | | | | | | |
| Power Supply | | | | | | | | | | | | | | | | | | | | |
| 24 / 48 / 60 V d.c. | 1 | | | | | | | | | | | | | | | | | | | |
| 110 / 125 / 220 / 250 V d.c.; 115 / 230 V a.c. | 2 | | | | | | | | | | | | | | | | | | | |
| 48 / 60 / 110 / 125 V d.c. ☺ | 3 | | | | | | | | | | | | | | | | | | | |
| Binary Input Rated Voltage | | | | | | | | | | | | | | | | | | | | |
| 24 V d.c. | A | | | | | | | | | | | | | | | | | | | |
| 48 / 60 V d.c. | B | | | | | | | | | | | | | | | | | | | |
| 110 / 125 V d.c. | C | | | | | | | | | | | | | | | | | | | |
| 220 / 250 V d.c. | D | | | | | | | | | | | | | | | | | | | |
| Expansion I/O | | | | | | | | | | | | | | | | | | | | |
| Slot 1 | | | | | * | | | | | | | | | | | | | | | |
| Slot 2 | | | | | | * | | | | | | | | | | | | | | |
| Slot 3 | | | | | | | * | | | | | | | | | | | | | |
| Slot 4 | | | | | | | | * | | | | | | | | | | | | |
| Slot 5 | | | | | | | | | * | | | | | | | | | | | |
| Slot 6 | | | | | | | | | | * | | | | | | | | | | |
| Slot 7 | | | | | | | | | | | * | | | | | | | | | |
| Slot 8 | | | | | | | | | | | | * | | | | | | | | |
| Slot 9 | | | | | | | | | | | | | * | | | | | | | |
| Slot 10 | | | | | | | | | | | | | | * | | | | | | |
| Slot 11 | | | | | | | | | | | | | | | * | | | | | |
| Slot 12 | | | | | | | | | | | | | | | | * | | | | |
| Slot 13 | | | | | | | | | | | | | | | | | * | | | |

| ...from previous table | R | S | T | U | V | W | X | Y | Z |
|--|---|---|---|---|------|---|---|------|----|
| COM1 Interface | | | | | | | | | |
| Not used ◊ | X | | | | | | | | |
| RS-232 | 1 | | | | | | | | |
| RS-485 | 2 | | | | | | | | |
| Plastic Optical Fibre | 3 | | | | | | | | |
| Glass Optical Fibre | 4 | | | | | | | | |
| COM2 Interface | | | | | | | | | |
| Not used ◊ | X | | | | | | | | |
| RS-232 | 1 | | | | | | | | |
| RS-485 | 2 | | | | | | | | |
| Plastic Optical Fibre | 3 | | | | | | | | |
| Glass Optical Fibre | 4 | | | | | | | | |
| COM3 Interface | | | | | | | | | |
| Not used ◊ | | | X | | | | | | |
| RS-232 | | | 1 | | | | | | |
| RS-485 | | | 2 | | | | | | |
| Plastic Optical Fibre | | | 3 | | | | | | |
| Glass Optical Fibre | | | 4 | | | | | | |
| COM4 Interface | | | | | | | | | |
| Not used | | | | X | | | | | |
| IRIG-B Optical Fibre | | | | 5 | | | | | |
| IRIG-B Galvanic | | | | 6 | | | | | |
| Remote End Communication | | | | | | | | | |
| According to remote interface list | | | | | XXXX | | | | |
| ETH1 / ETH2 Interface | | | | | | | | | |
| Dual RSTP-enabled 10/100BASE-TX ** | | | | | | 3 | | | |
| Dual RSTP-enabled 10/100BASE-TX or 100BASE-FX ** | | | | | | 4 | | | |
| Dual PRP-enabled 10/100BASE-TX | | | | | | 5 | | | |
| Dual PRP-enabled 10/100BASE-TX or 100BASE-FX | | | | | | 6 | | | |
| ETH3 Interface | | | | | | | | | |
| 10/100BASE-TX | | | | | | | 1 | | |
| 10/100BASE-TX or 100BASE-FX | | | | | | | 2 | | |
| Communication Protocols | | | | | | | | | |
| According to protocol list | | | | | | | | XXXX | |
| Application / Function Packages | | | | | | | | | |
| Three-Phase Tripping | | | | | | | | A1 | |
| Three-Phase / Single-Phase Tripping | | | | | | | | A2 | |
| Single Breaker Arrangements | | | | | | | | B1 | |
| Multiple Breaker Arrangements | | | | | | | | B2 | |
| Only Protection | | | | | | | | C1 | |
| Protection and Control | | | | | | | | C2 | |
| Line Differential | | | | | | | | D1 | |
| Line Differential with In-Zone Transformer | | | | | | | | D2 | |
| Without Distance | | | | | | | | E1 | |
| With Distance | | | | | | | | E2 | |
| With Distance and PSB/OOS | | | | | | | | E3 | |
| Without Synchronism Check | | | | | | | | | F1 |
| With Synchronism Check | | | | | | | | | F2 |

* See Expansion boards option codes

** Currently under development

◊ Preferred Options

EXPANSION BOARD CODES (FIELDS E TO Q)

| Expansion boards option codes table | | |
|--|--------------|------|
| Board type | Board name | Code |
| 16 Binary Inputs | MAP8020 | A |
| 32 Binary Inputs ◊ | MAP8021 | B |
| 8 Binary Inputs + 8 Binary Outputs | MAP8030 | C |
| 16 Binary Inputs + 8 Binary Outputs ◊ | MAP8031 | D |
| 16 Binary Outputs ◊ | MAP8051 | E |
| 8 High-Speed Binary Outputs ◊ | MAP8052 | F |
| 8 d.c. Analogue Inputs | MAP8081 | J |
| 12 a.c. Analogue Inputs (6 CT + 6 VT) | MAP8082 OP5 | O |
| 12 a.c. Analogue Inputs (12 CT) | MAP8082 OP6 | P |
| 12 a.c. Analogue Inputs (8 CT + 4 VT) | MAP8082 OP8 | Q |
| 12 a.c. Analogue Inputs (5 CT + 1 sensitive CT + 6 VT) | MAP8082 OP9 | R |
| 12 a.c. Analogue Inputs (6 CT + 2 sensitive CT + 4 VT) | MAP8082 OP12 | S |
| Inexistent or unavailable slot | - | X |

◊ - preferred option

Notes:

- ◆ If there is an a.c. analogue board in slot 11 (field O filled with codes 'O', 'P', 'Q', 'R' or 'S'), slot 12 must be empty (field P must be filled with 'X' code);
- ◆ Slot 13 (field Q) can only have one of five codes: 'O', 'P', 'Q', 'R' or 'S'.

MAXIMUM NUMBER OF ACCEPTABLE EXPANSION BOARDS

| Maximum number of a.c. analogue input boards; Available slots | Maximum number of binary I/O expansion boards; Available slots | Maximum number of d.c. analogue input boards; Available slots |
|---|--|---|
| 1 x MAP8082, slot 13 | Max. 8, slots 1 to 8 | Max. 4, slots 9 to 12 |
| 2 x MAP8082, slots 11 and 13 | Max. 8, slots 1 to 8 | Max. 2, slots 9 to 10 |
| | Max. 7, slots 1 to 7 | Max. 3, slots 8 to 10 |
| | Max. 6, slots 1 to 6 | Max. 4, slots 7 to 10 |

REMOTE INTERFACE CODES (FIELD V)

| Remote interface option codes table | Code |
|--|------|
| Not used | X |
| IEEE C37.94 Multi-mode Channel (maximum distance 2 km) | A |
| Single-mode Channel (maximum distance 40 km) | B |
| Single-mode Channel (maximum distance 60 km) | C |
| Single-mode Channel (maximum distance 100 km) | D |

Notes:

- ◆ A maximum of 4 channels is allowed;
- ◆ Any combination of single or multi-mode channels is allowed;
- ◆ Used channels must be filled from left to right (i.e. unused channels, with code 'X', must be in the end).

COMMUNICATION PROTOCOL CODES (FIELD Y)

| Slave / Server protocols | Code |
|---|------|
| None | X |
| IEC 60870-5-101/104 | A |
| IEC 60870-5-103 | B |
| IEC 61850-8-1 MMS Server and GOOSE publisher / subscriber | C |
| DNP 3.0 (Serial and/or TCP/IP) | D |
| Modbus (Serial and/or TCP/IP) | E |
| Others, please contact | |

| Master / Client protocols | Code |
|-----------------------------------|------|
| None | X |
| IEC 60870-5-101/104 ** | a |
| IEC 60870-5-103 | b |
| DNP 3.0 (Serial and/or TCP/IP) ** | d |
| Modbus (Serial and/or TCP/IP) | e |
| Courier | o |
| Others, please contact | |

Notes:

- ◆ A maximum of 4 simultaneous protocols is allowed;
- ◆ Master protocols are only available if Protection and Control option is selected (option 'C2' in field Z).

** - Currently under development



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